Exact solutions and upscaling for 1D hyperbolic flows in micro heterogeneous media

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$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = 0
$$





Mass conservation law with flux a function of density

 0, <sup>v</sup> v f t x 

1D flow with density-dependent flux function

$$
\rho v = f\left(\rho, x\right)
$$

Scalar conservation law with density-dependent flux function

$$
\frac{\partial s}{\partial t} + \frac{\partial f(s, x)}{\partial x} = 0
$$

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### Upscaling in micro heterogeneous media







#### Composite core

# Upscaling in numerical methods



Numerical schema for characteristic finitedifference solution of 1D transport equation: how to transform from dense grid to coarse grid?



# Schematic for upscaling

$$
F = F(S), S = F^{-1}(f)
$$

$$
F^{-1}(f) = \int\limits_{0}^{x_N} f^{-1}(f, y) dy
$$





With application of the upscaling for each numerical cell [x<sub>n</sub>,<sub>xn+1</sub>], the solution for microscale and upscaled systems, F(S) and f(s,x), coincide in all nodes  $x_n$ 

## **Contents**

Introduction:

- 1. Reminder of Riemann solution for f=f(s)
- 2. For f=f(s,x), flux is a Riemann invariant
- 3. Exact solutions of Riemann problem: rarefaction, shock, transitional solutions
- 4. Exact solution for any problem with ICs and BCs
- 5. Upscaling

Extensions of the approach

Conclusions <sup>6</sup>

# 1. Riemann' problems for conservation law

Cauchy' problem IC:

$$
t = 0 : s(x, 0) = \begin{cases} s_L, & x < 0 \\ s_R, & x > 0 \end{cases}
$$

Initial-boundary value problem BC:

$$
t = 0
$$
:  $s(x, 0) = s_L$ ,  $x = 0$ ,  $s(0, t) = s_R$ 

$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = 0
$$



R

 $\mathbf{r}$ 

$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = 0
$$

Self-similar solution:

$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = 0
$$
  
\nSelf-similar solution:  
\n
$$
x = 0 : s = s_L, \qquad t = 0 : s = s_R \qquad \int_{s}^{R} f(s) ds
$$
\n
$$
s(x, t) = S(v), \quad v = x/t, \qquad \int_{s}^{R} f(s) ds
$$
\n
$$
(v = 0) : s = s_L, \qquad (v \to \infty) : s = s_L \qquad \int_{s}^{R} f(s) ds
$$

S(v)=const over x=vt, v is the velocity, so value S is transported with speed v

Two types of continuous solutions:

$$
S(v) = const, v = f'_{s}(s)
$$

The Riemann solution consists of permanent state  $s(v)=s_L$ , f  $,$ rarefaction wave

$$
\frac{x}{t} = v = f'_{s}(s)
$$

and permanent state  $s(v)=s_R$ 

xerial divided in the solutions:<br>  $S(v) =$ <br>  $S(v) = S<sub>L</sub>,$ S

This solution is continuous

Exact solution for Riemann problem Exact solution for Riemann problem<br>for convex f-f-function f=f(s) - I<br> $\frac{\partial s}{\partial s} + \frac{\partial f(s)}{\partial s} = 0$ 



$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = 0
$$

m  
\n
$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = 0
$$
\n
$$
s(x,t) = \begin{cases}\nS_J, & 0 < \frac{x}{t} < f'(S_J) \\
\frac{x}{t} = \langle f \rangle'(s), & f'(S_J) < \frac{x}{t} < f'(S_J) \\
S_J, & f'(S_J) < \frac{x}{t} < \infty\n\end{cases}
$$

In continuous solution s=s(v), speed v must increase from zero to infinity. If  $S_L(S)$  is less than  $S_R(S^+)$ ,  $v$ decreases, so there is no continuous solution.





