

Cartan's Structure Theory of Symmetry Pseudo-Groups, Zero-Curvature Representations and Bäcklund Transformations of Differential Equations.

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A **pseudo-group** \mathfrak{G} on a manifold M is a set of local diffeomorphisms $\Phi: \mathcal{U} \rightarrow \hat{\mathcal{U}}$, $\Phi: x \mapsto \hat{x}$ such that

- 1) if $\Phi \in \mathfrak{G}$, $\Psi \in \mathfrak{G}$, and their composition $\Psi \circ \Phi$ is defined, then $\Psi \circ \Phi \in \mathfrak{G}$;
- 2) $\Phi \in \mathfrak{G} \Rightarrow \Phi^{-1} \in \mathfrak{G}$;
- 3) $\text{id}_M \in \mathfrak{G}$.

A pseudo-group \mathfrak{G} is called a **Lie pseudo-group**, if

- 4) the functions $\hat{x} = \Phi(x)$ are local analytic solutions of a system of PDEs (**Lie equations** of the pseudo-group \mathfrak{G})

$$R \left(x, \Phi(x), \frac{\partial \Phi(x)}{\partial x}, \dots, \frac{\partial^{\#I} \Phi(x)}{\partial x^I} \right) = 0.$$



Élie Cartan's method of equivalence

Maurer–Cartan forms of the Lie pseudo-group \mathfrak{G} : a collection of 1-forms

$$\omega^i \in \Omega^1(M \times N \times H), \quad i \in \{1, \dots, \dim M + \dim N\},$$

where N is a manifold, H is a finite Lie group.

A local diffeomorphism Φ on M , $\Phi: \mathcal{U} \rightarrow \hat{\mathcal{U}}$ belongs to \mathfrak{G} whenever there exists a fibre-preserving diffeomorphism Ψ on $M \times N \times H$, $\Psi: \mathcal{W} \rightarrow \hat{\mathcal{W}}$ such that

- Φ is the projection of Ψ w.r.t. $M \times N \times H \rightarrow M$;
- $\Psi^*(\omega^i|_{\hat{\mathcal{W}}}) = \omega^i|_{\mathcal{W}}$.



Élie Cartan's method of equivalence

Structure equations of a Lie pseudo-group \mathfrak{G} :

$$d\omega^i = A_{\alpha j}^i(U^\sigma) \pi^\alpha \wedge \omega^j + B_{jk}^i(U^\sigma) \omega^j \wedge \omega^k, \quad B_{jk}^i = -B_{kj}^i,$$

$$dU^\kappa = C_j^\kappa(U^\sigma) \omega^j,$$

$U^\sigma : M \rightarrow \mathbb{R}$, $\sigma \in \{1, \dots, s\}$, $s < \dim M$, — invariants of the pseudo-group \mathfrak{G}

- π^α — depend on differentials of coordinates on H ;
- involutivity conditions are satisfied,
- compatibility conditions are satisfied.

Maurer–Cartan forms and structure equations of a Lie pseudo-group can be found from its Lie equations algorithmically.



Involutivity conditions:

$$r^{(1)} = n \dim H - \sum_{k=1}^{n-1} (n-k) \sigma_k,$$

where $n = \dim M + \dim N$, $r^{(1)}$ is the dimension of the linear space of coefficients z_j^α such that the replacement

$\pi^\alpha \mapsto \pi^\alpha + z_j^\alpha \omega^j$ preserves the structure equations;

$$\sigma_k = \max_{u_1, \dots, u_k} \text{rank } \mathbb{A}_k(u_1, \dots, u_k) - \sum_{j=1}^{k-1} \sigma_j,$$

$$\mathbb{A}_1(u_1) = \left(A_{\alpha j}^i u_1^j \right),$$

$$\mathbb{A}_q(u_1, \dots, u_q) = \left(\begin{array}{c} \mathbb{A}_{q-1}(u_1, \dots, u_{q-1}) \\ A_{\alpha j}^i u_q^j \end{array} \right), \quad q \in \{2, \dots, n-1\}.$$



Compatibility conditions:

- $d(d\omega^i) = 0 = d\left(A_{\alpha j}^i \pi^\alpha \wedge \omega^j + B_{jk}^i \omega^j \wedge \omega^k\right)$
- $d(dU^\kappa) = 0 = d(C_j^\kappa \omega^j)$

\implies

over-determined system for the coefficients $A_{\alpha j}^i, B_{jk}^i, C_j^\kappa$;



Élie Cartan's method of equivalence

THEOREM (*Third fundamental Lie's theorem in Cartan's form*): For a Lie pseudo-group there exists a collection of Maurer–Cartan forms with involutive and compatible structure equations.

