

Lie Pseudo-Groups and Coverings of Differential Equations

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Lie pseudo-groups

A **pseudo-group** \mathfrak{G} on a manifold M is a collection of local diffeomorphisms $\Phi: \mathcal{U} \rightarrow \hat{\mathcal{U}}, \Phi: x \mapsto \hat{x}$ such that

- 1) if $\Phi \in \mathfrak{G}, \Psi \in \mathfrak{G}$, and their composition $\Psi \circ \Phi$ is defined, then $\Psi \circ \Phi \in \mathfrak{G}$;
- 2) $\Phi \in \mathfrak{G} \Rightarrow \Phi^{-1} \in \mathfrak{G}$;
- 3) $\text{id}_M \in \mathfrak{G}$;
- 4) if $\Phi: \mathcal{U} \rightarrow \hat{\mathcal{U}}$ belongs to \mathfrak{G} , then for any open subset $\mathcal{V} \subset \mathcal{U}$ $\Phi|_{\mathcal{V}} \in \mathfrak{G}$;
- 5) $\Phi_1: \mathcal{U}_1 \rightarrow \hat{\mathcal{U}}_1, \Phi_2: \mathcal{U}_2 \rightarrow \hat{\mathcal{U}}_2$ belong to \mathfrak{G} , and $\Phi_1|_{\mathcal{U}_1 \cap \mathcal{U}_2} = \Phi_2|_{\mathcal{U}_1 \cap \mathcal{U}_2}$, then $\Phi: \mathcal{U}_1 \cup \mathcal{U}_2 \rightarrow \hat{\mathcal{U}}_1 \cup \hat{\mathcal{U}}_2$ defined by $\Phi|_{\mathcal{U}_1} = \Phi_1$ and $\Phi|_{\mathcal{U}_2} = \Phi_2$ belongs to \mathfrak{G} .

A pseudo-group \mathfrak{G} is called a **Lie pseudo-group**, if

- 6) the functions $\hat{x} = \Phi(x)$ are local analytic solutions of a system of PDEs (**Lie equations** of the pseudo-group \mathfrak{G})

$$R \left(x, \Phi(x), \frac{\partial \Phi(x)}{\partial x}, \dots, \frac{\partial^{\#I} \Phi(x)}{\partial x^I} \right) = 0.$$



Lie pseudo-groups

EXAMPLE: Lie groups = finite Lie pseudo-groups

EXAMPLE: $\text{SDiff}(\mathbb{R}^2)$:

$$\Phi: (x, y) \mapsto (\hat{x}, \hat{y}), \quad \Phi^*(d\hat{x} \wedge d\hat{y}) = dx \wedge dy,$$

Lie equations:
$$\frac{\partial \hat{x}}{\partial x} \frac{\partial \hat{y}}{\partial y} - \frac{\partial \hat{x}}{\partial y} \frac{\partial \hat{y}}{\partial x} = 1$$



- Sophus Lie's infinitesimal method :
 - infinitesimal generators;
 - linearized Lie equations;
 - integration.
- Éli Cartan's method :
 - Maurer-Cartan forms;
 - structure equations;
 - algebraic operations, differentiation.



Cartan's method

EXAMPLE (cont'd): Maurer–Cartan forms for $\text{SDiff}(\mathbb{R}^2)$:

$$\omega^1, \omega^2 \in \Omega^1(\mathbb{R}^2 \times \text{SL}(\mathbb{R}, 2)),$$

$$\begin{pmatrix} \omega^1 \\ \omega^2 \end{pmatrix} = Q \cdot \begin{pmatrix} dx \\ dy \end{pmatrix}, \quad Q \in \text{SL}(\mathbb{R}, 2).$$

$$\Psi: \mathbb{R}^2 \times \text{SL}(\mathbb{R}, 2) \rightarrow \mathbb{R}^2 \times \text{SL}(\mathbb{R}, 2), \quad \Psi: (x, y, Q) \mapsto (\hat{x}, \hat{y}, \hat{Q})$$

