

Internal Lagrangians and gauge systems

Kostya Druzhkov

Department of Mathematics and Statistics
University of Saskatchewan

Geometry of Differential Equations, IUM
May 1, 2024

Classical Hamiltonian formalism

Canonical equations

$$\dot{p}_i = -\frac{\partial H}{\partial q^i}, \quad \dot{q}^i = \frac{\partial H}{\partial p_i} \quad (1)$$

Configuration manifold $K : q^1, \dots, q^N$.

Infinitely prolonged system (1)

$$\mathcal{E} : t, q^1, \dots, q^N, p_1, \dots, p_N, \quad \bar{D}_t = \partial_t + \frac{\partial H}{\partial p_i} \partial_{q^i} - \frac{\partial H}{\partial q^i} \partial_{p_i} \quad (2)$$

Paths through instantaneous states

$$\begin{array}{ccc} \mathcal{E} = T^*K \times \mathbb{R} & & \ell = p_i dq^i - H dt \in \Lambda^1(\mathcal{E}) \\ \sigma \begin{array}{c} \uparrow \\ \downarrow \pi_{\mathcal{E}} \\ \mathbb{R} \end{array} & \sigma : \begin{cases} q^i = f^i(t) \\ p_i = g_i(t) \end{cases} & \sigma \mapsto \int_{t_0}^{t_1} \sigma^*(\ell) \end{array} \quad (3)$$

$\bar{D}_t \rightarrow$ Hamiltonian dynamics \Leftrightarrow autonomy + the trivial connection on $\pi_{\mathcal{E}}$.

Before the Legendre transformation: L and $\pi_{\mathcal{E}} : TK \times \mathbb{R} \rightarrow \mathbb{R} \Rightarrow \ell$.

Classical Hamiltonian formalism

Canonical equations

$$\dot{p}_i = -\frac{\partial H}{\partial q^i}, \quad \dot{q}^i = \frac{\partial H}{\partial p_i} \quad (1)$$

Configuration manifold $K : q^1, \dots, q^N$.

Infinitely prolonged system (1)

$$\mathcal{E} : t, q^1, \dots, q^N, p_1, \dots, p_N, \quad \bar{D}_t = \partial_t + \frac{\partial H}{\partial p_i} \partial_{q^i} - \frac{\partial H}{\partial q^i} \partial_{p_i} \quad (2)$$

Paths through instantaneous states

$$\begin{array}{ccc} \mathcal{E} = T^*K \times \mathbb{R} & & \ell = p_i dq^i - H dt \in \Lambda^1(\mathcal{E}) \\ \sigma \begin{array}{c} \uparrow \\ \downarrow \pi_{\mathcal{E}} \\ \mathbb{R} \end{array} & \sigma : \begin{cases} q^i = f^i(t) \\ p_i = g_i(t) \end{cases} & \sigma \mapsto \int_{t_0}^{t_1} \sigma^*(\ell) \end{array} \quad (3)$$

$\bar{D}_t \rightarrow$ Hamiltonian dynamics \Leftrightarrow autonomy + the trivial connection on $\pi_{\mathcal{E}}$.

Before the Legendre transformation: L and $\pi_{\mathcal{E}} : TK \times \mathbb{R} \rightarrow \mathbb{R} \Rightarrow \ell$.

Classical Hamiltonian formalism

Canonical equations

$$\dot{p}_i = -\frac{\partial H}{\partial q^i}, \quad \dot{q}^i = \frac{\partial H}{\partial p_i} \quad (1)$$

Configuration manifold $K : q^1, \dots, q^N$.

Infinitely prolonged system (1)

$$\mathcal{E} : t, q^1, \dots, q^N, p_1, \dots, p_N, \quad \bar{D}_t = \partial_t + \frac{\partial H}{\partial p_i} \partial_{q^i} - \frac{\partial H}{\partial q^i} \partial_{p_i} \quad (2)$$

Paths through instantaneous states

$$\begin{array}{ccc} \mathcal{E} = T^*K \times \mathbb{R} & & \ell = p_i dq^i - H dt \in \Lambda^1(\mathcal{E}) \\ \sigma \begin{array}{c} \uparrow \\ \downarrow \pi_{\mathcal{E}} \\ \mathbb{R} \end{array} & \sigma : \begin{cases} q^i = f^i(t) \\ p_i = g_i(t) \end{cases} & \sigma \mapsto \int_{t_0}^{t_1} \sigma^*(\ell) \end{array} \quad (3)$$

$\bar{D}_t \rightarrow$ Hamiltonian dynamics \Leftrightarrow autonomy + the trivial connection on $\pi_{\mathcal{E}}$.

Before the Legendre transformation: L and $\pi_{\mathcal{E}} : TK \times \mathbb{R} \rightarrow \mathbb{R} \Rightarrow \ell$.

Classical Hamiltonian formalism

Canonical equations

$$\dot{p}_i = -\frac{\partial H}{\partial q^i}, \quad \dot{q}^i = \frac{\partial H}{\partial p_i} \quad (1)$$

Configuration manifold $K : q^1, \dots, q^N$.

Infinitely prolonged system (1)

$$\mathcal{E} : t, q^1, \dots, q^N, p_1, \dots, p_N, \quad \bar{D}_t = \partial_t + \frac{\partial H}{\partial p_i} \partial_{q^i} - \frac{\partial H}{\partial q^i} \partial_{p_i} \quad (2)$$

Paths through instantaneous states

$$\begin{array}{ccc} \mathcal{E} = T^*K \times \mathbb{R} & & \ell = p_i dq^i - H dt \in \Lambda^1(\mathcal{E}) \\ \sigma \begin{array}{c} \uparrow \\ \downarrow \pi_{\mathcal{E}} \\ \mathbb{R} \end{array} & \sigma : \begin{cases} q^i = f^i(t) \\ p_i = g_i(t) \end{cases} & \sigma \mapsto \int_{t_0}^{t_1} \sigma^*(\ell) \end{array} \quad (3)$$

$\bar{D}_t \rightarrow$ Hamiltonian dynamics \Leftrightarrow autonomy + the trivial connection on $\pi_{\mathcal{E}}$.

Before the Legendre transformation: L and $\pi_{\mathcal{E}} : TK \times \mathbb{R} \rightarrow \mathbb{R} \Rightarrow \ell$.

How can one describe the Lagrangian formalism in terms of the intrinsic geometry of differential equations?

Main idea

The Hamiltonian formalism is a (non-covariant) version of the Lagrangian one rewritten in terms of the intrinsic geometry of variational equations.

Outline

- If $\mathcal{E} \subset J^\infty(\pi)$ and $\mathbb{E}(L)$ vanishes on \mathcal{E} , then L produces a unique element of a certain cohomology group of \mathcal{E} (internal Lagrangian).
- Internal Lagrangians can be varied in a (non-)covariant manner within classes of paths through properly defined instantaneous states.
- Instantaneous states are encoded by the lifts of involutive hyperplane distributions from the base of a differential equation $\pi_{\mathcal{E}}: \mathcal{E} \rightarrow M$. In some cases, it is reasonable to consider such lifts gauge equations.

An alternative approach: *intrinsic* Lagrangians (M. Grigoriev).

How can one describe the Lagrangian formalism in terms of the intrinsic geometry of differential equations?

Main idea

The Hamiltonian formalism is a (non-covariant) version of the Lagrangian one rewritten in terms of the intrinsic geometry of variational equations.

Outline

- If $\mathcal{E} \subset J^\infty(\pi)$ and $E(L)$ vanishes on \mathcal{E} , then L produces a unique element of a certain cohomology group of \mathcal{E} (internal Lagrangian).
- Internal Lagrangians can be varied in a (non-)covariant manner within classes of paths through properly defined instantaneous states.
- Instantaneous states are encoded by the lifts of involutive hyperplane distributions from the base of a differential equation $\pi_{\mathcal{E}}: \mathcal{E} \rightarrow M$. In some cases, it is reasonable to consider such lifts gauge equations.

An alternative approach: *intrinsic* Lagrangians (M. Grigoriev).

How can one describe the Lagrangian formalism in terms of the intrinsic geometry of differential equations?

Main idea

The Hamiltonian formalism is a (non-covariant) version of the Lagrangian one rewritten in terms of the intrinsic geometry of variational equations.

Outline

- If $\mathcal{E} \subset J^\infty(\pi)$ and $E(L)$ vanishes on \mathcal{E} , then L produces a unique element of a certain cohomology group of \mathcal{E} (internal Lagrangian).
- Internal Lagrangians can be varied in a (non-)covariant manner within classes of paths through properly defined instantaneous states.
- Instantaneous states are encoded by the lifts of involutive hyperplane distributions from the base of a differential equation $\pi_{\mathcal{E}}: \mathcal{E} \rightarrow M$. In some cases, it is reasonable to consider such lifts gauge equations.

An alternative approach: *intrinsic* Lagrangians (M. Grigoriev).

Let $\pi: E^{n+m} \rightarrow M^n$ be a locally trivial smooth vector bundle. Denote by

- x^1, \dots, x^n coordinates in $U \subset M$ (independent variables),
- u^1, \dots, u^m coordinates along the fibers over U (dependent variables).

In local coordinates, the ∞ -jet $[h]_{x_0}^\infty$ of a section $h \in \Gamma(\pi)$ at a point $x_0 \in U$ is given by partial derivatives of its components. Coordinates on $J^\infty(\pi)$:

$$x^i([h]_{x_0}^\infty) = x^i(x_0), \quad u_\alpha^i([h]_{x_0}^\infty) = \frac{\partial^{|\alpha|} h^i}{(\partial x^1)^{\alpha_1} \dots (\partial x^n)^{\alpha_n}}(x_0) \quad (4)$$

The Cartan distribution \mathcal{C} on $J^\infty(\pi)$ is spanned by the total derivatives

$$D_{x^k} = \partial_{x^k} + u_{\alpha+x^k}^i \partial_{u_\alpha^i}, \quad k = 1, \dots, n \quad (5)$$

The Cartan distribution \mathcal{C} is a connection (= horizontal distribution) on the bundle $\pi_\infty: J^\infty(\pi) \rightarrow M$,

$$\pi_\infty: [h]_{x_0}^\infty \mapsto x_0 \quad (6)$$

Let $\pi: E^{n+m} \rightarrow M^n$ be a locally trivial smooth vector bundle. Denote by

- x^1, \dots, x^n coordinates in $U \subset M$ (independent variables),
- u^1, \dots, u^m coordinates along the fibers over U (dependent variables).

In local coordinates, the ∞ -jet $[h]_{x_0}^\infty$ of a section $h \in \Gamma(\pi)$ at a point $x_0 \in U$ is given by partial derivatives of its components. Coordinates on $J^\infty(\pi)$:

$$x^i([h]_{x_0}^\infty) = x^i(x_0), \quad u_\alpha^i([h]_{x_0}^\infty) = \frac{\partial^{|\alpha|} h^i}{(\partial_{x^1})^{\alpha_1} \dots (\partial_{x^n})^{\alpha_n}}(x_0) \quad (4)$$

The Cartan distribution \mathcal{C} on $J^\infty(\pi)$ is spanned by the total derivatives

$$D_{x^k} = \partial_{x^k} + u_{\alpha+x^k}^i \partial_{u_\alpha^i}, \quad k = 1, \dots, n \quad (5)$$

The Cartan distribution \mathcal{C} is a connection (= horizontal distribution) on the bundle $\pi_\infty: J^\infty(\pi) \rightarrow M$,

$$\pi_\infty: [h]_{x_0}^\infty \mapsto x_0 \quad (6)$$

Dual description

$$\text{the ideal } \mathcal{C}\Lambda^*(\pi) \subset \Lambda^*(\pi) \quad (7)$$

In local coordinates, a Cartan differential 1-form $\omega \in \mathcal{C}\Lambda^1(\pi)$ has the form

$$\omega = \omega_i^\alpha \theta_\alpha^i, \quad \theta_\alpha^i = du_\alpha^i - u_{\alpha+x^k}^i dx^k \quad (8)$$

Smooth functions on jets: $\mathcal{F}(\pi)$.