THEOREM (*Third inverse fundamental Lie's theorem in Cartan's form*): For a given involutive and compatible system of structure equations there exists a collection of 1-forms $\omega^1, \dots, \omega^n$ and functions U^1, \dots, U^s satisfying this system. The forms $\omega^1, \dots, \omega^m$ are Maurer–Cartan forms of a Lie pseudo-group, and the functions U^1, \dots, U^s are invariants of this pseudo-group.



Élie Cartan's method of equivalence

- É. Cartan. Œuvres Complètes, Paris: Gauthier - Villars, Vol. 2, Part II, 1953
- Vasil'eva M.V. Structure of Infinite Lie Groups of Transformations. Moscow: MSPI, 1972 (in Russian)
- Gardner R.B. The method of equivalence and its applications. CBMS–NSF regional conference series in applied math., SIAM, Philadelphia, 1989.
- Olver P.J. Equivalence, Invariants, and Symmetry. Cambridge: Cambridge University Press, 1995
- Stormark O. Lie's Structural Approach to PDE Systems. Cambridge: CUP, 2000



- Trivial bundle: $\pi: \mathbb{R}^n \times \mathbb{R} \rightarrow \mathbb{R}^n$, $\pi: (x^i, u) \mapsto (x^i)$
- Jets of the second order: $J^2(\pi)$, (x^i, u, u_i, u_{ij}) , $u_{ij} = u_{ji}$
- **Contact forms** : $\vartheta_0 = du - u_j dx^j$, $\vartheta_i = du_i - u_{ij} dx^j$
- Pseudo-group of **contact transformations** $\text{Cont}(J^2(\pi))$:

$$\Psi: J^2(\pi) \rightarrow J^2(\pi), \Psi: (x^i, u, u_i, u_{ij}) \mapsto (\hat{x}^i, \hat{u}, \hat{u}_i, \hat{u}_{ij})$$

such that Ψ preserves the algebraic ideal of contact forms:

$$\Psi^*(d\hat{u} - \hat{u}_j d\hat{x}^j) = a (du - u_j dx^j),$$

$$\Psi^*(d\hat{u}_i - \hat{u}_{ij} d\hat{x}^j) = P_i^j (du_j - u_{jk} dx^k) + Q_i (du - u_j dx^j),$$

$$\Psi^*d\hat{x}^i = b_j^i dx^j + R^i (du - u_j dx^j) + S^{ij} (du_j - u_{jk} dx^k),$$

$$a \neq 0, \det(b_j^i) \neq 0, \det(P_i^j) \neq 0$$



Maurer–Cartan forms for $\text{Cont}(J^2(\pi))$:

$$\Theta_0 = a (du - u_i dx^i),$$

$$\Theta_i = a B_i^j (du_j - u_{jk} dx^k) + g_i \Theta_0,$$

$$\Theta_{ij} = a B_i^k B_j^l (du_{kl} - u_{klm} dx^m) + s_{ij} \Theta_0 + w_{ij}^k \Theta_k,$$

$$\Xi^i = b_j^i dx^j + c^i \Theta_0 + f^{ij} \Theta_j,$$

where $a \neq 0$, $\det(b_j^i) \neq 0$, $b_k^i B_j^k = \delta_j^i$, $f^{ik} = f^{ki}$,

$s_{ij} = s_{ji}$, $w_{ij}^k = w_{ji}^k$, $u_{klm} = u_{lkm} = u_{kml}$

Structure equations

$$d\Theta_0 = \Phi_0^0 \wedge \Theta_0 + \Xi^i \wedge \Theta_i,$$

$$d\Theta_i = \Phi_i^0 \wedge \Theta_0 + \Phi_i^k \wedge \Theta_k + \Xi^k \wedge \Theta_{ik},$$

$$d\Theta_{ij} = \Phi_{ij}^k \wedge \Theta_{kj} - \Phi_{ij}^0 \wedge \Theta_{ij} + \Upsilon_{ij}^0 \wedge \Theta_0 + \Upsilon_{ij}^k \wedge \Theta_k + \Xi^k \wedge \Theta_{ijk},$$

$$d\Xi^i = \Phi_0^0 \wedge \Xi^i - \Phi_k^i \wedge \Xi^k + \Psi^{i0} \wedge \Theta_0 + \Psi^{ik} \wedge \Theta_k$$



