Reciprocal transformations and deformations of integrable hierarchies

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R-matrix formalism

A systematic way to construct the operators A_k for a given L so that we obtain self-consistent compatibility conditions $L_{t_k} = [A_k, L]$ is provided by the *R*-matrix formalism.

Given a Lie algebra \mathfrak{G} with the commutator [,], a linear map $R : \mathfrak{G} \to \mathfrak{G}$ such that the bracket

$$[a,b]_R := [Ra,b] + [a,Rb]$$
 (1)

is another Lie bracket on \mathfrak{G} is called the classical R-matrix.

R-matrix formalism II

A sufficient condition for R to be a classical Rmatrix is to satisfy the following so-called Yang-Baxter equation, YB(α),

$$[Ra, Rb] - R[a, b]_R + \alpha [a, b] = 0, \qquad (2)$$

where α is a number from the ground field \mathbb{K} (\mathbb{R} or \mathbb{C}). There are only two substantially different cases, namely $\alpha \neq 0$ and $\alpha = 0$.

Algebra of pseudo-differential operators

$$\mathfrak{A} = \left\{ L = \sum_{i=-\infty}^{N} h_i D^i \right\}, \qquad (3)$$

where D is (informally) the total x-derivative, where x is the independent variable.

The noncommutative multiplication in \mathfrak{A} is defined using the (generalized) Leibniz rule

$$D^{k} \circ f = \sum_{i=0}^{\infty} \frac{k(k-1)\cdots(k-i+1)}{i!} D^{i}(f) D^{k-i} \quad (4)$$
$$[A, B] := A \circ B - B \circ A \qquad A, B \in \mathfrak{A}.$$

Algebra of pseudo-differential operators II

Consider the following decomposition of \mathfrak{A} :

$$\mathfrak{A} = \mathfrak{A}_{\geqslant k} \oplus \mathfrak{A}_{< k} := \left\{ \sum_{i \geqslant k} u_i D^i \right\} \oplus \left\{ \sum_{i < k} a_i D^i \right\}.$$
(5)

Then, $\mathfrak{A}_{\geqslant k}$ and $\mathfrak{A}_{< k}$ are Lie subalgebras of \mathfrak{A} only for k = 0, 1, 2, and we have the classical R-matrices

$$R_k = \frac{1}{2}(P_{\geqslant k} - P_{< k}) = P_{\geqslant k} - \frac{1}{2} = \frac{1}{2} - P_{< k}, \quad (6)$$

where $P_{\geqslant k}$ and $P_{< k}$ are projections onto $\mathfrak{A}_{\geqslant k}$ and $\mathfrak{A}_{< k}$, respectively.

Fractional powers

Consider an element L from \mathfrak{A} of the form

$$L = u_N D^N + u_{N-1} D^{N-1} + u_{N-2} D^{N-2} + \dots,$$
 (7)

where N > 0. Then its N-th root

$$L^{\frac{1}{N}} = a_1 D + a_0 + a_{-1} D^{-1} + a_{-2} D^{-2} + \dots,$$

where the coefficients a_i are **local** (depend on u_i and a finite number of their *x*-derivatives) and can be constructed recursively from the equality

$$\left(L^{\frac{1}{N}}\right)^N = \overbrace{L^{\frac{1}{N}} \circ \ldots \circ L^{\frac{1}{N}}}^{N \text{ times}} = L.$$

Fractional powers and Lax hierarchies on \mathfrak{A} The fractional powers $L^{\frac{n}{N}} = L^{\frac{1}{N}} \circ \ldots \circ L^{\frac{1}{N}}$ generate the following Lax hierarchies related to classical *R*-matrices (6):

$$L_{t_n} = \begin{bmatrix} R_k(L^{\frac{n}{N}}), L \end{bmatrix} = \begin{bmatrix} \left(L^{\frac{n}{N}}\right)_{\geqslant k}, L \end{bmatrix} = -\begin{bmatrix} \left(L^{\frac{n}{N}}\right)_{< k}, L \end{bmatrix},$$

$$k = 0, 1, 2, \quad n = 1, 2, \dots, \quad n \not\equiv 0 \mod N$$
(8)

Key result: commutativity of the flows:

$$(L_{t_n})_{t_m} = (L_{t_m})_{t_n}$$

follows from the YBE for R_k .

More on Lax hierarchies on ${\mathfrak A}$

The Lax hierarchies involving *finitely many* dynamical variables u_i are obtained within this approach by choosing a special form of L.

$$k = 0, 1, 2: L = \sum_{j=0}^{N} u_j D^j,$$
(9)

$$k = 1, 2: L = \sum_{j=0}^{N} u_j D^j + D^{-1} \circ u_{-1}, \qquad (10)$$

$$k = 2: L = \sum_{j=0}^{N} u_j D^j + D^{-1} \circ u_{-1} + D^{-2} \circ u_{-2}, (11)$$

It can be shown that without loss of generality we can set $u_N = 1$ in (9) and (10).

Is there more than that?

