

A relative of the NLS equation revisited

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based on arXiv:2202.04512, Journal of Physics A

(largely similar work for the NLS equation:

O. Chvartatskyi and F. M.-H., J. Phys. A 50 (2017) 155204)

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Workshop on the occasion of Maxim Pavlov's 60th birthday

Introduction

The subject of this talk is the third-order nonlinear **PDE**

$$\left(\frac{f_{xt}}{f}\right)_t + 2(f^*f)_x = 0 \quad (1)$$

It is **completely integrable** (in the sense of possessing a Lax pair) if f is real. This is most likely **no longer true** if f is **complex**, without restriction. But in between, there is an integrable reduction of the latter case. Writing it as the **system**

$$a_t = (f^*f)_x \quad f_{xt} + 2af = 0 \quad (2)$$

the integrable reduction is obtained by restricting the function a to be **real** (which in fact still allows complex f).

A.L. Sakovich (arXiv:2205.09538): the reduction of the above system, where $a = a_1 + ia_2$, with real functions a_j , $j = 1, 2$, $a_2 \neq 0$, does **not** pass the **Painlevé test** of integrability.

A peculiar property of the PDE

A generalization of PDE (1) to higher dimensions is the system

$$\frac{\partial}{\partial t} \left(f^{-1} \frac{\partial}{\partial t} \frac{\partial}{\partial x^\mu} f \right) + 2 \frac{\partial}{\partial x^\mu} (f^* f) = 0 \quad \mu = 1, \dots, m$$

The left hand side behaves as the components of a covector (tensor of type (0,1)) under general coordinate transformations in m dimensions, if f is a scalar, also depending on a parameter t . This system thus defines dynamics of a scalar field on an m -dimensional differentiable manifold.

PDE (1) (and system (2)) is thus **invariant under general coordinate transformations** $x \mapsto x'$ in one dimension.

Kamchatnov and Pavlov, Phys. Lett. A 301 (2002) 269

Lax pair for a generalization of the SIT equations:

$$\begin{aligned} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}_x &= \begin{pmatrix} \lambda & q \\ r & -\lambda \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \\ \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}_\tau &= \frac{1}{\lambda - \zeta} \begin{pmatrix} a & b \\ c & -a \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \end{aligned}$$

Expansion in powers of ζ^{-1} ,

$$\frac{\partial}{\partial \tau} = \sum_{n \geq 0} \zeta^{-n} \frac{\partial}{\partial t_n}, \quad a = \sum_n \zeta^{-n} a_n, \quad b = \sum_n \zeta^{-n} b_n, \quad c = \sum_n \zeta^{-n} c_n$$

leads to recursion relations for the AKNS hierarchy equations.

Using instead

$$\frac{\partial}{\partial \tau} = \sum_{n \geq 1} \zeta^n \frac{\partial}{\partial t_{-n}}, \quad a = \sum_n \zeta^n a_{-n}, \quad b = \sum_n \zeta^n b_{-n}, \quad c = \sum_n \zeta^n c_{-n},$$

expansion in positive powers of ζ leads to recursion relations for the "**negative**" (or "reciprocal") AKNS hierarchy equations.

First "negative" AKNS flow:

$$(qr)_{t_1} = 2a_{-1,x}, \quad q_{t_{-1}x} = 4a_{-1}q, \quad r_{t_{-1}x} = 4a_{-1}r$$

Via $r = q^*$ and renamings, this becomes our system (2),

$$a_t = (f^*f)_x \quad f_{xt} + 2af = 0$$

The first "negative" AKNS flow has been studied by various scientists, including

H. Aratyn, L.A. Ferreira, J.F. Gomes, A.H. Zimerman 2000

M. Chen, S.-Q. Liu, Y. Zhang 2006

Soliton solutions:

J. Ji, J.B. Zhang and D.-J. Zhang 2009 via Hirota bilinearization

A. Dimakis, F. M.-H. 2010, 2011, V.E. Vekslerchik 2012

A vectorial binary Darboux transformation

Theorem

Let a_0, f_0 be a solution of the system (2) with real a_0 . Let n -comp. column vectors η_i , $i = 1, 2$, be solutions of the **linear system**

$$\begin{aligned} \Gamma \eta_{1x} &= a_0 \eta_1 + f_{0x}^* \eta_2 & \Gamma \eta_{2x} &= -a_0 \eta_2 + f_{0x} \eta_1 \\ \eta_{1t} &= -\frac{1}{2} \Gamma \eta_1 + f_0^* \eta_2 & \eta_{2t} &= \frac{1}{2} \Gamma \eta_2 - f_0 \eta_1 \end{aligned}$$

where Γ is an invertible constant $n \times n$ matrix. Requiring the spectrum condition $\text{spec}(\Gamma) \cap \text{spec}(-\Gamma^\dagger) = \emptyset$, let Ω be the unique solution of the rank 2 **Lyapunov equation**

$$\Gamma \Omega + \Omega \Gamma^\dagger = \eta_1 \eta_1^\dagger + \eta_2 \eta_2^\dagger$$

Where Ω^{-1} exists, $a = a_0 - (\eta_1^\dagger \Omega^{-1} \eta_1)_x$,

$$f = f_0 - \eta_1^\dagger \Omega^{-1} \eta_2$$

is also a solution of the system (2). f then solves PDE (1). \square

Lax pair

Writing the linear system in the form

$$\begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix}_x = \begin{pmatrix} a_0 \Gamma^{-1} & f_{0x}^* \Gamma^{-1} \\ f_{0x} \Gamma^{-1} & -a_0 \Gamma^{-1} \end{pmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix}$$

$$\begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix}_t = \begin{pmatrix} -\frac{1}{2} \Gamma & f_0^* I_n \\ -f_0 I_n & \frac{1}{2} \Gamma \end{pmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix}$$

where I_n is the $n \times n$ identity matrix, constitutes a **Lax pair** for the system (2) with **real** a , since its integrability condition is equivalent to a_0, f_0 satisfying the system (2) and $a_0^* = a_0$.

Note: the usual **spectral parameter** is promoted to a **matrix** Γ . This is typical for a **vectorial** generalization of a (binary) Darboux transformation. Basically, this can be traced back to **Marchenko's** work in the 1980s. (Also see, e.g., A.L. Sakhnovich 1994, F. Guil and M. Mañas 1996.)

Trivial seed solutions

If $f_0 = 0$, we choose $a_0 = -1/2$. Solution of the linear system:

$$\eta_1 = \exp\left(-\frac{1}{2}(\Gamma^{-1}x + \Gamma t)\right) v, \quad \eta_2 = \exp\left(\frac{1}{2}(\Gamma^{-1}x + \Gamma t)\right) w,$$

where v, w are constant n -component column vectors. Let Ω be the (unique) solution of the Lyapunov equation

$$\Gamma \Omega + \Omega \Gamma^\dagger = \eta_1 \eta_1^\dagger + \eta_2 \eta_2^\dagger.$$

Then

$$f = v^\dagger e^{-\frac{1}{2}(\Gamma^{-1}x + \Gamma^\dagger t)} \Omega^{-1} e^{\frac{1}{2}(\Gamma^{-1}x + \Gamma t)} w$$

solves PDE (1).

... with diagonal Γ

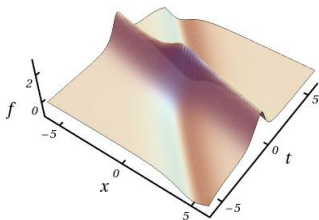
In this case we have

$$\Omega = (\Omega_{ij}) = \left(\frac{\eta_{1i} \eta_{1j}^* + \eta_{2i} \eta_{2j}^*}{\gamma_i + \gamma_j^*} \right) \quad \text{sum of 2 Cauchy-like matrices}$$

Example

Choosing $n = 2$, $\gamma_1 = 1$, $\gamma_2 = 2$ and $v_1 = v_2 = w_1 = w_2 = 1$, the above formula yields the special real 2-soliton solution

$$f = 6 \frac{\cosh(2t + \frac{1}{2}x) - 2 \cosh(t + x)}{\cosh(3t + \frac{3}{2}x) + 9 \cosh(t - \frac{1}{2}x) - 8}$$



Trivial seed, non-diagonal Γ

Without restriction, Γ can be chosen in Jordan normal form. In contrast to “simple solitons”, obtained with diagonal Γ , solutions determined by the above formula, with a non-diagonal Jordan matrix, depend also rationally on x and t .