$$\Psi^* \begin{pmatrix} \hat{\omega}^1 \\ \hat{\omega}^2 \end{pmatrix} = \begin{pmatrix} \omega^1 \\ \omega^2 \end{pmatrix}, \quad \text{where} \quad \begin{pmatrix} \hat{\omega}^1 \\ \hat{\omega}^2 \end{pmatrix} = \hat{Q} \cdot \begin{pmatrix} d\hat{x} \\ d\hat{y} \end{pmatrix} \iff$$

$$(\hat{x}, \hat{y}, \hat{Q}) = \left(f(x, y), g(x, y), Q \cdot \begin{pmatrix} f_x(x, y) & f_y(x, y) \\ g_x(x, y) & g_y(x, y) \end{pmatrix}^{-1} \right),$$

$$\det \begin{pmatrix} f_x & f_y \\ g_x & g_y \end{pmatrix} = 1 \quad (= \text{Lie equations})$$



Structure equations for $\text{SDiff}(\mathbb{R}^2)$:

$$\begin{pmatrix} \omega^1 \\ \omega^2 \end{pmatrix} = Q \begin{pmatrix} dx \\ dy \end{pmatrix}$$

\implies

$$d \begin{pmatrix} \omega^1 \\ \omega^2 \end{pmatrix} = dQ \wedge \begin{pmatrix} dx \\ dy \end{pmatrix} = dQ \cdot Q^{-1} \wedge \begin{pmatrix} \omega^1 \\ \omega^2 \end{pmatrix}$$

$$= \begin{pmatrix} \pi^1 & \pi^2 \\ \pi^3 & -\pi^1 \end{pmatrix} \wedge \begin{pmatrix} \omega^1 \\ \omega^2 \end{pmatrix}$$

\implies

$$\begin{cases} d\omega^1 = \pi^1 \wedge \omega^1 + \pi^2 \wedge \omega^2, \\ d\omega^2 = \pi^3 \wedge \omega^1 - \pi^1 \wedge \omega^2. \end{cases}$$



Third fundamental Lie's theorem in Cartan's form: For a Lie pseudo-group there exists a collection of Maurer–Cartan forms with involutive and compatible structure equations

$$d\omega^i = A_{\rho k}^i \pi^\rho \wedge \omega^k + \frac{1}{2} B_{jk}^i \omega^j \wedge \omega^k, \quad B_{jk}^i = -B_{kj}^i.$$

The coefficients $A_{\rho k}^i$, B_{jk}^i are either constants or functions of invariants U^1, \dots, U^s of the pseudo-group. In the latter case

$$dU^s = C_k^s(U) \omega^k.$$

Third inverse fundamental Lie's theorem in Cartan's form: For a given involutive and compatible system of structure equations there exists a collection of 1-forms $\omega^1, \dots, \omega^m$ and functions U^1, \dots, U^s satisfying this system. The forms $\omega^1, \dots, \omega^m$ are Maurer–Cartan forms of a Lie pseudo-group, and the functions U^1, \dots, U^s are invariants of this pseudo-group.



Details:

- Cartan É. Œuvres Complètes. Paris: Gauthier - Villars, 1953
- Vasil'eva M.V. Structure of Infinite Lie Groups of Transformations. Moscow: MSPI, 1972 (in Russian)
- Stormark O. Lie's Structural Approach to PDE Systems. Cambridge: CUP, 2000



Symmetry pseudo-groups of differential equations

EXAMPLE: contact transformations on $J^q(\mathbb{R}^n \times \mathbb{R}^m)$.