A discontinuous solution of hyperbolic equation

is admissible (stable)

if it is a limit of continuous solution of the equation with vanishing viscosity

The admissibility conditions: (i) Mass balance on the shock

$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = 0
$$

$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = \varepsilon \frac{\partial^2 s}{\partial x^2}
$$

n 
$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = 0
$$

$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = \varepsilon \frac{\partial^2 s}{\partial x^2}
$$

$$
D = \frac{dx_f(t)}{dt}, \quad f(s^-) - f(s^+) = D(s^- - s^+)
$$

(ii) Shock stability with respect to linear perturbations (Lax)

$$
f'_{s}(s^{+}) < D < f'_{s}(s^{-}) \qquad \qquad \text{if}
$$

Shock stability with respect to any perturbations (Oleinik)





 $(s)$  $= 0$  $\partial t$   $\partial x$  $\partial S$  $\pm$ 

Exact solution for Riemann problem for concave f-f-function Figure  $\left\{\begin{array}{c}\n\begin{array}{c}\n\frac{1}{s_1}\n\end{array}\n\end{array}\right\}$ <br>
Exact solution for Riemann<br>
problem for concave f-f-function<br>
f=f(s) – III – is shock wave with<br>
volume balance of the front<br>
(Hugoniot condition) volume balance of the front Exact solution for Riemann<br>
problem for concave f-f-function<br>
f=f(s) – III – is shock wave with<br>
volume balance of the front<br>
(Hugoniot condition)

$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = 0
$$
  

$$
s(x,t) = \begin{cases} s = S_J, & 0 < \frac{x}{t} < D = \frac{1}{S_I - S_J} \\ s = S_I, & D < \frac{x}{t} < \infty \end{cases}
$$

## Riemann' self-similar solution L→R for hyperbolic equation



 $(S)$  $= 0$  $f(s)$  $t$   $\partial x$  $\partial s$  $+$  $\partial t$   $\partial x$ 

## Determining  $f(s)$  from lab  $f(s(1,t))$ , i.e. from f-data at  $x=1$

$$
\frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} = 0
$$
  

$$
0 = \iint_{\Omega} \left[ \frac{\partial s}{\partial t} + \frac{\partial f(s)}{\partial x} \right] dx dt = \oint_{\Gamma} f dt - s dx
$$
  

$$
-S_I + \int_{0}^{t} f \left[ s(1, y) \right] dy = f \left[ s(1, t) \right] t - s(1, t)
$$



Given  $f(s(1,t))$ , we calculate  $s(1,t)$  for all  $t>0$ 

The inverse solution does not involve direct solution s(x,t) rather using its self-similarity alone

#### 2. Analysis of microscale equation with  $f=f(s,x)$

Multiplying by 
$$
f'_s
$$
  $f'_s \frac{\partial s}{\partial t} + f'_s \frac{\partial f(s, x)}{\partial x} = 0$   $\frac{\partial f(s, x)}{\partial t} + f'_s \frac{\partial f(s, x)}{\partial x} = 0$ 

Characteristic's form:

Characteristic's form:  
\n
$$
\frac{dx}{dt} = f'_s, \frac{df}{dt} = 0, \qquad f = f(s, x), \ s = f^{-1}(f, x)
$$
\nllicit expression for f-characteristics  $t = \tau(x, f)$   
\n
$$
\int_{0}^{x} = f'_s \left( f^{-1}(f, x), x \right) \qquad t = \int_{x_0}^{x} \frac{dy}{f'_s \left( f^{-1}(f(s_0(x_0)), y), y \right)}
$$

Implicit expression for f-characteristics  $t = \tau(x, f)$ 

$$
\frac{dx}{dt} = f'_{s}\left(f^{-1}\left(f,x\right),x\right)
$$

$$
(x, x), s = f^{-1}(f, x)
$$
  
\n
$$
\tau(x, f)
$$
  
\n
$$
t = \int_{x_0}^{x} \frac{dy}{f_s'\left(f^{-1}\left(f(s_0(x_0)), y\right), y\right)}
$$