Let η be a locally trivial smooth vector bundle over M , and let F be a section of $\pi_\infty^*(\eta)$. The infinite prolongation of $\{F = 0\} \subset J^\infty(\pi)$ is

$$\mathcal{E} : \quad D_\alpha(F^i) = 0 \quad (9)$$

Cartan distribution: on $J^\infty(\pi) \Rightarrow$ on $\mathcal{E} \Rightarrow$ connection on $\pi_\mathcal{E} = \pi_\infty|_\mathcal{E}$.

Dual description

$$\text{the ideal } \mathcal{C}\Lambda^*(\pi) \subset \Lambda^*(\pi) \quad (7)$$

In local coordinates, a Cartan differential 1-form $\omega \in \mathcal{C}\Lambda^1(\pi)$ has the form

$$\omega = \omega_i^\alpha \theta_\alpha^i, \quad \theta_\alpha^i = du_\alpha^i - u_{\alpha+x^k}^i dx^k \quad (8)$$

Smooth functions on jets: $\mathcal{F}(\pi)$.

Let η be a locally trivial smooth vector bundle over M , and let F be a section of $\pi_\infty^*(\eta)$. The infinite prolongation of $\{F = 0\} \subset J^\infty(\pi)$ is

$$\mathcal{E} : \quad D_\alpha(F^i) = 0 \quad (9)$$

Cartan distribution: on $J^\infty(\pi) \Rightarrow$ on $\mathcal{E} \Rightarrow$ connection on $\pi_{\mathcal{E}} = \pi_\infty|_{\mathcal{E}}$.

- If $\mathcal{E} \subset J^\infty(\pi)$ and $E(L)$ vanishes on \mathcal{E} , then L produces a unique element of a certain cohomology group of \mathcal{E} (internal Lagrangian).

If L is an element of

$$\Lambda_h^n(\pi) = \mathcal{F}(\pi) \cdot \pi_\infty^*(\Lambda^n(M)) \quad (10)$$

such that $E(L)|_{\mathcal{E}} = 0$, there is a Cartan n -form $\omega_L \in \mathcal{C}\Lambda^n(\pi)$ that satisfies

$$d(L + \omega_L) - \frac{\delta L_{1\dots n}}{\delta u^i} \theta_0^i \wedge dx^1 \wedge \dots \wedge dx^n \in \mathcal{C}^2\Lambda^{n+1}(\pi), \quad (11)$$

where $\mathcal{C}^2\Lambda^*(\pi)$ is the square of $\mathcal{C}\Lambda^*(\pi)$.

All restrictions $(L + \omega_L)|_{\mathcal{E}}$ play the role of Poincaré-Cartan forms.

$$\text{all } (L + \omega_L)|_{\mathcal{E}} \Rightarrow \text{the same element of } \frac{\{\ell \in \Lambda^n(\mathcal{E}) : d\ell \in \mathcal{C}^2\Lambda^{n+1}(\mathcal{E})\}}{d(\mathcal{C}\Lambda^{n-1}(\mathcal{E})) + \mathcal{C}^2\Lambda^n(\mathcal{E})} \quad (12)$$

The cohomology class of $L \Rightarrow$ a unique internal Lagrangian, i.e., element of

$$\frac{\{\ell \in \Lambda^n(\mathcal{E}) : d\ell \in \mathcal{C}^2\Lambda^{n+1}(\mathcal{E})\}}{d(\Lambda^{n-1}(\mathcal{E})) + \mathcal{C}^2\Lambda^n(\mathcal{E})} \quad (13)$$

- If $\mathcal{E} \subset J^\infty(\pi)$ and $E(L)$ vanishes on \mathcal{E} , then L produces a unique element of a certain cohomology group of \mathcal{E} (internal Lagrangian).

If L is an element of

$$\Lambda_h^n(\pi) = \mathcal{F}(\pi) \cdot \pi_\infty^*(\Lambda^n(M)) \quad (10)$$

such that $E(L)|_{\mathcal{E}} = 0$, there is a Cartan n -form $\omega_L \in \mathcal{C}\Lambda^n(\pi)$ that satisfies

$$d(L + \omega_L) - \frac{\delta L_{1\dots n}}{\delta u^i} \theta_0^i \wedge dx^1 \wedge \dots \wedge dx^n \in \mathcal{C}^2\Lambda^{n+1}(\pi), \quad (11)$$

where $\mathcal{C}^2\Lambda^*(\pi)$ is the square of $\mathcal{C}\Lambda^*(\pi)$.

All restrictions $(L + \omega_L)|_{\mathcal{E}}$ play the role of Poincaré-Cartan forms.

$$\text{all } (L + \omega_L)|_{\mathcal{E}} \Rightarrow \text{the same element of } \frac{\{\ell \in \Lambda^n(\mathcal{E}) : d\ell \in \mathcal{C}^2\Lambda^{n+1}(\mathcal{E})\}}{d(\mathcal{C}\Lambda^{n-1}(\mathcal{E})) + \mathcal{C}^2\Lambda^n(\mathcal{E})} \quad (12)$$

The cohomology class of $L \Rightarrow$ a unique internal Lagrangian, i.e., element of

$$\frac{\{\ell \in \Lambda^n(\mathcal{E}) : d\ell \in \mathcal{C}^2\Lambda^{n+1}(\mathcal{E})\}}{d(\Lambda^{n-1}(\mathcal{E})) + \mathcal{C}^2\Lambda^n(\mathcal{E})} \quad (13)$$

- If $\mathcal{E} \subset J^\infty(\pi)$ and $E(L)$ vanishes on \mathcal{E} , then L produces a unique element of a certain cohomology group of \mathcal{E} (internal Lagrangian).

If L is an element of

$$\Lambda_h^n(\pi) = \mathcal{F}(\pi) \cdot \pi_\infty^*(\Lambda^n(M)) \quad (10)$$

such that $E(L)|_{\mathcal{E}} = 0$, there is a Cartan n -form $\omega_L \in \mathcal{C}\Lambda^n(\pi)$ that satisfies

$$d(L + \omega_L) - \frac{\delta L_{1\dots n}}{\delta u^i} \theta_0^i \wedge dx^1 \wedge \dots \wedge dx^n \in \mathcal{C}^2\Lambda^{n+1}(\pi), \quad (11)$$

where $\mathcal{C}^2\Lambda^*(\pi)$ is the square of $\mathcal{C}\Lambda^*(\pi)$.

All restrictions $(L + \omega_L)|_{\mathcal{E}}$ play the role of Poincaré-Cartan forms.

$$\text{all } (L + \omega_L)|_{\mathcal{E}} \Rightarrow \text{the same element of } \frac{\{\ell \in \Lambda^n(\mathcal{E}) : d\ell \in \mathcal{C}^2\Lambda^{n+1}(\mathcal{E})\}}{d(\mathcal{C}\Lambda^{n-1}(\mathcal{E})) + \mathcal{C}^2\Lambda^n(\mathcal{E})} \quad (12)$$

The cohomology class of $L \Rightarrow$ a unique internal Lagrangian, i.e., element of

$$\frac{\{\ell \in \Lambda^n(\mathcal{E}) : d\ell \in \mathcal{C}^2\Lambda^{n+1}(\mathcal{E})\}}{d(\Lambda^{n-1}(\mathcal{E})) + \mathcal{C}^2\Lambda^n(\mathcal{E})} \quad (13)$$

For $\varphi \in \Gamma(\pi_\infty^*(\pi))$, we denote by E_φ the evolutionary vector field

$$E_\varphi = D_\alpha(\varphi^i)\partial_{u^i_\alpha} \quad (14)$$

The Noether identity: there is $\omega_L \in \mathcal{C}\Lambda^n(\pi)$ such that $E_\varphi \lrcorner \omega_L \in \Lambda_h^{n-1}(\pi)$,

$$\mathcal{L}_{E_\varphi} L = E_\varphi \lrcorner E(L) + d_h(E_\varphi \lrcorner \omega_L) \quad (15)$$

Internal Lagrangians are cohomology classes of $\Lambda(\mathcal{E})/\mathcal{C}^2\Lambda(\mathcal{E})$

The filtration $\Lambda(\mathcal{E}) \supset \mathcal{C}^2\Lambda(\mathcal{E}) \supset \mathcal{C}^3\Lambda(\mathcal{E}) \supset \mathcal{C}^4\Lambda(\mathcal{E}) \supset \dots$ leads to the spectral sequence for the Lagrangian formalism.

Let us recall that the Vinogradov \mathcal{C} -spectral sequence is produced by

$$\Lambda(\mathcal{E}) \supset \mathcal{C}\Lambda(\mathcal{E}) \supset \mathcal{C}^2\Lambda(\mathcal{E}) \supset \mathcal{C}^3\Lambda(\mathcal{E}) \supset \dots \quad (16)$$

Any embedding of \mathcal{E} to any ∞ -jet manifold ...

Each internal Lagrangian of \mathcal{E} can be (ambiguously, but globally) extended to the jet manifold.

Internal Lagrangians \Rightarrow the Noether theorem.

For $\varphi \in \Gamma(\pi_\infty^*(\pi))$, we denote by E_φ the evolutionary vector field

$$E_\varphi = D_\alpha(\varphi^i)\partial_{u^i_\alpha} \quad (14)$$

The Noether identity: there is $\omega_L \in \mathcal{C}\Lambda^n(\pi)$ such that $E_\varphi \lrcorner \omega_L \in \Lambda_h^{n-1}(\pi)$,

$$\mathcal{L}_{E_\varphi} L = E_\varphi \lrcorner E(L) + d_h(E_\varphi \lrcorner \omega_L) \quad (15)$$

Internal Lagrangians are cohomology classes of $\Lambda(\mathcal{E})/\mathcal{C}^2\Lambda(\mathcal{E})$

The filtration $\Lambda(\mathcal{E}) \supset \mathcal{C}^2\Lambda(\mathcal{E}) \supset \mathcal{C}^3\Lambda(\mathcal{E}) \supset \mathcal{C}^4\Lambda(\mathcal{E}) \supset \dots$ leads to the spectral sequence for the Lagrangian formalism.

Let us recall that the Vinogradov \mathcal{C} -spectral sequence is produced by

$$\Lambda(\mathcal{E}) \supset \mathcal{C}\Lambda(\mathcal{E}) \supset \mathcal{C}^2\Lambda(\mathcal{E}) \supset \mathcal{C}^3\Lambda(\mathcal{E}) \supset \dots \quad (16)$$

Any embedding of \mathcal{E} to any ∞ -jet manifold ...

Each internal Lagrangian of \mathcal{E} can be (ambiguously, but globally) extended to the jet manifold.

Internal Lagrangians \Rightarrow the Noether theorem.

- Instantaneous states are encoded by the lifts of involutive hyperplane distributions from the base of a differential equation $\pi_{\mathcal{E}}: \mathcal{E} \rightarrow M$.

...

Definition

A *spatial distribution* on \mathcal{E} is the lift of an involutive regular distribution of rank $= n - 1$ from the base M^n .