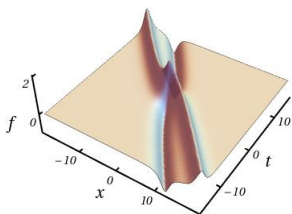
Example

$$\Gamma = \begin{pmatrix} \gamma & 0 \\ 1 & \gamma \end{pmatrix}, \quad \kappa := 2 \operatorname{Re}(\gamma)$$

$$\Rightarrow \Omega = \frac{1}{\kappa} \sum_{i=1}^2 \begin{pmatrix} |\eta_{i1}|^2 & \eta_{i1}(\eta_{i2} - \kappa^{-1}\eta_{i1})^* \\ \eta_{i1}^*(\eta_{i2} - \kappa^{-1}\eta_{i1}) & |\eta_{i2} - \kappa^{-1}\eta_{i1}|^2 + \kappa^{-2}|\eta_{i1}|^2 \end{pmatrix}$$

With $\gamma = v_1 = v_2 = w_1 = w_2 = 1$:

$$f = 4 \frac{\cosh(x+t) + (x-t) \sinh(x+t)}{1 + 2(x-t)^2 + \cosh(2(x+t))}$$



Jordan matrix solutions of the Lyapunov equation

$k \times k$ lower triangular Jordan matrix

$$\Gamma_{(k)} = \begin{pmatrix} \gamma & 0 & \cdots & \cdots & 0 \\ 1 & \gamma & \ddots & \ddots & 0 \\ 0 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & 1 & \gamma \end{pmatrix}$$

For $k \leq n$, let $\Omega_{(k)}$ be the solution of the Lyapunov equation with $\Gamma_{(k)}$ and with η_i replaced by $\eta_{i(k)} := (\eta_{i1}, \eta_{i2}, \dots, \eta_{ik})^T$, $i = 1, 2$.

$$\Omega_{(k+1)} = \begin{pmatrix} \Omega_{(k)} & B_{k+1} \\ B_{k+1}^\dagger & \omega_{k+1} \end{pmatrix}, \quad K_{(k)} := \Gamma_{(k)} \Big|_{\gamma \rightarrow \kappa}, \quad \kappa := 2 \operatorname{Re}(\gamma)$$

$$B_{k+1} := K_{(k)}^{-1} \left(\eta_{1(k)} \eta_{1,k+1}^* + \eta_{2(k)} \eta_{2,k+1}^* - \Omega_{(k)}(0, \dots, 0, 1)^T \right)$$

$$\omega_{k+1} := \frac{1}{\kappa} \left(|\eta_{1,k+1}|^2 + |\eta_{2,k+1}|^2 - 2 \operatorname{Re}[(0, \dots, 0, 1) B_{k+1}] \right)$$

... and their inverses

Solutions of the Lyapunov equation with Jordan matrices are thus **nested** and can be recursively computed.

For their inverses we have

$$\Omega_{(k+1)}^{-1} = \begin{pmatrix} \Omega_{(k)}^{-1} - S_{\Omega_{(k)}}^{-1} \Omega_{(k)}^{-1} B_{k+1} B_{k+1}^\dagger \Omega_{(k)}^{-1} & -S_{\Omega_{(k)}}^{-1} \Omega_{(k)}^{-1} B_{k+1} \\ -S_{\Omega_{(k)}}^{-1} B_{k+1}^\dagger \Omega_{(k)}^{-1} & S_{\Omega_{(k)}}^{-1} \end{pmatrix}$$

with the scalar Schur complement

$$S_{\Omega_{(k)}} = \omega_{k+1} - B_{n+1}^\dagger \Omega_{(k)}^{-1} B_{k+1}$$

(a special quasi-determinant). Hence also the inverses can be recursively computed.