## 3. Continuous solution for convex FFF



FFF curve II at  $x=0$ ,



#### Shock wave solution for concave FFF





Transition from shock to continuous wave with  $\mathbf{t}_{1}$ FFF decreasing in  $x$  from concave to convex  $\qquad \qquad \tiny \begin{array}{c} (a) \end{array}$ 



FFF V that is concave at 0<x<x<sub>c</sub>, straight line at  $x=x_c$ ,  $\qquad \qquad \qquad \Box$ and convex I at  $x_c < x < 1$ 



Transition from continuous wave to  $\mathbf{t}^1$ shock with FFF increasing in x from  $\mathbb{R}^6$ convex to concave



FFF I that is convex at  $0 <$ x $<$ x $_{c}$ , straight line at  $x=x_c$ , and concave V at  $x_c$ < $x$ <1



### Riemann's solution for S-shaped FFF





4. Exact continuous solution for any initial-boundary value problem

$$
t = 0: \ s = s_0(x) \qquad x = 0: \ f = f_0(t) \qquad \int_0^t \frac{dt}{\sqrt{t}} \, dt
$$
\n
$$
\text{Trajectory of characteristic carrying flux } t = \tau(x, f) \qquad \int_0^t \frac{dt}{\sqrt{t}} \, dt
$$
\n
$$
s(x, t) = \begin{cases} f^{-1}(f(s_0(x_0), x_0), x_0), \ t = \int_{x_0}^x \frac{dy}{f'_s(f^{-1}(f(s_0(x_0), x_0), y), y)}, \ t < \tau(x, f_0(0)) \\ f^{-1}(f_0(t_0), x), \ t = t_0 + \int_0^x \frac{dy}{f'_s(f^{-1}(f_0(t_0), y), y)}, \ t > \tau(x, f_0(0)) \end{cases}
$$

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#### 5. Upscaling of Riemann problem

Lab determining of fractional flow function f(s) from breakthrough water-cut history is a common method. It is valid for the case of micro-heterogeneous media  $f=f(s,x)$ ?

In lab, upscaling must give the same values at the end of core x=1.

Applying Green's theorem:

$$
\iint_{\Omega} \left[ \frac{\partial s}{\partial t} + \frac{\partial f(s, x)}{\partial x} \right] dx dt = \oint_{\Gamma} f dt - s dx = 0
$$



Integrals over the sides of curvilinear triangle:

$$
I: \oint_{\Gamma} f dt - s dx = -S_I
$$
  

$$
II: \oint_{\Gamma} f dt - s dx = \int_{0}^{t} f \Big[ s (1, t), I \Big] dt
$$

III : 
$$
\oint_{\Gamma} f dt - s dx = ft - \langle S(f, x) \rangle = ft - \langle f^{-1}(f, x) \rangle
$$

Comparing with self-similar case

 $\int_T T(\delta) dt - \delta dx - T\left(\frac{\delta}{t}\right)t - \delta\left(\frac{\delta}{t}\right)$  $\left(1\right)$   $\left(1\right)$  $\oint_{\Gamma} F(S) dt - S dx = F\left(\frac{I}{t}\right) t - S\left(\frac{I}{t}\right)$ 1 1  $\theta$  $s(f) = \int f^{-1}(f,x)dx$ 

we obtain the upscaling formula

$$
24\quad
$$



## 6. Upscaling of f(s,x) for any IC BC

Consider the case where  $t > \tau(0, f_0(0))$  and domain  $\Omega$  bounded by curvilinear rectangular  $\Gamma = \partial \Omega$ :  $(0,0) \rightarrow (1,0) \rightarrow (1,t) \rightarrow (0,t_0) \rightarrow (0,0)$  where  $f=const$  along the side  $(0,t_0) \rightarrow (1,t)$ 