Typical example

$$M = \mathbb{R}^n: x^0 = t, x^1, \dots, x^{n-1} \quad s \text{ on } M: \partial_{x^1}, \dots, \partial_{x^{n-1}} \quad (17)$$

$$\mathcal{C} \text{ on } \mathcal{E}: \bar{D}_t, \bar{D}_{x^1}, \dots, \bar{D}_{x^{n-1}} \quad \mathcal{S} \text{ on } \mathcal{E}: \bar{D}_{x^1}, \dots, \bar{D}_{x^{n-1}} \quad (18)$$

$$\mathcal{C}\Lambda^1(\mathcal{E}): \bar{\theta}_{\alpha}^i = \theta_{\alpha}^i|_{\mathcal{E}} \quad \mathcal{S}\Lambda^1(\mathcal{E}): dt, \bar{\theta}_{\alpha}^i = \theta_{\alpha}^i|_{\mathcal{E}} \quad (19)$$

s defines "simultaneous" \approx reference system (no time though).

$$\Lambda(\mathcal{E}) \supset \mathcal{S}\Lambda(\mathcal{E}) \supset \mathcal{S}^2\Lambda(\mathcal{E}) \supset \mathcal{S}^3\Lambda(\mathcal{E}) \supset \dots \quad (20)$$

$\mathcal{S}_p \subset \mathcal{C}_p \Rightarrow \mathcal{S}^k\Lambda^*(\mathcal{E}) \supset \mathcal{C}^k\Lambda^*(\mathcal{E}) \Rightarrow$ morphisms of the spectral sequences.

- Instantaneous states are encoded by the lifts of involutive hyperplane distributions from the base of a differential equation $\pi_{\mathcal{E}}: \mathcal{E} \rightarrow M$.

...

Definition

A *spatial distribution* on \mathcal{E} is the lift of an involutive regular distribution of rank $= n - 1$ from the base M^n .

Typical example

$$M = \mathbb{R}^n: \quad x^0 = t, x^1, \dots, x^{n-1} \quad s \text{ on } M: \quad \partial_{x^1}, \dots, \partial_{x^{n-1}} \quad (17)$$

$$\mathcal{C} \text{ on } \mathcal{E}: \quad \bar{D}_t, \bar{D}_{x^1}, \dots, \bar{D}_{x^{n-1}} \quad \mathcal{S} \text{ on } \mathcal{E}: \quad \bar{D}_{x^1}, \dots, \bar{D}_{x^{n-1}} \quad (18)$$

$$\mathcal{C}\Lambda^1(\mathcal{E}): \quad \bar{\theta}_{\alpha}^i = \theta_{\alpha}^i|_{\mathcal{E}} \quad \mathcal{S}\Lambda^1(\mathcal{E}): \quad dt, \bar{\theta}_{\alpha}^i = \theta_{\alpha}^i|_{\mathcal{E}} \quad (19)$$

s defines "simultaneous" \approx reference system (no time though).

$$\Lambda(\mathcal{E}) \supset \mathcal{S}\Lambda(\mathcal{E}) \supset \mathcal{S}^2\Lambda(\mathcal{E}) \supset \mathcal{S}^3\Lambda(\mathcal{E}) \supset \dots \quad (20)$$

$\mathcal{S}_p \subset \mathcal{C}_p \Rightarrow \mathcal{S}^k\Lambda^*(\mathcal{E}) \supset \mathcal{C}^k\Lambda^*(\mathcal{E}) \Rightarrow$ morphisms of the spectral sequences.

Paths through instantaneous states

Integral manifolds of spatial distributions are (local) solutions to the respective spatial equations. They represent (local) instantaneous states.

Definition

A section σ of the bundle $\pi_{\mathcal{E}}$ is an \mathcal{S} -section if

$$d\sigma_x(s_x) = \mathcal{S}_{\sigma(x)} \quad \text{for any } x \in M. \quad (21)$$

\mathcal{S} -sections encode paths through instantaneous states. We are going to perturb them.

Definition

A mapping $\gamma: \mathbb{R} \times M \rightarrow \mathcal{E}$ is a *path in \mathcal{S} -sections* if the mappings

$$\gamma(\tau): x \rightarrow \gamma(\tau, x) \quad (22)$$

are \mathcal{S} -sections for all $\tau \in \mathbb{R}$.

Paths through instantaneous states

Integral manifolds of spatial distributions are (local) solutions to the respective spatial equations. They represent (local) instantaneous states.

Definition

A section σ of the bundle $\pi_{\mathcal{E}}$ is an \mathcal{S} -section if

$$d\sigma_x(s_x) = \mathcal{S}_{\sigma(x)} \quad \text{for any } x \in M. \quad (21)$$

\mathcal{S} -sections encode paths through instantaneous states. We are going to perturb them.

Definition

A mapping $\gamma: \mathbb{R} \times M \rightarrow \mathcal{E}$ is a *path in \mathcal{S} -sections* if the mappings

$$\gamma(\tau): x \rightarrow \gamma(\tau, x) \quad (22)$$

are \mathcal{S} -sections for all $\tau \in \mathbb{R}$.

Non-covariant variational principle (6 slides before gauge)

- Internal Lagrangians can be varied in a non-covariant manner within classes of paths through properly defined instantaneous states.

Let ℓ be an internal Lagrangian of \mathcal{E} , $\ell \in \mathcal{L}$.

Definition

An \mathcal{S} -section σ is an \mathcal{S} -stationary point of ℓ if for any compact oriented submanifold $N^n \subset M^n$, the relation

$$\left. \frac{d}{d\tau} \right|_{\tau=0} \int_N \gamma(\tau)^*(\ell) = 0 \quad (23)$$

holds for each path γ in \mathcal{S} -sections such that $\gamma(0) = \sigma$ and all points of the boundary ∂N are fixed.

Let us stress that *the choice of a representative has no impact and all solutions of \mathcal{E} are \mathcal{S} -stationary points of ℓ .*

No time.

Non-covariant variational principle (6 slides before gauge)

- Internal Lagrangians can be varied in a non-covariant manner within classes of paths through properly defined instantaneous states.

Let ℓ be an internal Lagrangian of \mathcal{E} , $\ell \in \mathcal{L}$.

Definition

An \mathcal{S} -section σ is an \mathcal{S} -stationary point of ℓ if for any compact oriented submanifold $N^n \subset M^n$, the relation

$$\left. \frac{d}{d\tau} \right|_{\tau=0} \int_N \gamma(\tau)^*(\ell) = 0 \quad (23)$$

holds for each path γ in \mathcal{S} -sections such that $\gamma(0) = \sigma$ and all points of the boundary ∂N are fixed.

Let us stress that *the choice of a representative has no impact and all solutions of \mathcal{E} are \mathcal{S} -stationary points of ℓ .*

No time.

Is time actually important for the Hamiltonian formalism?

Examples

The Laplace equation

$$u_{yy} = -u_{xx} \quad (24)$$

$$\mathcal{E} : x, y, u, u_x, u_y, u_{xx}, u_{xy}, u_{xxx}, \dots \quad (25)$$

Consider the internal Lagrangian represented by the $\ell = (L + \omega_L)|_{\mathcal{E}}$,

$$L + \omega_L = -\frac{u_x^2 + u_y^2}{2} dx \wedge dy - u_x \theta_0 \wedge dy + u_y \theta_0 \wedge dx. \quad (26)$$

Suppose \mathcal{S} is the lift of the distribution $s = \ker dy$:

$$\mathcal{S} : \bar{D}_x = \partial_x + u_x \partial_u + u_{xx} \partial_{u_x} + u_{xy} \partial_{u_y} + u_{xxx} \partial_{u_{xx}} + u_{xxy} \partial_{u_{xy}} + \dots, \quad (27)$$

Solutions to the \mathcal{S} are given by $y_0 \in \mathbb{R}$ and arbitrary functions $a(x)$, $b(x)$,

$$y = y_0, \quad u = a(x), \quad u_y = b(x), \quad u_x = \partial_x a, \quad u_{xy} = \partial_x b, \quad \dots \quad (28)$$

Any \mathcal{S} -section σ has the form

$$u = f(x, y), \quad u_y = g(x, y), \quad u_x = \partial_x f, \quad u_{xy} = \partial_x g, \quad \dots \quad (29)$$

where $f, g \in C^\infty(\mathbb{R}^2)$ can be chosen arbitrarily.

Examples

The Laplace equation

$$u_{yy} = -u_{xx} \quad (24)$$

$$\mathcal{E} : x, y, u, u_x, u_y, u_{xx}, u_{xy}, u_{xxx}, \dots \quad (25)$$

Consider the internal Lagrangian represented by the $\ell = (L + \omega_L)|_{\mathcal{E}}$,

$$L + \omega_L = -\frac{u_x^2 + u_y^2}{2} dx \wedge dy - u_x \theta_0 \wedge dy + u_y \theta_0 \wedge dx. \quad (26)$$

Suppose \mathcal{S} is the lift of the distribution $s = \ker dy$:

$$\mathcal{S}: \bar{D}_x = \partial_x + u_x \partial_u + u_{xx} \partial_{u_x} + u_{xy} \partial_{u_y} + u_{xxx} \partial_{u_{xx}} + u_{xxy} \partial_{u_{xy}} + \dots, \quad (27)$$

Solutions to the \mathcal{S} are given by $y_0 \in \mathbb{R}$ and arbitrary functions $a(x)$, $b(x)$,

$$y = y_0, \quad u = a(x), \quad u_y = b(x), \quad u_x = \partial_x a, \quad u_{xy} = \partial_x b, \quad \dots \quad (28)$$

Any \mathcal{S} -section σ has the form

$$u = f(x, y), \quad u_y = g(x, y), \quad u_x = \partial_x f, \quad u_{xy} = \partial_x g, \quad \dots \quad (29)$$

where $f, g \in C^\infty(\mathbb{R}^2)$ can be chosen arbitrarily.

$$\sigma^*(\ell) = \left(\frac{g^2 - (\partial_x f)^2}{2} - g \partial_y f \right) dx \wedge dy \quad (30)$$

The Euler-Lagrange equations are

$$\partial_x^2 f + \partial_y g = 0, \quad g = \partial_y f \quad (31)$$

Thus

All \mathcal{S} -stationary points are solutions to Laplace's equation (and vice versa).

This is not a coincidence.

Theorem

Let L be a horizontal n -form, and let \mathcal{E} be the infinite prolongation of the Euler-Lagrange equation $\mathbb{E}(L) = 0$. Suppose \mathcal{S} is the lift of a nowhere characteristic involutive hyperplane distribution. Then an \mathcal{S} -section σ is an \mathcal{S} -stationary point of the corresponding internal Lagrangian if and only if σ is a solution to $\pi_{\mathcal{E}}$.

$$\sigma^*(\ell) = \left(\frac{g^2 - (\partial_x f)^2}{2} - g \partial_y f \right) dx \wedge dy \quad (30)$$

The Euler-Lagrange equations are

$$\partial_x^2 f + \partial_y g = 0, \quad g = \partial_y f \quad (31)$$

Thus

All \mathcal{S} -stationary points are solutions to Laplace's equation (and vice versa).

This is not a coincidence.

Theorem

Let L be a horizontal n -form, and let \mathcal{E} be the infinite prolongation of the Euler-Lagrange equation $\mathbb{E}(L) = 0$. Suppose \mathcal{S} is the lift of a nowhere characteristic involutive hyperplane distribution. Then an \mathcal{S} -section σ is an \mathcal{S} -stationary point of the corresponding internal Lagrangian if and only if σ is a solution to $\pi_{\mathcal{E}}$.

Why gauge?

Let us consider the wave equation

$$u_{xy} = 0 \quad (32)$$

Suppose $s = \ker dy$ (characteristic). Then any \mathcal{S} -section σ has the form

$$u = f(x, y), \quad u_x = \partial_x f, \quad u_y = h_1(y), \quad u_{xx} = \partial_x^2 f, \quad u_{yy} = h_2(y), \quad \dots \quad (33)$$

The functions $f(x, y)$, $h_1(y)$, $h_2(y)$, \dots can be chosen arbitrarily. They satisfy the infinite number of constraints (\approx the spatial equation)

$$\partial_x h_i = 0 \quad i = 1, 2, \quad (34)$$

What about the infinite number of the relations

$$\partial_y f = h_1, \quad \partial_y h_i = h_{i+1} ? \quad (35)$$

But

No internal Lagrangians can give an infinite number of equations.