Solutions with plane wave background

$$f_0 = C e^{i(\alpha x - \beta t)} \quad \alpha, \beta \in \mathbb{R}$$

Then $a_0 = -\alpha\beta/2$. Writing $\eta_1 = e^{-\frac{1}{2}i(\alpha x - \beta t)} \tilde{\eta}_1$,
 $\eta_2 = e^{\frac{1}{2}i(\alpha x - \beta t)} \tilde{\eta}_2$, the linear system can be simplified to

$$\tilde{\eta}_{1tt} - \left(\frac{1}{4}\tilde{\Gamma}^2 - |C|^2\right)\tilde{\eta}_1 = 0, \quad i\alpha\tilde{\eta}_{1t} + \Gamma\tilde{\eta}_{1x} = 0$$

$$\tilde{\eta}_2 = \frac{1}{C^*} \left(\tilde{\eta}_{1t} + \frac{1}{2}\tilde{\Gamma}\tilde{\eta}_1 \right) \quad \tilde{\Gamma} := \Gamma + i\beta I_n$$

If R is an invertible **matrix root** of

$$R^2 = \frac{1}{4}\tilde{\Gamma}^2 - |C|^2 I_n$$

this is solved by

$$\tilde{\eta}_1 = \cosh(\Theta) V, \quad \tilde{\eta}_2 = \frac{1}{2C^*} \left(\cosh(\Theta)\tilde{\Gamma} - 2R \sinh(\Theta) \right) V$$

with a constant n -component column vector V and

$$\Theta := i\alpha x (\tilde{\Gamma} - i\beta I_n)^{-1} R - t R + K$$

with a constant $n \times n$ matrix K that commutes with Γ (and R).

Solution of the PDE according to Theorem:

$$f = f_0 \left(1 - \frac{1}{|C|^2} V^\dagger \cosh(\Theta^\dagger) \Omega^{-1} (\cosh(\Theta) \tilde{\Gamma} - 2R \sinh(\Theta)) V \right)$$

The further elaboration only requires the solution Ω of the Lyapunov equation for specified Γ .

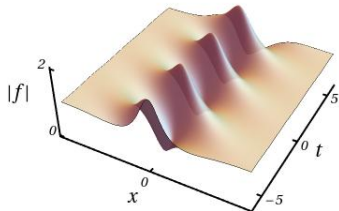
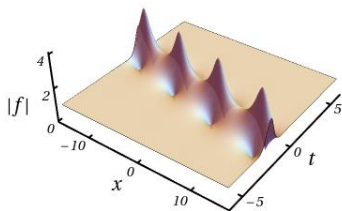
This leads to counterparts of **Akhmediev** and **Kuznetsov-Ma** breathers of the NLS equation.

For $n = 1$, we find

$$f = C e^{i(\alpha x - \beta t)} \left(1 - \frac{\operatorname{Re}(\tilde{\gamma}) \cosh(\Theta^*) (\tilde{\gamma} \cosh(\Theta) - 2r \sinh(\Theta))}{|C|^2 |\cosh(\Theta)|^2 + \frac{1}{4} |\tilde{\gamma} \cosh(\Theta) - 2r \sinh(\Theta)|^2} \right)$$

where now $\Theta = (i\alpha x / (\tilde{\gamma} - i\beta) - t)r + K$ with $r = \pm \sqrt{\frac{1}{4}\tilde{\gamma}^2 - |C|^2}$.

This is the counterpart of a single **Akhmediev breather** if $|\tilde{\gamma}| < 2|C|$ and a **Kuznetsov-Ma breather** if $|\tilde{\gamma}| > 2|C|$.