$q = 2$, $m = 1$, Maurer–Cartan forms:

$$\Theta_0 = a (du - u_i dx^i),$$

$$\Theta_i = a B_i^j (du_j - u_{jk} dx^k) + g_i \Theta_0,$$

$$\Theta_{ij} = a B_i^k B_j^l (du_{kl} - u_{klm} dx^m) + s_{ij} \Theta_0 + w_{ij}^k \Theta_k,$$

$$\Xi^i = b_j^i dx^j + c^i \Theta_0 + f^{ij} \Theta_j,$$

where $b_k^i B_j^k = \delta_j^i$, $f^{ik} = f^{ki}$, $s_{ij} = s_{ji}$, $w_{ij}^k = w_{ji}^k$,

$$u_{klm} = u_{lkm} = u_{kml}.$$

Structure equations:

$$d\Theta_0 = \Phi_0^0 \wedge \Theta_0 + \Xi^i \wedge \Theta_i,$$

$$d\Theta_i = \Phi_i^0 \wedge \Theta_0 + \Phi_i^k \wedge \Theta_k + \Xi^k \wedge \Theta_{ik},$$

$$d\Theta_{ij} = \Phi_i^k \wedge \Theta_{kj} - \Phi_0^0 \wedge \Theta_{ij} + \Upsilon_{ij}^0 \wedge \Theta_0 + \Upsilon_{ij}^k \wedge \Theta_k + \Xi^k \wedge \Theta_{ijk},$$

$$d\Xi^i = \Phi_0^0 \wedge \Xi^i - \Phi_k^i \wedge \Xi^k + \Psi^{i0} \wedge \Theta_0 + \Psi^{ik} \wedge \Theta_k$$



EXAMPLE: contact symmetries of a differential equation
 $\mathcal{E} \subset J^q(\mathbb{R}^n \times \mathbb{R}^m)$.

Details:

- Fels M., Olver P.J., Acta Appl. Math., 1998, 51, 161–213
- M., J. Phys. A: Math. Gen., 2002, 35, 2965–2977
- M., J. Math. Sci., 2006, 135, 2680–2694



Applications:

- equivalence problems for DEs;
- symmetry analysis of classes of DEs;
- differential invariants, automorphic systems of DEs, Vessiot group splittings of DEs;
- Darboux integrability;
- coverings of DEs ;
- recursion operators;
- ...



- $n = 2$, finite-dimensional coverings:

Bryant R.L., Griffiths P.A., Duke Math. J., 1995, 78,
531–676

- $n > 2$, infinite-dimensional coverings:

M., J. Geom. Phys., 2009, 59, 1461–1475



EXAMPLE: integrable extension of the structure equations for $\text{SDiff}(\mathbb{R}^2)$.

The structure equations

$$\begin{cases} d\omega^1 = \pi^1 \wedge \omega^1 + \pi^2 \wedge \omega^2, \\ d\omega^2 = \pi^3 \wedge \omega^1 - \pi^1 \wedge \omega^2 \end{cases}$$

We have: $d(\omega^1 \wedge \omega^2) = 0 \implies$

$$\begin{cases} d\omega^1 = \pi^1 \wedge \omega^1 + \pi^2 \wedge \omega^2, \\ d\omega^2 = \pi^3 \wedge \omega^1 - \pi^1 \wedge \omega^2, \\ d\omega^3 = \omega^1 \wedge \omega^2. \end{cases}$$



4-dimensional generalization of rdDym equation

The rdDym equation

$$u_{ty} = u_x u_{xy} - u_y u_{xx}$$

- Błaszak M., Phys. Lett. A, 2002, 297, 191–195
- Pavlov M.V., J. Math. Phys., 2003, 44, 4134–4156
- Ovsienko V., Adv. Pure Appl. Math., 2010, 1, 7–17