So, for any ℓ , \mathcal{S} -stationary points \supsetneq solutions. Apparently, instantaneous states here are not just solutions to the \mathcal{S} .

Why gauge?

Let us consider the wave equation

$$u_{xy} = 0 \quad (32)$$

Suppose $s = \ker dy$ (characteristic). Then any \mathcal{S} -section σ has the form

$$u = f(x, y), \quad u_x = \partial_x f, \quad u_y = h_1(y), \quad u_{xx} = \partial_x^2 f, \quad u_{yy} = h_2(y), \quad \dots \quad (33)$$

The functions $f(x, y)$, $h_1(y)$, $h_2(y)$, \dots can be chosen arbitrarily. They satisfy the infinite number of constraints (\approx the spatial equation)

$$\partial_x h_i = 0 \quad i = 1, 2, \quad (34)$$

What about the infinite number of the relations

$$\partial_y f = h_1, \quad \partial_y h_i = h_{i+1} ? \quad (35)$$

But

No internal Lagrangians can give an infinite number of equations.

So, for any ℓ , \mathcal{S} -stationary points \supsetneq solutions. Apparently, instantaneous states here are not just solutions to the \mathcal{S} .

Basic structures on \mathcal{E}

A $\pi_{\mathcal{E}}$ -vertical vector field X on \mathcal{E} is a *symmetry of $\pi_{\mathcal{E}}$* if

$$\mathcal{L}_X \mathcal{C}\Lambda^*(\mathcal{E}) \subset \mathcal{C}\Lambda^*(\mathcal{E}) \quad (36)$$

A *variational p -form* is an element of the vector space

$$E_1^{p, n-1}(\mathcal{E}) = \frac{\{\omega \in \mathcal{C}^p \Lambda^{p+n-1}(\mathcal{E}) : d\omega \in \mathcal{C}^{p+1} \Lambda^{p+n}(\mathcal{E})\}}{d(\mathcal{C}^p \Lambda^{p+n-2}(\mathcal{E})) + \mathcal{C}^{p+1} \Lambda^{p+n-1}(\mathcal{E})} \quad (37)$$

A *presymplectic structure* of \mathcal{E} is an element of $\ker d_1^{2, n-1}$, where

$$d_1^{2, n-1} : E_1^{2, n-1}(\mathcal{E}) \rightarrow E_1^{3, n-1}(\mathcal{E}) \quad (38)$$

An internal Lagrangian of \mathcal{E} generates a unique presymplectic structure.

All symmetries of \mathcal{E} define morphisms of the form

$$X_{\lrcorner} : E_1^{2, n-1}(\mathcal{E}) \rightarrow E_1^{1, n-1}(\mathcal{E}) \quad (39)$$

Gauge symmetries of Lagrangian equations can be defined internally.

Gauge symmetries: $X_{\lrcorner} \omega = 0$, where $\omega \ni d\ell$, while $\ell \Leftarrow$ the Lagrangian.

Basic structures on \mathcal{E}

A $\pi_{\mathcal{E}}$ -vertical vector field X on \mathcal{E} is a *symmetry of $\pi_{\mathcal{E}}$* if

$$\mathcal{L}_X \mathcal{C}\Lambda^*(\mathcal{E}) \subset \mathcal{C}\Lambda^*(\mathcal{E}) \quad (36)$$

A *variational p -form* is an element of the vector space

$$E_1^{p, n-1}(\mathcal{E}) = \frac{\{\omega \in \mathcal{C}^p \Lambda^{p+n-1}(\mathcal{E}) : d\omega \in \mathcal{C}^{p+1} \Lambda^{p+n}(\mathcal{E})\}}{d(\mathcal{C}^p \Lambda^{p+n-2}(\mathcal{E})) + \mathcal{C}^{p+1} \Lambda^{p+n-1}(\mathcal{E})} \quad (37)$$

A *presymplectic structure* of \mathcal{E} is an element of $\ker d_1^{2, n-1}$, where

$$d_1^{2, n-1} : E_1^{2, n-1}(\mathcal{E}) \rightarrow E_1^{3, n-1}(\mathcal{E}) \quad (38)$$

An internal Lagrangian of \mathcal{E} generates a unique presymplectic structure.

All symmetries of \mathcal{E} define morphisms of the form

$$X_{\lrcorner} : E_1^{2, n-1}(\mathcal{E}) \rightarrow E_1^{1, n-1}(\mathcal{E}) \quad (39)$$

Gauge symmetries of Lagrangian equations can be defined internally.

Gauge symmetries: $X_{\lrcorner} \omega = 0$, where $\omega \ni d\ell$, while $\ell \Leftarrow$ the Lagrangian.

...

- In some cases, it is reasonable to consider such lifts gauge equations.

A $\pi_{\mathcal{E}}$ -vertical vector field X on \mathcal{E} is an \mathcal{S} -symmetry if

$$\mathcal{L}_X \mathcal{S}\Lambda^*(\mathcal{E}) \subset \mathcal{S}\Lambda^*(\mathcal{E}) \quad (40)$$

$\mathcal{S}_p \subset \mathcal{C}_p \Rightarrow \mathcal{S}^k \Lambda^*(\mathcal{E}) \supset \mathcal{C}^k \Lambda^*(\mathcal{E}) \Rightarrow$ morphisms of the spectral sequences.

The morphisms are given by $\mathcal{C} \rightarrow \mathcal{S}$. For example, a variational p -form

$$\omega + d(\mathcal{C}^p \Lambda^{p+n-2}(\mathcal{E})) + \mathcal{C}^{p+1} \Lambda^{p+n-1}(\mathcal{E}) \quad (41)$$

gives rise to the \mathcal{S} -variational p -form

$$\omega + d(\mathcal{S}^p \Lambda^{p+n-2}(\mathcal{E})) + \mathcal{S}^{p+1} \Lambda^{p+n-1}(\mathcal{E}), \quad (42)$$

which is not a variational p -form for the $(\mathcal{E}, \mathcal{S})$. (Top horizontal degree)

Lagrangian $L \Rightarrow$ internal Lagrangian $\ell \Rightarrow$ presymplectic structure $\omega \Rightarrow$
 \mathcal{S} -presymplectic structure $\omega_{\mathcal{S}} \Rightarrow (\ell, \mathcal{S})$ -gauge symmetries: $X \lrcorner \omega_{\mathcal{S}} = 0$.

...

- In some cases, it is reasonable to consider such lifts gauge equations.

A $\pi_{\mathcal{E}}$ -vertical vector field X on \mathcal{E} is an \mathcal{S} -symmetry if

$$\mathcal{L}_X \mathcal{S}\Lambda^*(\mathcal{E}) \subset \mathcal{S}\Lambda^*(\mathcal{E}) \quad (40)$$

$\mathcal{S}_p \subset \mathcal{C}_p \Rightarrow \mathcal{S}^k \Lambda^*(\mathcal{E}) \supset \mathcal{C}^k \Lambda^*(\mathcal{E}) \Rightarrow$ morphisms of the spectral sequences.

The morphisms are given by $\mathcal{C} \rightarrow \mathcal{S}$. For example, a variational p -form

$$\omega + d(\mathcal{C}^p \Lambda^{p+n-2}(\mathcal{E})) + \mathcal{C}^{p+1} \Lambda^{p+n-1}(\mathcal{E}) \quad (41)$$

gives rise to the \mathcal{S} -variational p -form

$$\omega + d(\mathcal{S}^p \Lambda^{p+n-2}(\mathcal{E})) + \mathcal{S}^{p+1} \Lambda^{p+n-1}(\mathcal{E}), \quad (42)$$

which is not a variational p -form for the $(\mathcal{E}, \mathcal{S})$. (Top horizontal degree)

Lagrangian $L \Rightarrow$ internal Lagrangian $\ell \Rightarrow$ presymplectic structure $\omega \Rightarrow$
 \mathcal{S} -presymplectic structure $\omega_{\mathcal{S}} \Rightarrow (\ell, \mathcal{S})$ -gauge symmetries: $X \lrcorner \omega_{\mathcal{S}} = 0$.

Examples

The Laplace equation again

$$u_{yy} = -u_{xx} \quad s = \ker dy \quad \mathcal{S}: \bar{D}_x \quad (43)$$

The presymplectic structure is represented by the form $d\ell$,

$$d\ell = -\bar{\theta}_x \wedge \bar{\theta}_0 \wedge dy + \bar{\theta}_y \wedge \bar{\theta}_0 \wedge dx. \quad (44)$$

$$\bar{\theta}_0 = du - u_x dx - u_y dy, \quad \bar{\theta}_x = du_x - u_{xx} dx - u_{xy} dy,$$

$$\bar{\theta}_y = du_y - u_{xy} dx + u_{xx} dy. \quad \text{Since } -\bar{\theta}_x \wedge \bar{\theta}_0 \wedge dy \in \mathcal{S}^3 \Lambda^3(\mathcal{E}), \text{ the form}$$

$$\omega = \bar{\theta}_y \wedge \bar{\theta}_0 \wedge dx \quad (45)$$

represents the same \mathcal{S} -presymplectic structure as $d\ell$.

Any \mathcal{S} -symmetry has the form

$$X = \varphi \partial_u + \chi \partial_{u_y} + \bar{D}_x(\varphi) \partial_{u_x} + \bar{D}_x(\chi) \partial_{u_{xy}} + \dots \quad (46)$$

φ and χ are arbitrary functions on \mathcal{E} .

Examples

The Laplace equation again

$$u_{yy} = -u_{xx} \quad s = \ker dy \quad \mathcal{S}: \bar{D}_x \quad (43)$$

The presymplectic structure is represented by the form $d\ell$,

$$d\ell = -\bar{\theta}_x \wedge \bar{\theta}_0 \wedge dy + \bar{\theta}_y \wedge \bar{\theta}_0 \wedge dx. \quad (44)$$

$$\bar{\theta}_0 = du - u_x dx - u_y dy, \quad \bar{\theta}_x = du_x - u_{xx} dx - u_{xy} dy,$$

$$\bar{\theta}_y = du_y - u_{xy} dx + u_{xx} dy. \quad \text{Since } -\bar{\theta}_x \wedge \bar{\theta}_0 \wedge dy \in \mathcal{S}^3 \Lambda^3(\mathcal{E}), \text{ the form}$$

$$\omega = \bar{\theta}_y \wedge \bar{\theta}_0 \wedge dx \quad (45)$$

represents the same \mathcal{S} -presymplectic structure as $d\ell$.

Any \mathcal{S} -symmetry has the form

$$X = \varphi \partial_u + \chi \partial_{u_y} + \bar{D}_x(\varphi) \partial_{u_x} + \bar{D}_x(\chi) \partial_{u_{xy}} + \dots \quad (46)$$

φ and χ are arbitrary functions on \mathcal{E} .

No (ℓ, \mathcal{S}) -gauge symmetries for the Laplace equation

$$X \lrcorner \omega = \chi \bar{\theta}_0 \wedge dx - \varphi \bar{\theta}_y \wedge dx \quad (47)$$

Denote u_y by v . The spatial equation: the infinite prolongation of the ODE

$$y_x = 0, \quad 0 = 0, \quad 0 = 0 \quad \text{for } (y, u, v) \quad (48)$$

Any \mathcal{S} -variational 1-form is represented by

$$a dy \wedge dx + b \bar{\theta}_0 \wedge dx + c \bar{\theta}_y \wedge dx \quad (49)$$

Linearization of an equation $F = 0$: $E_\varphi(F) = I_F(\varphi) \Rightarrow I_\mathcal{E} = I_F|_\mathcal{E}$. Then

$$I_\mathcal{S} = \begin{pmatrix} \bar{D}_x & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad I_\mathcal{S}^* = \begin{pmatrix} -\bar{D}_x & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad (50)$$

\mathcal{S} -variational 1-form (49) is trivial iff $(a; b; c)^T \in \text{im } I_\mathcal{S}^*$ ($\Leftarrow k$ -line theorem).