Symmetry pseudo-groups of PDEs

- PDE of the second order: $\iota : \mathcal{E} \rightarrow J^2(\pi)$
- **Contact symmetries** of \mathcal{E} — contact transformations which map \mathcal{E} into itself: $\text{Cont}(\mathcal{E}) \subset \text{Cont}(J^2(\pi))$,
- **Maurer–Cartan forms for $\text{Cont}(\mathcal{E})$ can be found from the reduced forms $\theta_0 = \iota^* \Theta_0$, $\theta_i = \iota^* \Theta_i$, $\theta_{ij} = \iota^* \Theta_{ij}$, $\xi^i = \iota^* \Xi^i$, by procedures of Cartan’s equivalence method**
- Details:
 - Fels M., Olver P.J. Moving coframes I. A practical algorithm. // Acta Appl. Math., 1998, Vol. 51, pp. 161–213
 - Morozov O.I. Moving coframes and symmetries of differential equations. // J. Phys. A: Math. Gen., 2002, Vol. 35, pp. 2965 – 2977



Coverings of differential equations

Coverings (Lax pairs, Bäcklund transformations, prolongation structures, zero - curvature representations, integrable extensions, ...):

- Lax P.D. // Comm. Pure Appl. Math., 1969, Vol. 21, pp. 467 – 490
- V.E. Zakharov, A.B. Shabat. // Funct. Analysis Appl. 1974, Vol. 6, No 6, pp. 43 – 54
- H.D. Wahlquist, F.B. Estabrook, 1975, // J. Math. Phys., 1975, Vol. 16, pp. 1 – 7
- I.S. Krasil'shchik, A.M. Vinogradov, // Acta Appl. Math., 1984, Vol. 2, pp. 79–86
- I.S. Krasil'shchik, A.M. Vinogradov // Acta Appl. Math., 1989, Vol. 15, pp. 161–209



Coverings of differential equations

- Infinite jet bundle $J^\infty(\pi)$,
- Coordinates $(x^i, u, u_i, u_{ij}, \dots, u_I, \dots)$, $I = (i_1, i_2, \dots, i_m)$,
- Infinitely prolonged differential equation

$$\mathcal{E}^\infty \subset J^\infty(\pi),$$

- Total derivatives

$$D_i = \frac{\partial}{\partial x^i} + \sum_{\#I \geq 0} u_{Ii} \frac{\partial}{\partial u_I}, \quad \bar{D}_i = D_i|_{\mathcal{E}^\infty}.$$



Coverings of differential equations

- **Covering** over \mathcal{E}^∞ :

$$\tau : \tilde{\mathcal{E}}^\infty = \mathcal{E}^\infty \times \mathcal{V} \rightarrow \mathcal{E}^\infty, \quad \mathcal{V} = \{(v^\kappa) \mid 0 \leq \kappa \leq \infty\},$$

- **Extended total derivatives**

$$\tilde{D}_i = \bar{D}_i + \sum_{\kappa} T_i^\kappa(x^j, u_I, v^\rho) \frac{\partial}{\partial v^\kappa},$$

$$[\tilde{D}_i, \tilde{D}_j] = 0 \iff (x^i, u_I) \in \mathcal{E}^\infty$$

- **Extended contact forms (Wahlquist-Estabrook forms)**

$$\tilde{\vartheta}^\kappa = dv^\kappa - T_i^\kappa(x^j, u_I, v^\rho) dx^i$$



Coverings of differential equations

The problem of recognizing whether a given differential equation has a covering is of great importance. Different techniques were proposed to solve it.

$n = 2$.

- H.D. Wahlquist, F.B. Estabrook, 1975
- R. Dodd, A. Fordy, 1983
- C. Hoenselaers, 1986
- S.Yu. Sakovich, 1995
- M. Marvan, 1997
- S. Igonin, 2006
- ...