6. Upscaling of 
$$
f(s,x)
$$
 for any IC BC  
\nConsider the case where  $t > \tau(0,f_0(0))$  and domain  $\Omega$  bounded by curvilinear rectangular  
\n $F = \partial \Omega$ :  $(0,0) \rightarrow (1,0) \rightarrow (1,t) \rightarrow (0,t_0) \rightarrow (0,0)$  where  $f = const$  along the side  $(0,t_0) \rightarrow (1,t)$   
\n
$$
-\int_0^t s_0(x,0)dx, \quad \int_0^t f_1(y)dy, \quad -f_1(t)t + \int_0^t f^{-1}(f_1(t),x)dx, -\int_0^{t_0} f_0(y)dy
$$
\n
$$
t = \tau(f_0(t_0),1), \quad f_1(t) = f_0(t_0)
$$
\n
$$
(0,t_0)
$$
\n
$$
0 \qquad t = \tau(f_1(t_0)) = \int_0^t f^{-1}(f_1(t),x)dx = \int_0^{t_0} f_0(y)dy - \int_0^t (f_1(t) - f_1(y))dy + \int_0^t s_0(x,0)dx
$$

$$
S(I,t) = F^{-1}(f_I(t)) = \int_0^1 f^{-1}(f_I(t),x)dx = \int_0^{t_0} f_0(y)dy - \int_0^t (f_I(t) - f_I(y))dy + \int_0^1 s_0(x,0)dx
$$

#### **Microscale**

Microsoft: 
$$
S(I,t) = F^{-1}(f_I(t)) = \int_0^t f^{-1}(f_I(t),x) dx = \int_0^{t_0} f_0(y) dy - \int_0^t (f_I(t) - f_I(y)) dy + \int_0^t s_0(x,0) dx
$$

\nwhere  $f$  is the function  $f$  and  $f$  is the function  $f$ 



 $t\uparrow$ 

# Schematic for upscaling  $f=F$

$$
F^{-1}(f) = \int_{0}^{1} f^{-1}(f, y) dy
$$



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#### 7. Upscaling of piecewise-constant periodical system (composite core) three periods



$$
S(f) = \int_{0}^{1} f^{-1}(f, x) dx
$$



 $\alpha$  – fraction of the rock with ff f<sub>0</sub> in the overall core  $1-\alpha$  – fraction of the rock with ff  $f_1$  in the overall core  $\alpha = 0.4$ 

Flow in periodical two-piece (composite) porous media

Water

Microscale solutions are different for two cores. They coincide at macro scale

 $\alpha$  1 –  $\alpha$ 

 $Blue$   $co<sub>2</sub>$ 

core



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8. Numerical 
$$
t=0
$$
:  $s=s_0(x)$   $x=0$ :  $f=f_0(t)$ 





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Numerical schema for characteristic finite-difference solution of 1D two-phase transport equation

$$
f = F_n(s), \ s = f^{-1}(f), \ x \in [x_n, x_{n+1}], \ n = 0, 1...N, \ x_0 = 0, \ x_N = 1
$$

$$
f(s(x_n, t), x) = F_n(s(x_n, t))
$$

# Some extensions

Proposed Upscaling = exact solution at micro scale for  $f(s,x)$  + exact inverse solution at upper scale

Linear PDEs: exact solution by Green's function and inverse problem for its integral equation

# Scalar conservation laws

$$
\frac{\partial s}{\partial t} + \frac{\partial f(s,t)}{\partial x} = 0
$$
 Time-dependent

$$
\frac{\partial f(s,x)}{\partial t} + \frac{\partial s}{\partial x} = 0
$$

Space-dependent adsorption

flux

 $(s,t)$   $\partial s$ 0  $f(s,t)$   $\partial s$  $t \qquad \partial x$  $\partial\!f\left(\,s,t\,\right)\quad\partial\mathbf{r}$  $\partial t$   $\partial x$  $+\frac{CS}{2}=0$ 

Time-dependent adsorption

"Multicomponent" flows

S is the density, f is the advective flux, c-concentration of an additive, "Multicomponent" flows<br>
S is the density, f is the advective flux, c-concentration of an additive,<br>
cf is the advective flux of the additive, a – adsorption concentration<br>  $\frac{\partial s}{\partial t} + \frac{\partial f(s,c)}{\partial t} = 0$ ,  $\frac{\partial (cs + a(c))}{\partial t} + \frac$ 

ulticomponent" flows

\nis the density, f is the advective flux, c-concentration of an additive, s the advective flux of the additive, a – adsorption concentration