The 4-dimensional generalization of the rdDym equation

$$u_{ty} = u_z u_{xy} - u_y u_{xz}$$

- Martínez Alonso L., Shabat A.B., Theor. Math. Phys. 2004, 140, 1073–1085



4-dimensional generalization of rdDym equation

The structure equations for the symmetry pseudo-group

$$d\theta_0 = \eta_1 \wedge \theta_0 + \xi^1 \wedge \theta_1 + \xi^2 \wedge \theta_2 + \xi^3 \wedge \theta_3 + \xi^4 \wedge \theta_4,$$

$$d\theta_1 = (\eta_1 - \eta_2) \wedge \theta_1 - \eta_3 \wedge \theta_2 + \theta_0 \wedge (\xi^4 - \theta_{24}) + \xi^1 \wedge \theta_{11} + \xi^2 \wedge \theta_{12} - \xi^3 \wedge \theta_{24} + \xi^4 \wedge \theta_{14},$$

$$d\theta_2 = (\eta_1 - \eta_4) \wedge \theta_2 + \theta_0 \wedge (\xi^3 - \theta_{23}) + \xi^1 \wedge \theta_{12} + \xi^2 \wedge \theta_{22} + \xi^3 \wedge \theta_{23} + \xi^4 \wedge \theta_{24},$$

$$d\theta_3 = -\xi^1 \wedge \theta_{24} + \xi^2 \wedge \theta_{23} + \xi^3 \wedge \theta_{33} + \xi^4 \wedge \theta_{34},$$

$$d\theta_4 = (\eta_4 - \eta_2) \wedge \theta_4 + \eta_3 \wedge \theta_3 + \theta_3 \wedge \theta_4 + \xi^1 \wedge \theta_{14} + \xi^2 \wedge \theta_{24} + \xi^3 \wedge \theta_{34} + \xi^4 \wedge \theta_{44},$$

$$d\xi^1 = \eta_2 \wedge \xi^1,$$

$$d\xi^2 = \eta_3 \wedge \xi^1 + \eta_4 \wedge \xi^2,$$

$$d\xi^3 = (\eta_1 + \theta_3) \wedge \xi^3 - (\eta_3 - \theta_4) \wedge \xi^4,$$

$$d\xi^4 = (\eta_1 + \eta_2 - \eta_4) \wedge \xi^4,$$

$$d\theta_{11} = (\eta_1 - 2\eta_2) \wedge \theta_{11} - 2\eta_3 \wedge \theta_{12} + \eta_9 \wedge \xi^2 - \eta_{10} \wedge (\theta_0 + \xi^3) + \eta_{11} \wedge \xi^1 + \eta_{12} \wedge \xi^4 \\ - 2\theta_1 \wedge \theta_{24} + \theta_2 \wedge (\xi^3 + \theta_{14}),$$

$$d\theta_{12} = (\eta_1 - \eta_2 - \eta_4) \wedge \theta_{12} - \eta_3 \wedge \theta_{22} + \eta_5 \wedge (\theta_0 + \xi^3) + \eta_7 \wedge \xi^2 + \eta_9 \wedge \xi^1 + \eta_{10} \wedge \xi^4 \\ + \theta_1 \wedge (\theta_{23} - \xi^3),$$

$$d\theta_{14} = (\eta_4 - 2\eta_2) \wedge (\xi^3 + \theta_{14}) - (\eta_1 + \theta_3) \wedge \xi^3 + \eta_3 \wedge (3\xi^4 - 2\theta_{24}) + \eta_{10} \wedge \xi^2 \\ + (\eta_{12} - 2\theta_1) \wedge \xi^1 - \theta_4 \wedge \xi^4,$$

$$d\theta_{22} = (\eta_1 - 2\eta_4) \wedge \theta_{22} - \eta_5 \wedge \xi^4 + \eta_6 \wedge (\theta_0 + \xi^3) + \eta_7 \wedge \xi^1 + \eta_8 \wedge \xi^2 + \theta_2 \wedge (\theta_{23} - \xi^3),$$

$$d\theta_{23} = (\eta_1 + \theta_3) \wedge \xi^3 - (\eta_3 - \theta_4) \wedge \xi^4 + \eta_4 \wedge (\xi^3 - \theta_{23}) + \eta_5 \wedge \xi^1 + \eta_6 \wedge \xi^2,$$

...