Triviality $\Rightarrow b = c = 0$. Then (47) defines the trivial \mathcal{S} -variational 1-form iff $\varphi = \chi = 0$. No (ℓ, \mathcal{S}) -gauge symmetries.

No (ℓ, \mathcal{S}) -gauge symmetries for the Laplace equation

$$X \lrcorner \omega = \chi \bar{\theta}_0 \wedge dx - \varphi \bar{\theta}_y \wedge dx \quad (47)$$

Denote u_y by v . The spatial equation: the infinite prolongation of the ODE

$$y_x = 0, \quad 0 = 0, \quad 0 = 0 \quad \text{for } (y, u, v) \quad (48)$$

Any \mathcal{S} -variational 1-form is represented by

$$a dy \wedge dx + b \bar{\theta}_0 \wedge dx + c \bar{\theta}_y \wedge dx \quad (49)$$

Linearization of an equation $F = 0$: $E_\varphi(F) = l_F(\varphi) \Rightarrow l_{\mathcal{E}} = l_F|_{\mathcal{E}}$. Then

$$l_{\mathcal{S}} = \begin{pmatrix} \bar{D}_x & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad l_{\mathcal{S}}^* = \begin{pmatrix} -\bar{D}_x & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad (50)$$

\mathcal{S} -variational 1-form (49) is trivial iff $(a; b; c)^T \in \text{im } l_{\mathcal{S}}^*$ (\Leftarrow k -line theorem).

Triviality $\Rightarrow b = c = 0$. Then (47) defines the trivial \mathcal{S} -variational 1-form iff $\varphi = \chi = 0$. No (ℓ, \mathcal{S}) -gauge symmetries.

The wave equation again

$$u_{xy} = 0, \quad \mathcal{S}: \bar{D}_x \quad (51)$$

$$\ell = -\frac{u_x u_y}{2} dx \wedge dy - \frac{u_y}{2} \bar{\theta}_0 \wedge dy - \frac{u_x}{2} dx \wedge \bar{\theta}_0, \quad \bar{\theta}_0 = du - u_x dx - u_y dy. \quad (52)$$

Any vector field of the form

$$Y_\varphi = \varphi_0 \partial_u + \varphi_1 \partial_{u_y} + \varphi_2 \partial_{u_{yy}} + \varphi_3 \partial_{u_{yyy}} + \dots \quad (53)$$

is an (ℓ, \mathcal{S}) -gauge symmetry, where $\varphi_0, \varphi_1, \dots$ are arbitrary functions of y, u_y, u_{yy}, \dots . Indeed, $d\ell$ represents the same \mathcal{S} -presymplectic structure as

$$\omega = \frac{1}{2} \bar{\theta}_x \wedge \bar{\theta}_0 \wedge dx, \quad (54)$$

$$\bar{\theta}_0 = du - u_x dx - u_y dy, \quad \bar{\theta}_x = du_x - u_{xx} dx.$$

$$Y_\varphi \lrcorner \omega = \frac{\varphi_0}{2} dx \wedge \bar{\theta}_x \in d\left(\frac{\varphi_0}{2} \bar{\theta}_0\right) + \mathcal{S}^2 \Lambda^2(\mathcal{E}) \quad (55)$$

Let us note that if $\varphi_1 = \bar{D}_y(\varphi_0)$, $\varphi_2 = \bar{D}_y^2(\varphi_0)$, \dots , then Y_φ is a symmetry of the wave equation.

The wave equation again

$$u_{xy} = 0, \quad \mathcal{S}: \bar{D}_x \quad (51)$$

$$\ell = -\frac{u_x u_y}{2} dx \wedge dy - \frac{u_y}{2} \bar{\theta}_0 \wedge dy - \frac{u_x}{2} dx \wedge \bar{\theta}_0, \quad \bar{\theta}_0 = du - u_x dx - u_y dy. \quad (52)$$

Any vector field of the form

$$Y_\varphi = \varphi_0 \partial_u + \varphi_1 \partial_{u_y} + \varphi_2 \partial_{u_{yy}} + \varphi_3 \partial_{u_{yyy}} + \dots \quad (53)$$

is an (ℓ, \mathcal{S}) -gauge symmetry, where $\varphi_0, \varphi_1, \dots$ are arbitrary functions of y, u_y, u_{yy}, \dots . Indeed, $d\ell$ represents the same \mathcal{S} -presymplectic structure as

$$\omega = \frac{1}{2} \bar{\theta}_x \wedge \bar{\theta}_0 \wedge dx, \quad (54)$$

$$\bar{\theta}_0 = du - u_x dx - u_y dy, \quad \bar{\theta}_x = du_x - u_{xx} dx.$$

$$Y_\varphi \lrcorner \omega = \frac{\varphi_0}{2} dx \wedge \bar{\theta}_x \in d\left(\frac{\varphi_0}{2} \bar{\theta}_0\right) + \mathcal{S}^2 \Lambda^2(\mathcal{E}) \quad (55)$$

Let us note that if $\varphi_1 = \bar{D}_y(\varphi_0)$, $\varphi_2 = \bar{D}_y^2(\varphi_0)$, \dots , then Y_φ is a symmetry of the wave equation.

Spatial-gauge Cauchy problems on the characteristics

An \mathcal{S} -section σ

$$u = f(x, y), \quad u_x = \partial_x f, \quad u_y = h_1(y), \quad u_{xx} = \partial_x^2 f, \quad u_{yy} = h_2(y), \quad \dots \quad (56)$$

is an \mathcal{S} -stationary point of ℓ if and only if

$$\partial_x \partial_y f = 0 \quad (57)$$

Any \mathcal{S} -stationary point σ can be transformed into a solution of the wave equation using the transformation Φ^1 , where Φ^T denotes the flow of the (ℓ, \mathcal{S}) -gauge symmetry $Y_\varphi = \varphi_0 \partial_u + \varphi_1 \partial_{u_y} + \varphi_2 \partial_{u_{yy}} + \varphi_3 \partial_{u_{yyy}} + \dots$ for

$$\varphi_0 = 0, \quad \varphi_1 = -h_1 + \partial_y f, \quad \varphi_2 = -h_2 + \partial_y^2 f, \quad \varphi_3 = -h_3 + \partial_y^3 f, \quad \dots \quad (58)$$

Solutions to the spatial equation have the form

$$y = y_0, \quad u = a(x), \quad u_x = \partial_x a, \quad u_y = c_1, \quad u_{xx} = \partial_x^2 a, \quad u_{yy} = c_2, \quad \dots \quad (59)$$

Initial data (initial state): $a(x)$ modulo $+const_0$, c_1 modulo $+const_1$, \dots

The solution is a unique (ℓ, \mathcal{S}) -gauge equivalence class of \mathcal{S} -sections.

Spatial-gauge Cauchy problems on the characteristics

An \mathcal{S} -section σ

$$u = f(x, y), \quad u_x = \partial_x f, \quad u_y = h_1(y), \quad u_{xx} = \partial_x^2 f, \quad u_{yy} = h_2(y), \quad \dots \quad (56)$$

is an \mathcal{S} -stationary point of ℓ if and only if

$$\partial_x \partial_y f = 0 \quad (57)$$

Any \mathcal{S} -stationary point σ can be transformed into a solution of the wave equation using the transformation Φ^1 , where Φ^T denotes the flow of the (ℓ, \mathcal{S}) -gauge symmetry $Y_\varphi = \varphi_0 \partial_u + \varphi_1 \partial_{u_y} + \varphi_2 \partial_{u_{yy}} + \varphi_3 \partial_{u_{yyy}} + \dots$ for

$$\varphi_0 = 0, \quad \varphi_1 = -h_1 + \partial_y f, \quad \varphi_2 = -h_2 + \partial_y^2 f, \quad \varphi_3 = -h_3 + \partial_y^3 f, \quad \dots \quad (58)$$

Solutions to the spatial equation have the form

$$y = y_0, \quad u = a(x), \quad u_x = \partial_x a, \quad u_y = c_1, \quad u_{xx} = \partial_x^2 a, \quad u_{yy} = c_2, \quad \dots \quad (59)$$

Initial data (initial state): $a(x)$ modulo $+const_0$, c_1 modulo $+const_1$, \dots

The solution is a unique (ℓ, \mathcal{S}) -gauge equivalence class of \mathcal{S} -sections.

Non-covariant action and spatial-gauge equivalence

If an (ℓ, \mathcal{S}) -gauge symmetry generates a global flow

the corresponding transformations play the role of spatial-gauge ones. For a spatial equation \mathcal{S} , the set of all such transformations generates a group (group operation is composition), which we call (ℓ, \mathcal{S}) -gauge group.

If an equation \mathcal{E} is embedded into a certain $J^\infty(\pi)$ and L is a horizontal n -form such that $\mathbb{E}(L)|_{\mathcal{E}} = 0$, then L (but not its cohomology class) gives rise to a unique \mathcal{S} -variational 1-form of \mathcal{E} .

If ξ is an \mathcal{S} -variational 1-form and for each $x \in \partial M$, $s_x = T_x \partial M$, then the action

$$\sigma \mapsto \int_M \sigma^*(\xi) \tag{60}$$

is well-defined on \mathcal{S} -sections, provided M is compact and oriented.

Non-covariant action and spatial-gauge equivalence

If an (ℓ, \mathcal{S}) -gauge symmetry generates a global flow

the corresponding transformations play the role of spatial-gauge ones. For a spatial equation \mathcal{S} , the set of all such transformations generates a group (group operation is composition), which we call (ℓ, \mathcal{S}) -gauge group.

If an equation \mathcal{E} is embedded into a certain $J^\infty(\pi)$ and L is a horizontal n -form such that $\mathbb{E}(L)|_{\mathcal{E}} = 0$, then L (but not its cohomology class) gives rise to a unique \mathcal{S} -variational 1-form of \mathcal{E} .

If ξ is an \mathcal{S} -variational 1-form and for each $x \in \partial M$, $s_x = T_x \partial M$, then the action

$$\sigma \mapsto \int_M \sigma^*(\xi) \tag{60}$$

is well-defined on \mathcal{S} -sections, provided M is compact and oriented.

Maxwell's equations

Let \mathcal{E} be the infinite prolongation of the Maxwell equations

$$\partial_\mu F^{\mu\nu} = 0. \quad (61)$$

Here $M = \mathbb{R}^n$; $F^{\mu\nu}$ denotes $\partial^\mu A^\nu - \partial^\nu A^\mu$; the metric is $(+, -, \dots, -)$; $x^0 = t, x^1, \dots, x^{n-1}$; $\mu, \nu = 0, \dots, n-1$; $n > 2$.

We also use the spatial indices $i, j, k = 1, \dots, n-1$.

$$L = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} d^n x, \quad d^n x = dx^0 \wedge \dots \wedge dx^{n-1} \quad (62)$$

$$L + \omega_L = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} d^n x - F_{\mu\nu} \theta^\nu \wedge (\partial^\mu \lrcorner d^n x), \quad \theta^\nu = dA^\nu - \partial_\mu A^\nu dx^\mu$$

$\ell = (L + \omega_L)|_{\mathcal{E}}$. Put $s = \ker dt$. The \mathcal{S} -presymplectic structure:

$$\omega = -\bar{\theta}_{0i} \wedge \bar{\theta}^i \wedge (\partial^0 \lrcorner d^n x), \quad (63)$$

where $\bar{\theta}_{0i} = (dF_{0i} - \partial_\mu F_{0i} dx^\mu)|_{\mathcal{E}}$, and $\bar{\theta}^i = \theta^i|_{\mathcal{E}}$.