\n
$$
\frac{\partial s}{\partial t} + \frac{\partial f(s, c)}{\partial x} = 0, \qquad \frac{\partial (cs + a(c))}{\partial t} + \frac{\partial (cf)}{\partial x} = 0
$$
\n
$$
d\varphi = fdt - sdf, \quad \varphi = \int fdt - sdf, \quad s(x, t) = S(x, \varphi), c(x, t) = C(x, \varphi)
$$
\n
$$
\frac{\partial a(c)}{\partial \varphi} + \frac{\partial c}{\partial x} = 0
$$

The solution  $c(x, \phi)$  contains shocks only if

$$
t=0: c=0, x=0: c=1, a^{n/2}(c) < 0
$$

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#### Conclusions

For any initial-boundary value problem of f(s,x), the flux is Riemann invariant; the characteristics allow for 1st integral yielding implicit formulae for the characteristics. First integrals for front trajectories are obtained by integration of differential mass balance form  $f(s,x)dt-sdx$  over the closed contours in plane  $(x,t)$ that comprise two arriving characteristics  $f$  and  $f^*$  and the intervals of axes x and t where the initial-boundary values are given.

Saturation S that corresponds to upscaled value  $F=F(S)$  is an average in x of the "microscale" inverse function  $s=f^{-1}(F,x)$ .

The numerical solution obtained by an explicit finite difference method with advance over  $\Delta x$  for micro scale model, coincides with the solution for the largescale system obtained by history-based upscaling, in the points on numerical cell boundaries  $x_0, x_1, ..., x_n$ .

There are two challenges:

There are two challenges:<br>1 - Lab determining of fractional flow function f(s) from breakthrough water-cut history is a<br>common method. It is valid for the case of micro-heterogeneous media f=f(s,x)?<br>In lab, upscaling must common method. It is valid for the case of micro-heterogeneous media f=f(s,x)?

In lab, upscaling must give the same values at the end of core x=1. Upscaling of Riemann problem

There are two challenges:<br>1 - Lab determining of fractional flow function f(s) from breakthrough water-cut history is a<br>common method. It is valid for the case of micro-heterogeneous media f=f(s,x)?<br>In lab, upscaling must numerical model, i.e. f=f(s,x). How to calculate f(s) that will present the same results at the course grid?

In numerical model, the same numerical finite-difference solution. Upscaling of initialboundary value problem



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## Upscaling in micro heterogeneous formations



$$
\frac{\partial s}{\partial t} + \frac{\partial f(s, x)}{\partial x} = 0
$$
  

$$
\frac{\partial s}{\partial t} + \frac{\partial F(s)}{\partial x} = 0
$$



Schematic for displacement of water by gas





Numerical schema for characteristic finite-difference solution of 1D transport equation

Shock occurs near to v=D

Mass balance on the shock

Stability of solution with respect to small perturbations in linearised equation

Stability of solution with respect to small perturbations in original equation

Discontinuous solutions – shocks, jumps:

\n
$$
S(D-0) = S^-, S(D+0) = S^+, v = D
$$
\nock occurs near to v=D

\n
$$
S(v) = \begin{cases} S^+, & v > D \\ S^-, & v < D \end{cases}
$$
\nss balance on the shock

\nblility of solution with respect to small

\nturbations in linearised equation

\n
$$
f'(S^-) < D < f'(S^+)
$$
\nblity of solution with respect to small

\nturbations in original equation

\n
$$
D > \frac{f(s(v)) - f(S^-)}{s(v) - S^-}
$$
\n
$$
S(v) = \frac{f(s(v)) - f(S^-)}{s(v) - S^-}
$$

2. Mass balance for 1D flow in micro heterogeneous flow