4-dimensional generalization of rdDym equation

THEOREM 1. The above structure equations have no contact integrable extensions with constant coefficients. Each their contact integrable extension with one additional invariant is contact - equivalent to the following one

$$d\omega_0 = (\eta_1 + \omega_2) \wedge \omega_0 + W_1 (\omega_2 + \theta_4) \wedge \xi^1 + W_1 \omega_1 \wedge \xi^2 - (\omega_1 + \theta_3) \wedge \xi^3 + W_1 \omega_2 \wedge \xi^4,$$

$$dW_1 = W_1 (\eta_1 - \eta_4) + Z_1 (\omega_0 - W_1 \xi^2 + \xi^3),$$

where Z_1 is an arbitrary parameter.

REMARK. $Z_1 = 0 \Rightarrow$ a non-removable parameter in the corresponding covering



4-dimensional generalization of rdDym equation

COROLLARY 1. The 4D rdDym equation has two coverings defined by systems

$$\begin{cases} q_t &= u_z q_x - \lambda^{-1} q_z, \\ q_y &= \lambda u_y q_x, \end{cases}$$

and

$$\begin{cases} q_t &= u_z q_x - q^{-1} q_z, \\ q_y &= u_y q q_x. \end{cases}$$

The parameter λ in the first system is non-removable.

REMARK. Nonlocal symmetries, nonlocal conservation laws, Kähler structure.



- Recursion operators as integro-differential operators
 - P.J. Olver, 1977
 - B. Fuchssteiner, 1979
 - V.E. Zakharov, B.G. Konopelchenko, 1984
 - A.S. Fokas. P.M. Santini, 1986
 - . . .
 - J.A. Sanders, J.P. Wang, 2001
- Recursion operators as Bäcklund autotransformations for tangent coverings
 - C.J. Papachristou, B.K. Harrison, 1988
 - C.J. Papachristou, 1990
 - G.A. Guthrie, 1994
 - I.S. Krasil'shchik, P.H.M. Kersten, 1994
 - M. Marvan, 1996
 - A. Sergyeyev, 2000
 - . . .
 - C.J. Papachristou, B.K. Harrison, 2010
 - I.S. Krasil'shchik, A.M. Verbovetsky, R. Vitolo, 2011
 - M. Marvan, A. Sergyeyev, 2012



Recursion operators

- A holonomic section $\varphi: \mathcal{E} \rightarrow \mathcal{T}(\mathcal{E})$ of the tangent covering is a symmetry of \mathcal{E} .
- A recursion operator for symmetries of \mathcal{E} is a Bäcklund autotransformation of $\mathcal{T}(\mathcal{E})$

Details and examples:

- M. Marvan. Differential Geometry and Applications. Brno: Masaryk University, 1996, 393–402
- I.S. Krasil'shchik, A.M. Verbovetsky, R. Vitolo, Acta Appl. Math., 2012, 120, 199–218

The technique of the contact integrable extensions can be adapted to the problem of finding recursion operators for symmetries of PDEs.



EXAMPLE: The 4D rdDym equation

$$u_{ty} = u_z u_{xy} - u_y u_{xz} \quad (1)$$

The linearization:

$$v_{ty} = u_z v_{xy} - u_y v_{xz} + u_{xy} v_z - u_{xz} v_y. \quad (2)$$

The tangent covering: the infinite prolongation of system (1), (2) equipped with the restrictions of the extended total derivatives.