Maxwell's equations

Let \mathcal{E} be the infinite prolongation of the Maxwell equations

$$\partial_\mu F^{\mu\nu} = 0. \quad (61)$$

Here $M = \mathbb{R}^n$; $F^{\mu\nu}$ denotes $\partial^\mu A^\nu - \partial^\nu A^\mu$; the metric is $(+, -, \dots, -)$; $x^0 = t, x^1, \dots, x^{n-1}$; $\mu, \nu = 0, \dots, n-1$; $n > 2$.

We also use the spatial indices $i, j, k = 1, \dots, n-1$.

$$L = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} d^n x, \quad d^n x = dx^0 \wedge \dots \wedge dx^{n-1} \quad (62)$$

$$L + \omega_L = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} d^n x - F_{\mu\nu} \theta^\nu \wedge (\partial^\mu \lrcorner d^n x), \quad \theta^\nu = dA^\nu - \partial_\mu A^\nu dx^\mu$$

$\ell = (L + \omega_L)|_{\mathcal{E}}$. Put $s = \ker dt$. The \mathcal{S} -presymplectic structure:

$$\omega = -\bar{\theta}_{0i} \wedge \bar{\theta}^i \wedge (\partial^0 \lrcorner d^n x), \quad (63)$$

where $\bar{\theta}_{0i} = (dF_{0i} - \partial_\mu F_{0i} dx^\mu)|_{\mathcal{E}}$, and $\bar{\theta}^i = \theta^i|_{\mathcal{E}}$.

Maxwell's equations

Let \mathcal{E} be the infinite prolongation of the Maxwell equations

$$\partial_\mu F^{\mu\nu} = 0. \quad (61)$$

Here $M = \mathbb{R}^n$; $F^{\mu\nu}$ denotes $\partial^\mu A^\nu - \partial^\nu A^\mu$; the metric is $(+, -, \dots, -)$; $x^0 = t, x^1, \dots, x^{n-1}$; $\mu, \nu = 0, \dots, n-1$; $n > 2$.

We also use the spatial indices $i, j, k = 1, \dots, n-1$.

$$L = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} d^n x, \quad d^n x = dx^0 \wedge \dots \wedge dx^{n-1} \quad (62)$$

$$L + \omega_L = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} d^n x - F_{\mu\nu} \theta^\nu \wedge (\partial^\mu \lrcorner d^n x), \quad \theta^\nu = dA^\nu - \partial_\mu A^\nu dx^\mu$$

$\ell = (L + \omega_L)|_{\mathcal{E}}$. Put $s = \ker dt$. The \mathcal{S} -presymplectic structure:

$$\omega = -\bar{\theta}_{0i} \wedge \bar{\theta}^i \wedge (\partial^0 \lrcorner d^n x), \quad (63)$$

where $\bar{\theta}_{0i} = (dF_{0i} - \partial_\mu F_{0i} dx^\mu)|_{\mathcal{E}}$, and $\bar{\theta}^i = \theta^i|_{\mathcal{E}}$.

Coordinates on \mathcal{E} : x^μ , and

A^ν , F^{0i} , $\partial_0 A^0$, $\partial_0^2 A^0$, \dots and all their spatial derivatives, except for, say, $\partial_1 F^{01}$ and its spatial derivatives.

Infinitely many degrees of spatial freedom of the form $\partial_0^p A^0$.

Any \mathcal{S} -symmetry has the form

$$X_{(\chi, \eta, \varphi)} = \chi^i \partial_{A^i} + \eta^i \partial_{F^{0i}} + \varphi^0 \partial_{A^0} + \varphi^1 \partial_{\partial_0 A^0} + \varphi^2 \partial_{\partial_0^2 A^0} + \dots \quad (64)$$

$\chi^i, \varphi^0, \varphi^1, \dots \in \mathcal{F}(\mathcal{E})$ can be chosen arbitrarily, while $\eta^i \in \mathcal{F}(\mathcal{E})$ satisfy

$$\bar{D}_i(\eta^i) = 0, \quad \bar{D}_i = D_i|_{\mathcal{E}}. \quad (65)$$

$$X_{(\chi, \eta, \varphi)} \lrcorner \omega = -\eta^i \bar{\theta}_i \wedge (\partial^0 \lrcorner d^n x) + \chi^i \bar{\theta}_{0i} \wedge (\partial^0 \lrcorner d^n x). \quad (66)$$

This differential form represents the trivial \mathcal{S} -variational 1-form iff $\eta^i = 0$ and there exists a function $\epsilon \in \mathcal{F}(\mathcal{E})$ such that

$$\chi^i = \bar{D}^i(\epsilon) \quad i = 1, \dots, n-1. \quad (67)$$

(ℓ, \mathcal{S}) -gauge symmetries: $X_{(\chi, \eta, \varphi)}$ for $\eta^i = 0$, $\chi^i = \bar{D}^i(\epsilon)$.

Coordinates on \mathcal{E} : x^μ , and

A^ν , F^{0i} , $\partial_0 A^0$, $\partial_0^2 A^0$, ... and all their spatial derivatives, except for, say, $\partial_1 F^{01}$ and its spatial derivatives.

Infinitely many degrees of spatial freedom of the form $\partial_0^p A^0$.

Any \mathcal{S} -symmetry has the form

$$X_{(\chi, \eta, \varphi)} = \chi^i \partial_{A^i} + \eta^i \partial_{F^{0i}} + \varphi^0 \partial_{A^0} + \varphi^1 \partial_{\partial_0 A^0} + \varphi^2 \partial_{\partial_0^2 A^0} + \dots \quad (64)$$

$\chi^i, \varphi^0, \varphi^1, \dots \in \mathcal{F}(\mathcal{E})$ can be chosen arbitrarily, while $\eta^i \in \mathcal{F}(\mathcal{E})$ satisfy

$$\bar{D}_i(\eta^i) = 0, \quad \bar{D}_i = D_i|_{\mathcal{E}}. \quad (65)$$

$$X_{(\chi, \eta, \varphi)} \lrcorner \omega = -\eta^i \bar{\theta}_i \wedge (\partial^0 \lrcorner d^n x) + \chi^i \bar{\theta}_{0i} \wedge (\partial^0 \lrcorner d^n x). \quad (66)$$

This differential form represents the trivial \mathcal{S} -variational 1-form iff $\eta^i = 0$ and there exists a function $\epsilon \in \mathcal{F}(\mathcal{E})$ such that

$$\chi^i = \bar{D}^i(\epsilon) \quad i = 1, \dots, n-1. \quad (67)$$

(ℓ, \mathcal{S}) -gauge symmetries: $X_{(\chi, \eta, \varphi)}$ for $\eta^i = 0$, $\chi^i = \bar{D}^i(\epsilon)$.

(ℓ, \mathcal{S}) -gauge symmetries

$$\bar{D}^i(\epsilon)\partial_{A^i} + \varphi^0\partial_{A^0} + \varphi^1\partial_{\partial_0 A^0} + \varphi^2\partial_{\partial_0^2 A^0} + \dots$$

for arbitrary $\epsilon, \varphi^0, \varphi^1, \dots \in \mathcal{F}(\mathcal{E})$.

The degrees of spatial freedom $\partial_0^p A^0$ are spatial-gauge, while

gauge symmetries of the Maxwell equations ($\varphi^0 = \bar{D}^0(\epsilon)$, $\varphi^1 = \bar{D}^0(\varphi^0)$, \dots) can not get rid of the spatial-gauge freedom degrees.

Any \mathcal{S} -section σ has the form

$$\begin{aligned} \sigma: \quad A^\nu &= f^\nu, \quad F^{0i} = g^i, \quad \partial_0 A^0 = h^1, \quad \partial_0^2 A^0 = h^2, \quad \dots \\ \partial_i A^\nu &= \partial_i f^\nu, \quad \dots \end{aligned} \quad (68)$$

$f^\nu, h^1, h^2, \dots \in C^\infty(\mathbb{R}^n)$ can be chosen arbitrarily, while $g^i \in C^\infty(\mathbb{R}^n)$ must satisfy one constraint (Gauss's law):

$$\partial_i g^i = 0 \quad (69)$$

Here $\partial_\mu f^\nu, \partial_\mu g^i, \dots$ denote the partial derivatives $\partial_{x^\mu} f^\nu, \partial_{x^\mu} g^i, \dots$

(ℓ, \mathcal{S}) -gauge symmetries

$$\bar{D}^i(\epsilon)\partial_{A^i} + \varphi^0\partial_{A^0} + \varphi^1\partial_{\partial_0 A^0} + \varphi^2\partial_{\partial_0^2 A^0} + \dots$$

for arbitrary $\epsilon, \varphi^0, \varphi^1, \dots \in \mathcal{F}(\mathcal{E})$.

The degrees of spatial freedom $\partial_0^p A^0$ are spatial-gauge, while

gauge symmetries of the Maxwell equations ($\varphi^0 = \bar{D}^0(\epsilon)$, $\varphi^1 = \bar{D}^0(\varphi^0)$, ...) can not get rid of the spatial-gauge freedom degrees.

Any \mathcal{S} -section σ has the form

$$\sigma: \quad \begin{aligned} A^\nu &= f^\nu, & F^{0i} &= g^i, & \partial_0 A^0 &= h^1, & \partial_0^2 A^0 &= h^2, & \dots \\ \partial_i A^\nu &= \partial_i f^\nu, & \dots & & & & & & \end{aligned} \quad (68)$$

$f^\nu, h^1, h^2, \dots \in C^\infty(\mathbb{R}^n)$ can be chosen arbitrarily, while $g^i \in C^\infty(\mathbb{R}^n)$ must satisfy one constraint (Gauss's law):

$$\partial_i g^i = 0 \quad (69)$$

Here $\partial_\mu f^\nu, \partial_\mu g^i, \dots$ denote the partial derivatives $\partial_{x^\mu} f^\nu, \partial_{x^\mu} g^i, \dots$

Any (ℓ, \mathcal{S}) -gauge symmetry: $\bar{D}^i(\epsilon)\partial_{A^i} + \varphi^0\partial_{A^0} + \varphi^1\partial_{\partial_0 A^0} + \varphi^2\partial_{\partial_0^2 A^0} + \dots$

Any \mathcal{S} -section: $A^\nu = f^\nu, \quad F^{0i} = g^i, \quad \partial_0 A^0 = h^1, \quad \partial_0^2 A^0 = h^2, \quad \dots$
 $\partial_i g^i = 0$

Any (ℓ, \mathcal{S}) -gauge equivalence class of \mathcal{S} -sections has the form

$$f^i \text{ modulo } + \partial^i \epsilon, \quad g^i, \quad (70)$$

$$f^0 \text{ modulo } + \text{anything}, \quad h^1 \text{ modulo } + \text{anything}, \quad \dots \quad (71)$$

Here $\epsilon \in C^\infty(\mathbb{R}^n)$.

$n = 4$:

(ℓ, \mathcal{S}) -gauge equivalence classes of solutions to the spatial equation \Leftrightarrow tuples $(t_0; E_0; B_0)$, where E_0 and B_0 are instantaneous electric and magnetic field (at $t = t_0$) respectively.

Any (ℓ, \mathcal{S}) -gauge symmetry: $\bar{D}^i(\epsilon)\partial_{A^i} + \varphi^0\partial_{A^0} + \varphi^1\partial_{\partial_0 A^0} + \varphi^2\partial_{\partial_0^2 A^0} + \dots$

Any \mathcal{S} -section: $A^\nu = f^\nu, \quad F^{0i} = g^i, \quad \partial_0 A^0 = h^1, \quad \partial_0^2 A^0 = h^2, \quad \dots$
 $\partial_i g^i = 0$

Any (ℓ, \mathcal{S}) -gauge equivalence class of \mathcal{S} -sections has the form

$$f^i \text{ modulo } + \partial^i \epsilon, \quad g^i, \quad (70)$$

$$f^0 \text{ modulo } + \text{anything}, \quad h^1 \text{ modulo } + \text{anything}, \quad \dots \quad (71)$$

Here $\epsilon \in C^\infty(\mathbb{R}^n)$.