Coverings of differential equations

The problem is much more difficult in the case of $n > 2$:

- G.M. Kuz'mina, 1967
- H.C. Morris, 1976
- V.E. Zakharov, 1982
- G.S. Tondo, 1985
- M. Marvan, 1992
- B.K. Harrison, 2002
- ...



Coverings of differential equations

G.M. Kuz'mina. On a possibility to reduce a system of two partial differential equations of the first order to a single equation of the second order. // Proc. Moscow State Pedagogical Institute, 1967, Vol. 271, 67–76 (in Russian)

$$u_{yy} = u_{tx} + u u_{xx} + u_x^2 \quad (\text{dispersionless KP})$$

Covering

$$\begin{cases} v_t = (v^2 - u) v_x - u_y - v u_x, \\ v_y = v v_x - u_x \end{cases}$$

Excluding u : define w such that $w_x = v$ and $w_y = \frac{1}{2} v^2 - u$, then

$$w_{yy} = w_{tx} + \left(\frac{1}{2} w_x^2 - w_y\right) w_{xx} \quad (\text{modified dKP})$$

The central idea: **to apply Cartan's structure theory of Lie pseudo-groups**



Bryant R.L., Griffiths P.A. Characteristic Cohomology of Differential Systems (II): Conservation Laws for a Class of Parabolic Equations. Duke Math. J., 1995, Vol. 78, pp. 531–676:

$n = 2$, finite-dimensional coverings



Definition 1. Let

$$d\omega^i = A_{\alpha j}^i \pi^\alpha \wedge \omega^j + B_{jk}^i \omega^j \wedge \omega^k, \quad (1)$$

$$dU^\kappa = C_j^\kappa \omega^j \quad (2)$$

be structure equations of a Lie pseudo-group \mathfrak{G} . Its coefficients are supposed to be functions of the invariants U^σ of \mathfrak{G} . Consider the system

$$\begin{aligned} d\tau^q = & D_{\rho r}^q \eta^\rho \wedge \tau^r + E_{rs}^q \tau^r \wedge \tau^s + F_{r\beta}^q \tau^r \wedge \pi^\beta \\ & + G_{rj}^q \tau^r \wedge \omega^j + H_{\beta j}^q \pi^\beta \wedge \omega^j + I_{jk}^q \omega^j \wedge \omega^k, \end{aligned} \quad (3)$$

$$dV^\epsilon = J_j^\epsilon \omega^j + K_q^\epsilon \tau^q, \quad (4)$$



Integrable extensions

with unknown 1-forms τ^q , $q \in \{1, \dots, Q\}$, η^ρ , $\rho \in \{1, \dots, R\}$, and unknown functions V^ϵ , $\epsilon \in \{1, \dots, S\}$, $Q, R, S \in \mathbb{N}$. The coefficients of this system are supposed to be functions of U^σ and V^ϵ . System (3), (4) is called an **integrable extension** of system (1), (2), if equations (1) – (4) are simultaneously compatible and involutive.

Suppose system (3), (4) is an integrable extension of system (1), (2). Then, in accordance with the third inverse fundamental theorem of Lie, system (1)–(4) defines a Lie pseudo-group \mathfrak{H} .



Definition 2. The integrable extension (3), (4) is called **trivial** , if there exists a change of variables on the manifold of action of the pseudo-group \mathfrak{H} such that in the new variables equations (3), (4) do not contain the forms ω^j , π^β , and the coefficients of (3), (4) do not depend on U^q . Otherwise, the integrable extension is called **non-trivial** .

Let θ_K^α , ξ^j be Maurer–Cartan forms of the pseudo-group $\text{Cont}(\mathcal{E})$ of symmetries for a PDE \mathcal{E} such that θ_K^α are contact forms (their restrictions on each solution of the equation \mathcal{E} are equal to 0), and ξ^j are horizontal forms ($\xi^1 \wedge \dots \wedge \xi^n \neq 0$ on each solution).