The structure equations for the symmetry pseudo-group of the tangent covering is a CIE of the structure equations for the symmetry pseudo-group of the 4D rdDym equation:

$$\begin{aligned}
 d\zeta_0 &= (\eta_1 - \zeta_3 + X_3 \xi^1 + X_2 \xi^2 + X_1 \xi^3 + X_4 \xi^4) \wedge \zeta_0 - \zeta_1 \wedge \xi^1 - \zeta_2 \wedge \xi^2 - \zeta_3 \wedge \xi^3 \\
 &\quad - \zeta_4 \wedge \xi^4 + \theta_0 \wedge (\zeta_3 - X_1 \xi^3 - X_4 \xi^4), \\
 d\zeta_1 &= -\theta_{24} \wedge \zeta_0 + (\eta_1 - \eta_2 - \zeta_3) \wedge \zeta_1 - \eta_3 \wedge \zeta_2 - \theta_1 \wedge \zeta_3 + (\eta_{34} + X_1 (\zeta_1 + \theta_1)) \wedge \theta_0 \\
 &\quad + \eta_{32} \wedge \xi^1 + \eta_{33} \wedge \xi^2 + \eta_{34} \wedge \xi^3 + \eta_{35} \wedge \xi^4, \\
 d\zeta_2 &= \zeta_0 \wedge (\theta_0 + \theta_{23}) + \zeta_1 \wedge (X_2 \xi^1 - X_1 \xi^4) + (\eta_1 - \eta_4 + X_3 \xi^1 - X_1 \theta_0 + X_4 \xi^4) \wedge \zeta_2 \\
 &\quad + (\zeta_2 + \theta_2) \wedge \zeta_3 + (\eta_{24} - \eta_{34} - X_1 \theta_1 - X_4 \theta_2 - X_5 (\theta_{23} + \theta_0)) \wedge \xi^4 + \eta_{33} \wedge \xi^1 \\
 &\quad + \eta_{36} \wedge \xi^2 + \eta_{37} \wedge \xi^3 + (\eta_{37} + X_1 \theta_2) \wedge \theta_0, \\
 d\zeta_3 &= (\eta_{34} + X_1 (\zeta_1 + \theta_1) - X_3 \zeta_3) \wedge \xi^1 + (\eta_{37} + \zeta_0 + X_1 (\zeta_2 + \theta_2) - X_3 \zeta_3) \wedge \xi^2 \\
 &\quad + \eta_{38} \wedge \xi^3 + \eta_{39} \wedge \xi^4, \\
 d\zeta_4 &= (\eta_3 - X_4 \xi^3) \wedge \zeta_3 - (\zeta_3 + \eta_2 - \eta_4 - X_3 \xi^1 - X_2 \xi^2 - X_1 \xi^3) \wedge \zeta_4 + \eta_{40} \wedge \xi^4 \\
 &\quad + (\eta_{35} - \zeta_0 + X_4 (\zeta_1 + \theta_1)) \wedge \xi^1 - (\eta_{34} + X_1 (\zeta_1 + \theta_1) + X_5 \theta_{23} - \theta_{24}) \wedge \xi^2 \\
 &\quad + (\eta_{39} + X_4 \theta_3 - X_1 \theta_4) \wedge \xi^3.
 \end{aligned}$$

THEOREM 2. The structure equations for the symmetry pseudo-group of the tangent covering of the 4D rdDym equation have a CIE

$$\begin{aligned}d\zeta_5 &= W_2 (\xi^2 - X_5 \xi^1) \wedge \zeta_5 + (\theta_{24} - W_2 \zeta_4) \wedge \xi^1 + (W_2 \zeta_3 - \theta_{23}) \wedge \xi^2 \\ &\quad + \zeta_6 \wedge \xi^3 + \zeta_7 \wedge \xi^4, \\ dW_2 &= W_2 (\zeta_3 - \zeta_5 - \eta_4 - (X_3 + X_5 W_2) \xi^1 - (X_2 - W_2) \xi^2) + Y_2 \xi^3 + Y_3 \xi^4.\end{aligned}$$

The inverse third fundamental Lie theorem \implies

$$\zeta_5 = \frac{1}{w} \left(dw - \frac{u_y v_z - u_z v_y + (u_z u_{xy} - u_y u_{xz}) w}{u_y} dt - \frac{u_{xy} w - v_y}{u_y} dx - w_y dy - w_z dz \right).$$



$$\zeta_5 = 0 \implies$$

$$\begin{cases} w_t &= u_y^{-1} (u_y v_z - u_z v_y + (u_z u_{xy} - u_y u_{xz}) w), \\ w_x &= u_y^{-1} (u_{xy} w - v_y) \end{cases}$$