$n = 4$:

(ℓ, \mathcal{S}) -gauge equivalence classes of solutions to the spatial equation \Leftrightarrow tuples $(t_0; E_0; B_0)$, where E_0 and B_0 are instantaneous electric and magnetic field (at $t = t_0$) respectively.

$$\int \sigma^*(\ell) = \int \left(\frac{1}{2} g^i g_i - \frac{1}{4} (\partial_i f_j - \partial_j f_i) (\partial^i f^j - \partial^j f^i) - g_i (\partial^0 f^i - \partial^i f^0) \right) d^n x .$$

Resolve the constraint $\partial_i g^i = 0$:

$$g^i = \partial_j r^{ij}, \quad r^{ij} \in C^\infty(\mathbb{R}^n) \quad r^{ij} = -r^{ji} \quad (72)$$

$$\begin{aligned} \int \sigma^*(\ell) &= \quad (73) \\ &= \int \left(\frac{1}{2} \partial_k r^{ik} \partial^j r_{ij} - \frac{1}{4} (\partial_i f_j - \partial_j f_i) (\partial^i f^j - \partial^j f^i) - \partial^j r_{ij} (\partial^0 f^i - \partial^i f^0) \right) d^n x . \end{aligned}$$

For any compact oriented submanifold $N^n \subset \mathbb{R}^n$

we can take as variations $\delta f^\nu, \delta r^{ij}, \delta h^1, \delta h^2, \dots$ arbitrary functions on \mathbb{R}^n that vanish with all their derivatives on ∂N and such that $\delta r^{ij} = -\delta r^{ji}$.

$$\int \sigma^*(\ell) = \int \left(\frac{1}{2} g^i g_i - \frac{1}{4} (\partial_i f_j - \partial_j f_i) (\partial^i f^j - \partial^j f^i) - g_i (\partial^0 f^i - \partial^i f^0) \right) d^n x.$$

Resolve the constraint $\partial_i g^i = 0$:

$$g^i = \partial_j r^{ij}, \quad r^{ij} \in C^\infty(\mathbb{R}^n) \quad r^{ij} = -r^{ji} \quad (72)$$

$$\begin{aligned} \int \sigma^*(\ell) &= \quad (73) \\ &= \int \left(\frac{1}{2} \partial_k r^{ik} \partial^j r_{ij} - \frac{1}{4} (\partial_i f_j - \partial_j f_i) (\partial^i f^j - \partial^j f^i) - \partial^j r_{ij} (\partial^0 f^i - \partial^i f^0) \right) d^n x. \end{aligned}$$

For any compact oriented submanifold $N^n \subset \mathbb{R}^n$

we can take as variations $\delta f^\nu, \delta r^{ij}, \delta h^1, \delta h^2, \dots$ arbitrary functions on \mathbb{R}^n that vanish with all their derivatives on ∂N and such that $\delta r^{ij} = -\delta r^{ji}$.

Then the variational problem reduces to the corresponding E-L equations

$$\begin{aligned}\partial_0 \partial_j r^{ij} &= \partial_j (\partial^i f^j - \partial^j f^i), \\ \partial_j (\partial^k r_{ik} - (\partial_0 f_i - \partial_i f_0)) &= \partial_i (\partial^k r_{jk} - (\partial_0 f_j - \partial_j f_0)).\end{aligned}\tag{74}$$

The latter equation is equivalent to the existence of $\lambda \in C^\infty(\mathbb{R}^n)$ such that

$$\partial^k r_{ik} - (\partial_0 f_i - \partial_i f_0) = \partial_i \lambda.\tag{75}$$

Thus, an \mathcal{S} -section σ is an \mathcal{S} -stationary point of the internal Lagrangian ℓ iff there is a function $\lambda \in C^\infty(\mathbb{R}^n)$ such that σ satisfies the equations

$$\partial_0 g^i = \partial_j (\partial^i f^j - \partial^j f^i),\tag{76}$$

$$g^i = \partial^0 f^i - \partial^i (f^0 - \lambda).\tag{77}$$

Any \mathcal{S} -stationary point $A^\nu = f^\nu$, $F^{0i} = g^i$, $\partial_0 A^0 = h^1, \dots \Rightarrow$ into a solution using Φ^1 , where $\Phi^\mathcal{T}$ is the flow of the (ℓ, \mathcal{S}) -gauge symmetry

$$\varphi^0 \partial_{A^0} + \varphi^1 \partial_{\partial_0 A^0} + \varphi^2 \partial_{\partial_0^2 A^0} + \dots\tag{78}$$

for $\varphi^0 = -\lambda$, $\varphi^1 = -h^1 + \partial_0 (f^0 - \lambda)$, $\varphi^2 = -h^2 + \partial_0^2 (f^0 - \lambda)$, \dots

Then the variational problem reduces to the corresponding E-L equations

$$\begin{aligned}\partial_0 \partial_j r^{ij} &= \partial_j (\partial^i f^j - \partial^j f^i), \\ \partial_j (\partial^k r_{ik} - (\partial_0 f_i - \partial_i f_0)) &= \partial_i (\partial^k r_{jk} - (\partial_0 f_j - \partial_j f_0)).\end{aligned}\tag{74}$$

The latter equation is equivalent to the existence of $\lambda \in C^\infty(\mathbb{R}^n)$ such that

$$\partial^k r_{ik} - (\partial_0 f_i - \partial_i f_0) = \partial_i \lambda.\tag{75}$$

Thus, an \mathcal{S} -section σ is an \mathcal{S} -stationary point of the internal Lagrangian ℓ iff there is a function $\lambda \in C^\infty(\mathbb{R}^n)$ such that σ satisfies the equations

$$\partial_0 g^i = \partial_j (\partial^i f^j - \partial^j f^i),\tag{76}$$

$$g^i = \partial^0 f^i - \partial^i (f^0 - \lambda).\tag{77}$$

Any \mathcal{S} -stationary point $A^\nu = f^\nu$, $F^{0i} = g^i$, $\partial_0 A^0 = h^1$, $\dots \Rightarrow$ into a solution using Φ^1 , where Φ^T is the flow of the (ℓ, \mathcal{S}) -gauge symmetry

$$\varphi^0 \partial_{A^0} + \varphi^1 \partial_{\partial_0 A^0} + \varphi^2 \partial_{\partial_0^2 A^0} + \dots\tag{78}$$

for $\varphi^0 = -\lambda$, $\varphi^1 = -h^1 + \partial_0 (f^0 - \lambda)$, $\varphi^2 = -h^2 + \partial_0^2 (f^0 - \lambda)$, \dots

Remarkable conclusion

All \mathcal{S} -stationary points of the Maxwell system are (ℓ, \mathcal{S}) -gauge equivalent to its solutions!

Since Maxwell's equations are Lorentz-invariant, the same conclusion can be made for all spatial distributions that one can obtain from the \mathcal{S} using Lorentz transformations.

Let us consider an example of a variational equation that is not a Lagrangian one. The potential KdV equation

$$u_t = 3u_x^2 + u_{xxx} \quad (79)$$

admits the differential consequence $\mathbb{E}(L) = 0$, where

$$L = \left(\frac{u_x u_t}{2} - u_x^3 + \frac{u_{xx}^2}{2} \right) dt \wedge dx. \quad (80)$$

$$\mathcal{E} : \quad t, x, u, u_x, u_{xx}, u_{xxx}, \dots \quad \bar{D}_t, \bar{D}_x \quad (81)$$

Remarkable conclusion

All \mathcal{S} -stationary points of the Maxwell system are (ℓ, \mathcal{S}) -gauge equivalent to its solutions!

Since Maxwell's equations are Lorentz-invariant, the same conclusion can be made for all spatial distributions that one can obtain from the \mathcal{S} using Lorentz transformations.

Let us consider an example of a variational equation that is not a Lagrangian one. The potential KdV equation

$$u_t = 3u_x^2 + u_{xxx} \quad (79)$$

admits the differential consequence $E(L) = 0$, where

$$L = \left(\frac{u_x u_t}{2} - u_x^3 + \frac{u_{xx}^2}{2} \right) dt \wedge dx. \quad (80)$$

$$\mathcal{E} : \quad t, x, u, u_x, u_{xx}, u_{xxx}, \dots \quad \bar{D}_t, \bar{D}_x \quad (81)$$

The corresponding internal Lagrangian ℓ is represented by

$$\ell = \left(\frac{u_x(3u_x^2 + u_{xxx})}{2} - u_x^3 + \frac{u_{xx}^2}{2} \right) dt \wedge dx - \frac{1}{2}(3u_x^2 + u_{xxx}) dt \wedge \bar{\theta}_0 + u_{xx} dt \wedge \bar{\theta}_x + \frac{1}{2}u_x \bar{\theta}_0 \wedge dx, \quad (82)$$

$$\bar{\theta}_0 = du - u_x dx - (3u_x^2 + u_{xxx})dt, \quad \bar{\theta}_x = du_x - u_{xx} dx - (6u_x u_{xx} + u_{xxxx})dt.$$

Let \mathcal{S} be the lift of the distribution $\ker dt$. The \mathcal{S} -presymplectic structure:

$$\omega = \frac{1}{2}\bar{\theta}_x \wedge \bar{\theta}_0 \wedge dx. \quad (83)$$

Any \mathcal{S} -symmetry of the potential KdV equation has the form

$$X = \varphi \partial_u + \bar{D}_x(\varphi) \partial_{u_x} + \bar{D}_x^2(\varphi) \partial_{u_{xx}} + \dots, \quad (84)$$

where $\varphi \in \mathcal{F}(\mathcal{E})$ can be chosen arbitrarily. Then

$$X \lrcorner \omega = \frac{1}{2} \left(\bar{D}_x(\varphi) \bar{\theta}_0 - \varphi \bar{\theta}_x \right) \wedge dx \in \bar{D}_x(\varphi) \bar{\theta}_0 \wedge dx + d \left(\frac{\varphi}{2} \bar{\theta}_0 \right) + \mathcal{S}^2 \Lambda^2(\mathcal{E})$$

and (ℓ, \mathcal{S}) -gauge symmetries are given by functions of the form $\varphi = \varphi(t)$.

The corresponding internal Lagrangian ℓ is represented by

$$\ell = \left(\frac{u_x(3u_x^2 + u_{xxx})}{2} - u_x^3 + \frac{u_{xx}^2}{2} \right) dt \wedge dx - \frac{1}{2}(3u_x^2 + u_{xxx}) dt \wedge \bar{\theta}_0 + u_{xx} dt \wedge \bar{\theta}_x + \frac{1}{2}u_x \bar{\theta}_0 \wedge dx, \quad (82)$$

$$\bar{\theta}_0 = du - u_x dx - (3u_x^2 + u_{xxx})dt, \quad \bar{\theta}_x = du_x - u_{xx} dx - (6u_x u_{xx} + u_{xxxx})dt.$$

Let \mathcal{S} be the lift of the distribution $\ker dt$. The \mathcal{S} -presymplectic structure:

$$\omega = \frac{1}{2}\bar{\theta}_x \wedge \bar{\theta}_0 \wedge dx. \quad (83)$$

Any \mathcal{S} -symmetry of the potential KdV equation has the form

$$X = \varphi \partial_u + \bar{D}_x(\varphi) \partial_{u_x} + \bar{D}_x^2(\varphi) \partial_{u_{xx}} + \dots, \quad (84)$$

where $\varphi \in \mathcal{F}(\mathcal{E})$ can be chosen arbitrarily. Then

$$X \lrcorner \omega = \frac{1}{2} \left(\bar{D}_x(\varphi) \bar{\theta}_0 - \varphi \bar{\theta}_x \right) \wedge dx \in \bar{D}_x(\varphi) \bar{\theta}_0 \wedge dx + d \left(\frac{\varphi}{2} \bar{\theta}_0 \right) + \mathcal{S}^2 \Lambda^2(\mathcal{E})$$

and (ℓ, \mathcal{S}) -gauge symmetries are given by functions of the form $\varphi = \varphi(t)$.