Definition 3. Nontrivial integrable extension of the structure equations of the pseudo-group $\text{Cont}(\mathcal{E})$

$$d\omega^q = \Pi_r^q \wedge \omega^r + \xi^j \wedge \Omega_j^q$$

is called **contact integrable extension** when

- $\Omega_j^q \equiv 0 \pmod{\theta_K^\alpha, \omega_j^q}$ for a set of additional forms ω_j^q ;
- $\Omega_j^q \not\equiv 0 \pmod{\omega_j^q}$
- coefficients of expansions of Ω_j^q w.r.t. $\{\theta_I^\alpha, \omega_i^r\}$ and Π_r^q w.r.t. $\{\theta_I^\alpha, \xi^j, \omega^r, \omega_i^r\}$ depend on the invariants of $\text{Cont}(\mathcal{E})$ and, maybe, on a set of additional functions W^ρ , $\rho \in \{1, \dots, \Lambda\}$, $\Lambda \geq 1$.
- In the latter case there exist functions $P_\alpha^{I\rho}, Q_q^\rho, R_q^{j\rho}, S_j^\rho$ such that

$$dW^\rho = P_\alpha^{I\rho} \theta_I^\alpha + Q_q^\rho \omega^q + R_q^{j\rho} \omega_j^q + S_j^\rho \xi^j.$$

These equations are required to satisfy the compatibility conditions.



Plebański's second heavenly equation

The second heavenly equation (J.F. Plebański, J. Math. Phys., 1975, Vol. 16, pp. 2395 – 2402):

$$u_{xz} = u_{ty} + u_{yy} u_{zz} - u_{yz}^2$$

Covering:

$$\begin{cases} v_t = (u_{yz} + \lambda) v_z - u_{zz} v_y, \\ v_x = u_{yy} v_z - (u_{yz} - \lambda) v_y \end{cases}$$

- J.F. Plebański, *ibid*
- Viqar Husain, Phys. Rev. Lett., 1994, Vol. 72, pp. 800–803
- L.V. Bogdanov, B.G. Konopelchenko, Phys. Lett. A, 2005, Vol. 345, pp. 137–143



Plebański's second heavenly equation

THEOREM. The symmetry pseudo-group of the second heavenly equation has two contact integrable extensions with the following Wahlquist–Estabrook forms:

$$\omega_1 = q_1 (dv + (v_{zz} v_y - (u_{yz} + \lambda) v_z) dt \\ + ((u_{yz} - \lambda) v_y - u_{yy} v_z) dx - v_y dy - v_z dz),$$

with $\lambda = \text{const}$ and

$$\omega_2 = q_2 (dv + (v_{zz} v_y - (u_{yz} + v) v_z) dt \\ + ((u_{yz} - v) v_y - u_{yy} v_z) dx - v_y dy - v_z dz),$$



Plebański's second heavenly equation

The first form corresponds to the known covering of the second heavenly equation, while the second form gives its new covering

$$\begin{cases} v_t &= (u_{yz} + v) v_z - u_{zz} v_y, \\ v_x &= u_{yy} v_z - (u_{yz} - v) v_y \end{cases}$$

Details:

- O.I. Morozov, Global and Stochastic Analysis, 2011, Vol.1, pp. 89 – 102 (arXiv : 1104.3011)



Generalized (2+1)-dDym equation

$$u_{ty} = u_y u_{xx} + 2(2\kappa + 1) u_x u_{xy} + u_y^{8\kappa+5} u_{yy}$$

- $\kappa = -\frac{1}{2}$:
 - E.V. Ferapontov, K.R. Khusnutdinova, Comm. Math. Phys., 2004, Vol. 248, pp. 187 – 206
 - V.S. Dryuma, 2007
 - E.V. Ferapontov, A. Moro, V.V. Sokolov, Comm. Math. Phys., 2009, Vol. 285, pp. 31 – 65
- $\kappa = 0$:
 - E.V. Ferapontov, A.V. Odesskii, N.M. Stoilov, arXiv:1007.3782
- $\kappa = -\frac{5}{8}$:
 - O.I. Morozov, J. Geom. Phys., 2009, Vol. 59, pp. 1461 – 1475