If Γ (and then also $\tilde{\Gamma}$) is an $n \times n$ Jordan matrix, a root of the quadratic equation is given by the Toeplitz matrix

$$R = \frac{1}{2} \sqrt{\tilde{\gamma}^2 - 4|C|^2} \begin{pmatrix} 1 & 0 & \dots & \dots & \dots & 0 \\ \tilde{\gamma}(\tilde{\gamma}^2 - 4|C|^2)^{-1} & 1 & \ddots & \ddots & \ddots & \vdots \\ -2(\tilde{\gamma}^2 - 4|C|^2)^{-2} & \ddots & \ddots & \ddots & \ddots & \vdots \\ 2\tilde{\gamma}(\tilde{\gamma}^2 - 4|C|^2)^{-3} & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ \vdots & & & \ddots & \ddots & \ddots & 1 \end{pmatrix}$$

Regularity of higher Akhmediev and Kuznetsov-Ma breathers

Proposition. Let $\tilde{\Gamma}$ be an $n \times n$ (lower triangular) Jordan matrix with $\operatorname{Re}(\tilde{\gamma}) \neq 0$ and $\tilde{\gamma} \neq \pm 2|C|$. Then the solution

$$f = f_0 \left(1 - \frac{1}{|C|^2} V^\dagger \cosh(\Theta^\dagger) \Omega^{-1} (\cosh(\Theta) \tilde{\Gamma} - 2R \sinh(\Theta)) V \right)$$

of PDE (1) is **regular** if the first component of the vector V is different from zero.

Without restriction of generality one can set $V = (1, 0, \dots, 0)^T$.



This mainly rests on the following (cf. Chvartatskyi and M.-H., J. Phys. A **50** (2017) 155204, Appendices A and B).

Proposition. Let Γ be a lower triangular $n \times n$ Jordan block with eigenvalue γ and $\operatorname{Re}(\gamma) \neq 0$. If the first component of one of the vectors η_i is different from zero, then the solution Ω of the rank k Lyapunov equation

$$\Gamma \Omega + \Omega \Gamma^\dagger = \sum_{i=1}^k \eta_i \eta_i^\dagger$$

is invertible.

Sketch of Proof: $\Omega = \sum_{i=1}^k \Omega_i$. If $\eta_{11} \neq 0$, then $\det(\Omega_1) \neq 0$. Furthermore, one can show that $\Omega_i = B_i^\dagger B_i$ with a matrix B_i .

$$\det(\Omega) = \underbrace{\det(B_1^\dagger)}_{\neq 0} \det\left(I_n + \underbrace{B_1^{-1\dagger} \left(\sum_{i=2}^k B_i^\dagger B_i\right) B_1^{-1}}_{\text{positive semi-definite}}\right) \underbrace{\det(B_1)}_{\neq 0} \neq 0$$



A degenerate case of the linear system

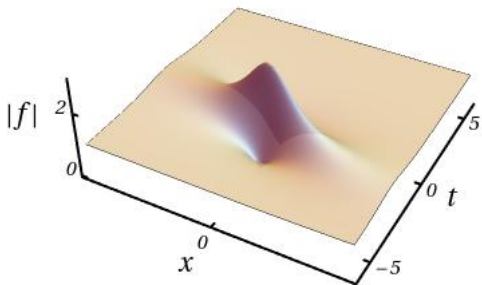
Example

Let $n = 1$ and $\tilde{\gamma} = 2|C|$. Then we have

$$\begin{aligned}\tilde{\eta}_1 &= c_0 + c_1 \left(\frac{\alpha x}{2i|C| + \beta} + t \right), & \tilde{\eta}_2 &= \frac{C}{|C|} \tilde{\eta}_1 + \frac{c_1}{C^*} \\ \Omega &= \frac{1}{4|C|} \left(2 \left| \tilde{\eta}_1 + \frac{c_1}{2|C|} \right|^2 + \frac{|c_1|^2}{2|C|^2} \right) \\ f &= C e^{i(\alpha x - \beta t)} \left[1 - \frac{1}{|C|\Omega} \left(\left| c_0 + c_1 \left(\frac{\alpha x}{2i|C| + \beta} + t \right) \right|^2 \right. \right. \\ &\quad \left. \left. + \frac{c_1}{|C|} \left[c_0^* + c_1^* \left(\frac{\alpha x}{-2i|C| + \beta} + t \right) \right] \right) \right]\end{aligned}$$

This quasi-rational solution is the counterpart of the **Peregrine breather** solution of the focusing NLS equation, which models a **rogue wave**.