\mathcal{S} -stationary points are (ℓ, \mathcal{S}) -gauge equivalent to solutions

Any \mathcal{S} -section σ has the form

$$\sigma: \quad u = f, \quad u_x = \partial_x f, \quad u_{xx} = \partial_x^2 f, \quad u_{xxx} = \partial_x^3 f, \quad \dots, \quad (85)$$

where $f \in C^\infty(\mathbb{R}^2)$ can be chosen arbitrarily.

$$\sigma^*(\ell) = \left(\frac{\partial_x f \partial_t f}{2} - (\partial_x f)^3 + \frac{(\partial_x^2 f)^2}{2} \right) dt \wedge dx, \quad (86)$$

\mathcal{S} -stationary points are described by the Euler-Lagrange equation

$$\partial_x \left(\partial_t f - 3(\partial_x f)^2 - \partial_x^3 f \right) = 0 \quad \Leftrightarrow \quad \partial_t f = 3(\partial_x f)^2 + \partial_x^3 f + g(t) \quad (87)$$

Denote by Φ_g^T the flow of the (ℓ, \mathcal{S}) -gauge symmetry $\varphi = -\int_0^t g(\tau) d\tau$.
 Φ_g^1 relate \mathcal{S} -stationary points to solutions of the potential KdV.

\mathcal{S} -stationary points are (ℓ, \mathcal{S}) -gauge equivalent to solutions

Any \mathcal{S} -section σ has the form

$$\sigma: \quad u = f, \quad u_x = \partial_x f, \quad u_{xx} = \partial_x^2 f, \quad u_{xxx} = \partial_x^3 f, \quad \dots, \quad (85)$$

where $f \in C^\infty(\mathbb{R}^2)$ can be chosen arbitrarily.

$$\sigma^*(\ell) = \left(\frac{\partial_x f \partial_t f}{2} - (\partial_x f)^3 + \frac{(\partial_x^2 f)^2}{2} \right) dt \wedge dx, \quad (86)$$

\mathcal{S} -stationary points are described by the Euler-Lagrange equation

$$\partial_x \left(\partial_t f - 3(\partial_x f)^2 - \partial_x^3 f \right) = 0 \quad \Leftrightarrow \quad \partial_t f = 3(\partial_x f)^2 + \partial_x^3 f + g(t) \quad (87)$$

Denote by Φ_g^T the flow of the (ℓ, \mathcal{S}) -gauge symmetry $\varphi = -\int_0^t g(\tau) d\tau$.
 Φ_g^1 relate \mathcal{S} -stationary points to solutions of the potential KdV.

KdV and potential KdV

$$\begin{array}{ccc} u_t = 3u_x^2 + u_{xxx} & & \\ \downarrow \rho & \rho: & v = u_x, v_x = u_{xx}, \dots \\ v_t = 6vv_x + v_{xxx} & & \end{array} \quad (88)$$

ρ establishes the one-to-one correspondence

- between (ℓ, \mathcal{S}) -gauge equivalence classes of \mathcal{S} -sections of the potential KdV and $\rho_*(\mathcal{S})$ -sections of the KdV equation.
- between (ℓ, \mathcal{S}) -gauge equivalence classes of \mathcal{S} -stationary points of ℓ and solutions to the KdV.

Thus, in this example, (ℓ, \mathcal{S}) -gauge symmetries lead to the description of dynamics given by another equation (spatial-gauge Cauchy problems for potential KdV = Cauchy problems for KdV).

KdV and potential KdV

$$\begin{array}{ccc} u_t = 3u_x^2 + u_{xxx} & & \\ \downarrow \rho & \rho: & v = u_x, \quad v_x = u_{xx}, \quad \dots \\ v_t = 6vv_x + v_{xxx} & & \end{array} \quad (88)$$

ρ establishes the one-to-one correspondence

- between (ℓ, \mathcal{S}) -gauge equivalence classes of \mathcal{S} -sections of the potential KdV and $\rho_*(\mathcal{S})$ -sections of the KdV equation.
- between (ℓ, \mathcal{S}) -gauge equivalence classes of \mathcal{S} -stationary points of ℓ and solutions to the KdV.

Thus, in this example, (ℓ, \mathcal{S}) -gauge symmetries lead to the description of dynamics given by another equation (spatial-gauge Cauchy problems for potential KdV = Cauchy problems for KdV).

Covariant child

Suppose ℓ is an internal Lagrangian of \mathcal{E} represented by a form $\ell \in \Lambda^n(\mathcal{E})$.

A section σ of the bundle $\pi_{\mathcal{E}}$ is an *almost solution* if for each $x \in M$,

$$\dim(d\sigma_x(T_x M) \cap \mathcal{C}_{\sigma(x)}) \geq n - 1. \quad (89)$$

A mapping $\gamma: \mathbb{R} \times M \rightarrow \mathcal{E}$ is a *path in almost solutions* of $\pi_{\mathcal{E}}$ if the

$$\gamma(\tau): x \mapsto \gamma(\tau, x) \quad (90)$$

are almost solutions of $\pi_{\mathcal{E}}$ for all $\tau \in \mathbb{R}$.

Almost solutions σ and σ' of $\pi_{\mathcal{E}}$ are *almost gauge equivalent* if there exist diffeomorphisms $f_1, \dots, f_k: \mathcal{E} \rightarrow \mathcal{E}$ such that

- 1) each f_i is an \mathcal{S}_i -gauge transformation, where \mathcal{S}_i is a spatial distribution;
- 2) σ is an \mathcal{S}_1 -section;
- 3) $f_i \circ \dots \circ f_1 \circ \sigma$ is an \mathcal{S}_{i+1} -section, $1 \leq i \leq k - 1$;
- 4) $\sigma' = f_k \circ \dots \circ f_2 \circ f_1 \circ \sigma$.

Covariant child

Suppose ℓ is an internal Lagrangian of \mathcal{E} represented by a form $\ell \in \Lambda^n(\mathcal{E})$.

A section σ of the bundle $\pi_{\mathcal{E}}$ is an *almost solution* if for each $x \in M$,

$$\dim(d\sigma_x(T_x M) \cap \mathcal{C}_{\sigma(x)}) \geq n - 1. \quad (89)$$

A mapping $\gamma: \mathbb{R} \times M \rightarrow \mathcal{E}$ is a *path in almost solutions* of $\pi_{\mathcal{E}}$ if the

$$\gamma(\tau): x \mapsto \gamma(\tau, x) \quad (90)$$

are almost solutions of $\pi_{\mathcal{E}}$ for all $\tau \in \mathbb{R}$.

Almost solutions σ and σ' of $\pi_{\mathcal{E}}$ are *almost gauge equivalent* if there exist diffeomorphisms $f_1, \dots, f_k: \mathcal{E} \rightarrow \mathcal{E}$ such that

- 1) each f_i is an \mathcal{S}_i -gauge transformation, where \mathcal{S}_i is a spatial distribution;
- 2) σ is an \mathcal{S}_1 -section; 3) $f_i \circ \dots \circ f_1 \circ \sigma$ is an \mathcal{S}_{i+1} -section, $1 \leq i \leq k - 1$;
- 4) $\sigma' = f_k \circ \dots \circ f_2 \circ f_1 \circ \sigma$.

An almost solution σ is a *stationary point* of ℓ if

for any compact oriented submanifold $N^n \subset M^n$, the relation

$$\left. \frac{d}{d\tau} \right|_{\tau=0} \int_N \gamma(\tau)^*(\ell) = 0 \quad (91)$$

holds for each path γ in almost solutions such that $\gamma(0) = \sigma$ and all points of the boundary ∂N are fixed.

Covariant canonical variational principle

An almost gauge equivalence class *satisfies the covariant canonical variational principle* if it can be represented by a stationary point of ℓ .

- The choice of a representative of ℓ has no impact.
- Solutions of a variational equation produce almost gauge equivalence classes that satisfy the covariant canonical variational principle.
- No concept/role of time.

An almost solution σ is a *stationary point* of ℓ if

for any compact oriented submanifold $N^n \subset M^n$, the relation

$$\left. \frac{d}{d\tau} \right|_{\tau=0} \int_N \gamma(\tau)^*(\ell) = 0 \quad (91)$$

holds for each path γ in almost solutions such that $\gamma(0) = \sigma$ and all points of the boundary ∂N are fixed.

Covariant canonical variational principle

An almost gauge equivalence class *satisfies the covariant canonical variational principle* if it can be represented by a stationary point of ℓ .

- The choice of a representative of ℓ has no impact.
- Solutions of a variational equation produce almost gauge equivalence classes that satisfy the covariant canonical variational principle.
- No concept/role of time.

$$\mathcal{E} \subset J^\infty(\pi), \quad E(L)|_{\mathcal{E}} = 0$$

$$L \Rightarrow \boldsymbol{\lambda} \in \frac{\{l \in \Lambda^n(\mathcal{E}) : dl \in \mathcal{C}^2 \Lambda^{n+1}(\mathcal{E})\}}{d(\mathcal{C} \Lambda^{n-1}(\mathcal{E})) + \mathcal{C}^2 \Lambda^n(\mathcal{E})} \quad (92)$$

If M is compact and oriented, then the action






$$\sigma \mapsto \int_M \sigma^*(\boldsymbol{\lambda}) \quad (93)$$




is well-defined on almost solutions such that $\forall x \in \partial M$,

$$d\sigma_x(T_x \partial M) \subset \mathcal{C}_{\sigma(x)} \quad (94)$$

Main weakness of this approach

Constrained variational problems may arise due to the non-triviality of spatial equations.

-  K. Druzhkov, Internal Lagrangians and spatial-gauge symmetries.
<https://arxiv.org/pdf/2404.06606>.
-  K. Druzhkov, Lagrangian formalism and the intrinsic geometry of PDEs, J. Geom. Phys. 189 (2023) 104848.
<https://doi.org/10.1016/j.geomphys.2023.104848>.
-  K. Druzhkov, Internal Lagrangians of PDEs as variational principles, J. Geom. Phys. 199 (2024) 105143.
<https://doi.org/10.1016/j.geomphys.2024.105143>.
-  M. Grigoriev, Presymplectic structures and intrinsic Lagrangians.
arXiv:1606.07532.
-  M. Grigoriev, V. Gritzaenko, Presymplectic structures and intrinsic Lagrangians for massive fields, Nucl. Phys. B (2022) 975(4):115686.
DOI: [10.1016/j.nuclphysb.2022.115686](https://doi.org/10.1016/j.nuclphysb.2022.115686).

-  A.M. Vinogradov, I.S. Krasil'schik (eds.), Symmetries and Conservation Laws for Differential Equations of Mathematical Physics, Vol. 182, American Mathematical Society, 1999.
-  A.M. Vinogradov, The \mathcal{C} -spectral sequence, Lagrangian formalism and conservation laws: I the linear theory; II the non-linear theory, J. Math. Anal. and Appl. 100 (1984) 1–40, 41–129.
[doi.org/10.1016/0022-247X\(84\)90071-4](https://doi.org/10.1016/0022-247X(84)90071-4),
[doi.org/10.1016/0022-247X\(84\)90072-6](https://doi.org/10.1016/0022-247X(84)90072-6).
-  A.M. Verbovetsky, Notes on the horizontal cohomology, Secondary Calculus and Cohomological Physics (M. Henneaux, I.S. Krasil'shchik and A.M. Vinogradov, eds.), Contemporary Mathematics, Amer. Math. Soc. Vol. 219. (1998). [arXiv:math.DG/9803115](https://arxiv.org/abs/math/9803115).

Thank you!