Generalized (2+1)-dDym equation

THEOREM. When $\kappa \notin \{-\frac{5}{8}, -\frac{3}{4}, -\frac{1}{2}\}$, the symmetry pseudo-group of the generalized (2+1)-dDym equation has two contact integrable extensions with the Wahlquist–Estabrook forms

$$\omega_0 = \frac{u_{xy}}{u_y^{4\kappa+3} v_y} \left(dv - \lambda u_y^{4\kappa+2} v_y dx - v_y dy \right. \\ \left. - 2(2\kappa + 1) u_y^{4\kappa+2} v_y (\lambda u_x - (4\kappa + 3)^{-1} u_y^{4\kappa+3}) dt \right)$$

and

$$\omega_0 = \frac{u_{xy}}{u_y^{4\kappa+3} H^{2\kappa+1}} \left(dw - u_y^{4\kappa+2} H^{2\kappa+1} dx - w_y dy \right. \\ \left. - H^{2\kappa+1} u_y^{4\kappa+2} (\alpha u_x + \beta u_y^{4\kappa+3} H^{2\kappa} H') dt \right),$$



Generalized (2+1)-dDym equation

where the function $H = H(w_y)$ is a solution of the ODE

$$H' = (2\kappa + 1)^{-1} H^{-2\kappa} \sqrt{H + \lambda^2},$$

while $\alpha = 2(2\kappa + 1)$, $\beta = 2(2\kappa + 1)^2(8\kappa + 5)^{-1}$, and $\lambda^2 = -(8\kappa + 5)(4\kappa + 3)^{-1}$.

When $\kappa = -\frac{3}{4}$, the symmetry pseudo-group of the generalized (2+1)-dDym equation has a contact integrable extension with the Wahlquist–Estabrook form

$$\omega_0 = u_{xy} G' \left(dw - \frac{1}{u_y G'} (dx + (G - u_x) dt) - w_y dy \right),$$

where the function $G = G(w_y)$ is a solution of the following ODE:

$$G' = \exp\left(\frac{1}{2} G^2\right).$$



Generalized (2+1)-dDym equation

The corresponding coverings are defined by the systems

$$\begin{cases} v_t &= 2(2\kappa + 1) u_y^{4\kappa+2} v_y (\lambda u_x - (4\kappa + 3)^{-1} u_y^{4\kappa+3}), \\ v_x &= \lambda u_y^{4\kappa+2} v_y, \end{cases}$$

$$\begin{cases} w_t &= H^{2\kappa+1} u_y^{4\kappa+2} (\alpha u_x + \beta u_y^{4\kappa+3} H^{2\kappa} H'), \\ w_x &= u_y^{4\kappa+2} H^{2\kappa+1}, \end{cases}$$

when $\kappa \notin \{-\frac{5}{8}, -\frac{3}{4}, -\frac{1}{2}\}$ and

$$\begin{cases} w_t &= \frac{G - u_x}{u_y G'}, \\ w_x &= \frac{1}{u_y G'}, \end{cases}$$

when $\kappa = -\frac{3}{4}$.



Generalized (2+1)-dDym equation

These systems define Bäcklund transformations from the generalized (2+1)-dDym equation to the equations

$$v_{ty} = \left(\frac{v_x}{\lambda v_y} \right)^{\frac{1}{4\kappa+2}} v_{xx} + \left(\frac{v_x}{\lambda v_y} \right)^{\frac{8\kappa+5}{4\kappa+2}} v_{yy} + \left(\frac{v_t}{v_x} + \lambda^{-\frac{6\kappa+4}{2\kappa+1}} \frac{4\kappa-2}{4\kappa+3} \left(\frac{v_x}{\lambda v_y} \right)^{\frac{4\kappa+3}{4\kappa+2}} \right) v_{xy},$$

$$w_{ty} = H^{-\frac{1}{2}} w_x^{\frac{1}{4\kappa+2}} w_{xx} + w_x^{\frac{8\kappa+5}{4\kappa+2}} H^{-\frac{8\kappa+5}{2}} w_{yy} + \left(\frac{w_t}{w_x} - \frac{4\kappa+2}{8\kappa+5} w_x^{\frac{4\kappa+3}{4\kappa+2}} H^{-\frac{4\kappa+3}{2}} (H + \lambda^2)^{\frac{1}{2}} \right) w_{xy},$$

and

$$w_{ty} = \frac{1}{w_x \exp\left(\frac{1}{2} G^2\right)} w_{xx} + \frac{w_t + w_x^2}{w_x} w_{xy} + w_x \exp\left(\frac{1}{2} G^2\right) w_{yy}.$$