Counterpart of Peregrine breather



Counterparts of **higher order Peregrine breathers** are obtained if $\tilde{\Gamma}$ is a Jordan matrix with eigenvalue $\tilde{\gamma} = 2|C|$.
(For NLS: exhaustively elaborated by V.B. Matveev.)

Proposition. Let

$$\mathcal{N} := \frac{1}{4} \tilde{\Gamma}^2 - |C|^2 I_n$$

be nilpotent of degree $N > 0$. The linear system is then solved by

$$\begin{aligned} \tilde{\eta}_1 &= (R_1(\mathcal{N}, t) R_1(-\alpha^2 \Gamma^{-2} \mathcal{N}, x) - i \alpha \Gamma^{-1} \mathcal{N} R_2(\mathcal{N}, t) R_2(-\alpha^2 \Gamma^{-2} \mathcal{N}, x)) v \\ &\quad + (R_1(\mathcal{N}, t) R_2(-\alpha^2 \Gamma^{-2} \mathcal{N}, x) + \frac{i}{\alpha} \Gamma R_2(\mathcal{N}, t) R_1(-\alpha^2 \Gamma^{-2} \mathcal{N}, x)) w \\ \tilde{\eta}_2 &= \frac{1}{C^*} \left(\tilde{\eta}_{1t} + \frac{1}{2} \tilde{\Gamma} \tilde{\eta}_1 \right) \end{aligned}$$

with constant n -component vectors v, w , and

$$R_1(\mathcal{N}, t) := \sum_{k=0}^{N-1} \frac{t^{2k}}{(2k)!} \mathcal{N}^k, \quad R_2(\mathcal{N}, t) := \sum_{k=0}^{N-1} \frac{t^{2k+1}}{(2k+1)!} \mathcal{N}^k$$



Regularity of higher order Peregrine breathers

Proposition. Let $\tilde{\Gamma}$ be a (lower triangular) Jordan matrix with eigenvalue $\tilde{\gamma} = 2|C|$. Let η_1, η_2 be the above solution of the linear system. The solution of PDE (1), obtained via the vectorial binary Darboux transformation, is then regular if the first component of v is different from zero. Without restriction of generality, we can set $v = (1, 0, \dots, 0)^T$. □

More general solutions

... can be generated by solving the Lyapunov equation with

$$\Gamma = \begin{pmatrix} \Gamma_{k_1} & 0 & \cdots & \cdots & 0 \\ 0 & \Gamma_{k_2} & \ddots & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & 0 \\ 0 & \cdots & \cdots & 0 & \Gamma_{k_m} \end{pmatrix}$$

where Γ_{k_i} is the $k_i \times k_i$ Jordan block with eigenvalue γ_i .

Origin of the above Darboux transformation: bidifferential calculus

A **graded associative algebra** is an associative algebra

$$\Omega = \bigoplus_{r \geq 0} \Omega^r$$

over a field \mathbb{K} of characteristic zero, where $\mathcal{A} := \Omega^0$ is an associative algebra over \mathbb{K} and Ω^r , $r \geq 1$, are \mathcal{A} -bimodules such that $\Omega^r \Omega^s \subseteq \Omega^{r+s}$. Elements of Ω^r are called **r -forms**.