Exclude $v \implies w$ is solution to the linearization \implies

COROLLARY 2. System

$$\begin{cases} D_t(\psi) &= u_y^{-1} (u_y D_z(\varphi) - u_z D_y(\varphi) + (u_z u_{xy} - u_y u_{xz}) \psi), \\ D_x(\psi) &= u_y^{-1} (u_{xy} \psi - D_y(\varphi)) \end{cases}$$

defines a recursion operator for symmetries of 4D rdDym equation. The inverse operator is defined by

$$\begin{cases} D_y(\varphi) &= -u_y D_x(\psi) + u_{xy} \psi, \\ D_z(\varphi) &= D_t(\psi) - u_z D_x(\psi) + u_{xz} \psi. \end{cases}$$



Ovsienko's system

$$u_{ty} = u_x u_{xy} - u_y u_{xx},$$

$$v_{ty} = u_x v_{xy} - u_y v_{xx} + 2(u_{xx} v_y - u_{xy} v_x) + 2\kappa(2u_x u_{xy} - u_y u_{xx})$$

- $\kappa = 1$: Ovsienko V. Adv. Pure Appl. Math. 2010, 1, 7–17: bi-Hamiltonian system on the dual space to the looped Virasoro algebra.
- $\kappa = 0$: the cotangent covering of the rdDym equation



THEOREM 3. The structure equations for the symmetry pseudo-group of the rdDym equations have a CIE defined by the forms

$$\omega_0 = p_{00} (dv - v_t dt - v_x dx - v_y dy) + \sum_{j=0}^3 q_{0j} \theta_j,$$

$$\begin{aligned} \omega_i = & p_{i0} (dv - v_t dt - v_x dx - v_y dy) + p_{i1} (dv_t - v_{tt} dt - v_{tx} dx - R dy) \\ & + p_{i2} (dv_x - v_{tx} dt - v_{xx} dx - v_{xy} dy) + p_{i3} (dv_y - R dt - v_{xy} dx - v_{yy} dy) \\ & + \sum_{j=0}^3 q_{ij} \theta_j + \sum^* s_{ijk} \theta_{jk}, \quad i \in \{1, 2, 3\}, \end{aligned}$$

where R is the r.h.s. of the second equation of the system, θ_j and θ_{jk} are the M-C forms of the symmetry pseudo-group of the first equations, while \sum^* means summation over all j, k such that $1 \leq j \leq k \leq 3$ and $(j, k) \neq (1, 3)$. In these forms $p_{00} \neq 0$, $\det(p_{ij}) \neq 0$ for $1 \leq i \leq 3$, $1 \leq j \leq 3$, and $q_{01}^2 + q_{02}^2 + q_{03}^2 \neq 0$.



$$d\omega_0 = \eta_{12} \wedge \omega_0 + \xi^1 \wedge \omega_1 + \xi^2 \wedge \omega_2 + \xi^3 \wedge \omega_3 + \eta_{13} \wedge \theta_0 + \eta_{14} \wedge \theta_1 + \eta_{15} \wedge \theta_2 + \eta_{16} \wedge \theta_3,$$

$$d\omega_1 = (2\theta_{22} + 3X_1\xi^3) \wedge \omega_0 + (\eta_1 + \eta_{12} + (X_1 + 2)\theta_3 - 2\theta_{23} + 2X_2\xi^3) \wedge \omega_1 \\ + 3(\theta_2 + \frac{1}{2}(X_1 + 2)\xi^3) \wedge \omega_2 + 3\eta_{13} \wedge \theta_1 + \eta_{14} \wedge (2\theta_1 + \theta_{11}) + \eta_{15} \wedge (X_1\theta_1 + \theta_{12}) \\ + \eta_{16} \wedge (\theta_{22} - 3(\theta_2 + \xi^3)) + \eta_{17} \wedge (\theta_0 + \xi^3) + \eta_{18} \wedge \xi^1 + \eta_{19} \wedge \xi^2,$$