Błaszak and Szablikowski (*J. Math. Phys.* 2006) found the following deformations of the above R-matrices R_k :

$$R'_{k} = P_{\geq k} - \frac{1}{2} + \epsilon P_{k-1}(\cdot) D^{k} = \frac{1}{2} - P_{< k} + \epsilon P_{k-1}(\cdot) D^{k}, \ i.e.,$$

 $\begin{aligned} R'_k(L) &= P_{\geqslant k}(L) - \frac{1}{2}L + \epsilon P_{k-1}(L)D^k \\ &= \frac{1}{2}L - P_{<k}(L) + \epsilon P_{k-1}(L)D^k, \quad L \in \mathfrak{A}. \end{aligned}$ Here $P_k = P_{\geqslant k} - P_{\geqslant k-1}$ and ϵ is an arbitrary constant.

Deformed Lax hierarchies

$$L_{t_n} = \left[R'_k(L^{\frac{n}{N}}), L \right] = \left[\left(L^{\frac{n}{N}} \right)_{\geqslant k} + \epsilon P_{k-1}(L^{\frac{n}{N}}) D^k, L \right]$$
$$= -\left[\left(L^{\frac{n}{N}} \right)_{< k} - \epsilon P_{k-1}(L^{\frac{n}{N}}) D^k, L \right],$$
$$k = 0, 1, 2, \quad n \equiv 1, 2, \dots, \quad n \not\equiv 0 \mod N$$
$$(12)$$

However, for k = 0 and k = 2 Błaszak & Szablikowski have shown that these hierarchies can be reduced to known ones, i.e., the deformations in question are trivial.

Problem: is this true also for k = 1?

Trivializing transformation for k = 1

Consider the reciprocal transformation from x and t_i , $i = 1, 2, ..., i \not\equiv 0 \mod N$ to new independent variables z and τ_i , $i = 1, 2, ..., where <math>\tau_i = t_i$, $i = 1, 2, ..., i \not\equiv 0 \mod N$ and z is defined by the formula

$$dz = (u_N)^{-1/N} dx + \epsilon \sum_{\substack{q=1, q \neq 0 \ modN}}^{\infty} (u_N)^{-1/N} P_0(L^{q/N}) dt_q.$$
(13)

Trivializing transformation for k = 1: continued Introduce new dependent variables v_i related to u_i by means of the formulas

$$\tilde{L} = L|_{D=(u_N)^{-1/N}\tilde{D}} = \sum_{i=-\infty}^{N} u_i((u_N)^{-1/N}\tilde{D})^i$$
$$\equiv \tilde{D}^N + \sum_{i=-\infty}^{N-1} v_i\tilde{D}^i$$
(14)

(informally, \tilde{D} is the total z-derivative) and

$$v_N = (u_N)^{1/N}.$$
 (15)

Main result

Theorem 1 The above transformation sends the hierarchy

$$L_{t_n} = \left[R'_1(L^{\frac{n}{N}}), L \right] = \left[\left(L^{\frac{n}{N}} \right)_{\geq 1} + \epsilon P_0(L^{\frac{n}{N}})D, L \right]$$

$$k = 0, 1, 2, \quad n = 1, 2, \ldots, \quad n \not\equiv 0 \mod N$$

into the undeformed k = 1-hierarchy for v_i ,

$$\tilde{L}_{\tau_q} = [P_{\geq 1}(\tilde{L}^q), \tilde{L}], \quad q = 1, 2, \dots, q \not\equiv 0 \mod N,$$

for $\tilde{L} = \tilde{D}^N + \sum_{i=-\infty}^{N-1} v_i \tilde{D}^i$ along with a hierarchy of equations for v_N : $(v_N)_{\tau_q} = -\epsilon \tilde{D}(P_0(\tilde{L}^{q/N})), q = 1, 2, ..., q \not\equiv 0 \mod N.$ **Example: Extended Broer–Kaup hierarchy** Consider the extended Broer–Kaup system with $L = uD + v + D^{-1} \circ w$. From

$$L_{t_i} = [P_{\geq 1}(L^i) + \epsilon P_0(L^i)D, L]$$

with i = 1, 2 we obtain

$$\begin{pmatrix} u \\ v \\ w \end{pmatrix}_{t_1} = \begin{pmatrix} \epsilon u_x v - \epsilon u v_x \\ u v_x + \epsilon v v_x \\ u_x w + u w_x + \epsilon v_x w + \epsilon v w_x \end{pmatrix}$$

Extended Broer–Kaup system

$$u_{t_{2}} = \epsilon u_{x}v^{2} - 2\epsilon uvv_{x} - 2\epsilon u^{2}w_{x} - \epsilon u^{2}v_{xx}$$

$$v_{t_{2}} = 2uu_{x}w + 2uvv_{x} + 2u^{2}w_{x} + uu_{x}v_{x} + u^{2}v_{xx}$$

$$+\epsilon v^{2}v_{x} + 2\epsilon uv_{x}w + \epsilon uv_{x}^{2}$$

$$w_{t_{2}} = 2u_{x}vw + 2uv_{x}w + 2uvw_{x} - u_{x}^{2}w - 3uu_{x}w_{x}$$

$$-uu_{xx}w - u^{2}w_{xx} + 2\epsilon u_{x}w^{2}$$

$$+2\epsilon vv_{x}w + \epsilon u_{x}v_{x}w + \epsilon v^{2}w_{x} + 4\epsilon uww_{x}$$

$$+\epsilon uv_{x}w_{x} + \epsilon uv_{xx}w.$$

Upon setting $\epsilon = 0$ and u = 1 we recover from the second (t_2) flow the standard Kaup-Broer system.