A **bidifferential calculus** is a unital graded associative algebra Ω , supplied with two \mathbb{K} -linear **graded derivations**

$$d, \bar{d} : \Omega^r \rightarrow \Omega^{r+1}$$

and such that

$$d^2 = \bar{d}^2 = d\bar{d} + \bar{d}d = 0$$

bDT in bidifferential calculus

Theorem. Given a bidifferential calculus, let 0-forms Δ, Γ and 1-forms κ, λ satisfy

$$\begin{aligned}\bar{d}\Delta + [\lambda, \Delta] &= (d\Delta) \Delta, & \bar{d}\lambda + \lambda^2 &= (d\lambda) \Delta, \\ \bar{d}\Gamma - [\kappa, \Gamma] &= \Gamma d\Gamma, & \bar{d}\kappa - \kappa^2 &= \Gamma d\kappa\end{aligned}$$

Let 0-forms θ and η be solutions of the linear equations

$$\bar{d}\theta = (d\phi) \theta + (d\theta) \Delta + \theta \lambda, \quad \bar{d}\eta = -\eta (d\phi) + \Gamma d\eta + \kappa \eta$$

where the 0-form ϕ satisfies

$$\boxed{\bar{d}d\phi = d\phi d\phi}$$

Furthermore, let Ω be an invertible solution of the linear system

$$\boxed{\Gamma \Omega - \Omega \Delta = \eta \theta} \quad (\text{generalization of Sylvester equation})$$

$$\bar{d}\Omega = (d\Omega) \Delta - (d\Gamma) \Omega + \kappa \Omega + \Omega \lambda + (d\eta) \theta$$

Then

$$\boxed{\phi' = \phi - \theta \Omega^{-1} \eta + K}$$

with $dK = 0$ solves the same equation. □

Application to the first negative AKNS flow

Let \mathcal{A} be the commutative algebra of smooth functions on \mathbb{R}^2 and $\text{Mat}(\mathcal{A})$ the algebra of all matrices over \mathcal{A} , where the product of two matrices is defined to be zero whenever their dimensions do not fit. We choose

$$\Omega = \text{Mat}(\mathcal{A}) \otimes \bigwedge \mathbb{C}^2,$$

where $\bigwedge \mathbb{C}^2$ is the exterior algebra of the vector space \mathbb{C}^2 . Let ξ_1, ξ_2 be a basis of $\bigwedge^1 \mathbb{C}^2$. For an $m \times n$ matrix F over \mathcal{A} , let

$$dF = F_x \xi_1 + \frac{1}{2}(J_m F - F J_n) \xi_2, \quad \bar{d}F = \frac{1}{2}(J_m F - F J_n) \xi_1 + F_t \xi_2$$

where $J_2 = \text{diag}(1, -1)$ etc. (A. Dimakis, F. M.-H. 2010).

Then $\bar{d}d\phi = d\phi d\phi$ with

$$\phi = \begin{pmatrix} p & f \\ q & -p \end{pmatrix} \quad a := p_x - \frac{1}{2}$$

becomes the **first negative flow of the AKNS hierarchy**

$$a_t = (fq)_x, \quad f_{xt} = -2af, \quad q_{xt} = -2aq,$$

and the last theorem can be worked out to obtain a vectorial binary Darboux transformation for it.

Finally, we impose the **reduction**

$$q = f^*$$

to obtain our vectorial Darboux transformation for system (2).

Remarks

- The PDE admits generalizations of the 1-soliton solution to Jacobi elliptic functions, which could also serve as seed for the bDT. Can this be worked out in some detail ?
- There are \bar{d} and \bar{d} such that $\bar{d}d\phi = d\phi d\phi$ becomes the whole "negative" (or "reciprocal") AKNS hierarchy, see Dimakis and M.-H., SIGMA **6** (2010) 055.
- Rusuo Ye (2022): a Riccati-type Miura transformation from **Fokas-Lenells system**

$$q + q_{xt} - 2iqrq_x = 0 \quad r + r_{xt} + 2irqr_x = 0$$

to the first negative AKNS system.

Still open: a bidifferential calculus for the FL system.

- What more can be concluded about the **non**-integrable reduction of PDE (1) ?

Thanks for your attention !

Many thanks to Maxim for valuable help over the years and very pleasant times together !

All the best for Maxim for the next decades !

And thanks to Joseph for organizing this meeting !