$$d\omega_2 = \omega_0 \wedge (2\xi^1 - X_1\xi^2) + \frac{1}{2}(4 - 3X_1)\omega_1 \wedge \xi^1 + 2\omega_3 \wedge \xi^3 + \eta_{17} \wedge \xi^2 + \eta_{19} \wedge \xi^1 \\ + \omega_2 \wedge (\theta_{23} - \eta_{12} + \xi^1 - \frac{1}{2}(X_1 + 2)(\theta_3 + \xi^2) - X_2\xi^3) + \eta_{13} \wedge (3(\theta_2 - \frac{1}{2}X_1\theta_0) + 5\xi^3) \\ + \eta_{14} \wedge (\theta_0 + \theta_{12} - \frac{1}{2}X_1\theta_1 + \xi^3) + \eta_{16} \wedge (\theta_{23} - \frac{1}{2}(X_1 + 6)\theta_3 - 3\xi^2 - X_2\xi^3) \\ + \eta_{15} \wedge (\theta_{22} - \frac{1}{4}X_1(3X_1 + 2)\theta_0 + \frac{3}{2}X_1\theta_2 + \frac{1}{2}(7X_1 + 4)\xi^3),$$

$$d\omega_3 = -(X_1\omega_0 + \frac{1}{2}(3X_1 + 2)\omega_2) \wedge \xi^1 + \omega_3 \wedge (\eta_1 - \eta_{12} + 3\theta_3 + \frac{1}{2}(X_1 + 6)\xi^2) \\ + \eta_{13} \wedge (3\theta_3 + 5\xi^2) + \eta_{14} \wedge (2\theta_2 - \frac{3}{2}X_1\theta_0 + \theta_{22} + \xi^2) + \eta_{17} \wedge \xi^1 + \eta_{20} \wedge \xi^3 \\ + \eta_{15} \wedge ((X_1 + 2)\theta_3 + \theta_{23} + \frac{1}{2}(7X_1 + 4)\xi^2) + \eta_{16} \wedge (\theta_{33} - 3\xi^1 - X_2\xi^2).$$

$$X_1 = u_y u_{xxy} u_{xy}^{-2}, \quad X_2 = u_y u_{xxx} (u_{xy} u_{yy} - u_y u_{xyy}) u_{xy}^{-4}$$



The coefficients of the CIE do not depend on $\kappa \implies$

COROLLARY 3. There exists a Bäcklund transformation of the form

$$\left\{ \begin{array}{l} \tilde{t} = h_1(t, x, y), \\ \tilde{x} = h_2(t, x, y), \\ \tilde{y} = h_3(t, x, y), \\ \tilde{u} = h_4(t, x, y, u), \\ \tilde{v} = h_5(t, x, y, u, u_t, u_x, u_y, v), \\ \tilde{v}_{\tilde{t}} = h_6(t, x, y, u, u_t, u_x, u_y, u_{tt}, u_{tx}, u_{xx}, u_{xy}, u_{yy}, v, v_t, v_x, v_y), \\ \tilde{v}_{\tilde{x}} = h_7(t, x, y, u, u_t, u_x, u_y, u_{tt}, u_{tx}, u_{xx}, u_{xy}, u_{yy}, v, v_t, v_x, v_y), \\ \tilde{v}_{\tilde{y}} = h_8(t, x, y, u, u_t, u_x, u_y, u_{tt}, u_{tx}, u_{xx}, u_{xy}, u_{yy}, v, v_t, v_x, v_y) \end{array} \right.$$

mapping Ovsienko's system to the cotangent covering of the rdDym equation.