Transformation to the Broer–Kaup hierarchy By Theorem 1, pass from x and $t_{1,2}$ to z and $\tau_{1,2}$ defined by the formulas $\tau_1 = t_1$, $\tau_2 = t_2$, and

$$dz = (1/u)dx + \epsilon(v/u)dt_1 + (\epsilon/u)(2wu + uv_x + v^2)dt_2$$

(we ignore here the times t_i with $i \neq 1, 2$). We have $\partial_x = (1/u)\partial_z$, so L goes into

$$\tilde{L} = \left(uD + v + D^{-1} \circ w\right)_{D = (1/u)\tilde{D}} = \tilde{D} + v + \tilde{D}^{-1} \circ r,$$

where r = wu.

Transformation to the Broer–Kaup hierarchy II

We readily see that the transformed hierarchy

$$\tilde{L}_{\tau_q} = [P_{\geq 1}(\tilde{L}^q), \tilde{L}], \quad q = 1, 2, \dots,$$

is nothing but the *standard* Broer–Kaup hierarchy for v, r with the independent variables z and τ_i , and we have separated equations for u which are linear on the background of this hierarchy:

$$u_{\tau_q} = -\epsilon \tilde{D}(P_0(\tilde{L}^{q/N})), q = 1, 2, \dots$$

Dispersionless limit

Theorem 1 remains valid if we replace the algebra \mathfrak{A} by its dispersionless (or *quasiclassical*) limit: $D \rightarrow p, [,] \rightarrow \{,\}, \{,\}$ is the Poisson bracket:

$$\{f,g\} = D(f)\frac{\partial g}{\partial p} - D(g)\frac{\partial f}{\partial p}$$

Now $L = \sum_{i=-\infty}^{N} u_i p^i$ is a function rather than an operator, the reciprocal transformation is the same: from x and t_i we pass to z and τ_i , where $\tau_i = t_i, i = 1, 2, ...,$ where z is defined by $dz = (u_N)^{-1/N} dx + \epsilon \sum_{q=1,q \neq 0}^{\infty} (u_N)^{-1/N} P_0(L^{q/N}) dt_q.$

Dispersionless limit II

New dependent variables v_i are now related to u_i by means of the formulas

$$\begin{split} \tilde{L} &= L|_{p=(u_N)^{-1/N}\tilde{p}} = \sum_{i=-\infty}^{N} u_i ((u_N)^{-1/N}\tilde{p})^i \\ &\equiv \tilde{p}^N + \sum_{i=-\infty}^{N-1} v_i \tilde{p}^i, \end{split}$$

i.e.,

$$v_i = u_i (u_N)^{-i/N},$$
 (16)

and

$$v_N = (u_N)^{1/N}.$$
 (17)

Main result for the dispersionless case

Theorem 2 The above transformation sends $L_{t_n} = \{R'_1(L^{\frac{n}{N}}), L\} = \{(L^{\frac{n}{N}})_{\geq 1} + \epsilon P_0(L^{\frac{n}{N}})p, L\}$ $k = 0, 1, 2, \quad n = 1, 2, \dots, \quad n \not\equiv 0 \mod N$ into the undeformed k = 1-hierarchy for v_i , $\tilde{L}_{\tau_a} = \{P_{>1}(\tilde{L}^q), \tilde{L}\}', \quad q = 1, 2, \dots, q \not\equiv 0 \mod N,$ for $\tilde{L} = \tilde{p}^N + \sum_{i=-\infty}^{N-1} v_i \tilde{p}^i$, where $\{f,g\}' = \tilde{D}(f)\frac{\partial g}{\partial \tilde{p}} - \tilde{D}(g)\frac{\partial f}{\partial \tilde{p}},$

along with a hierarchy for v_N :

 $(v_N)_{\tau_q} = -\epsilon \tilde{D}(P_0(\tilde{L}^{q/N})), q = 1, 2, \dots, q \not\equiv 0 \mod N.$

Conclusions

All integrable hierarchies constructed using the deformed *R*-matrices on \mathfrak{A} given for k = 0, 1, 2 by

$$R'_{k}(L) = P_{\geq k}(L) - \frac{1}{2}L + \epsilon P_{k-1}(L)D^{k}$$

= $\frac{1}{2}L - P_{$

can be reduced to linear extensions of the undeformed ($\epsilon = 0$) hierarchies using suitable changes of dependent and independent variables. The same holds for their dispersionless counterparts.