

Structure preserving discretizations of the Liouville equation

L. Martina

Dip. Matematica e Fisica "Ennio De Giorgi" - Università del Salento,
Sezione INFN, Lecce, Italy



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Aims

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- ① How symmetry structure in PDEs can be preserved in P Δ E s ;
- ② Compare three different structure preserving procedures of discretization for the Liouville equation (as prototype):
 - maximal finite subgroup of the point symmetry group,
 - infinite point-symmetry group as discrete higher symmetries ,
 - linearizability .
- ③ Geometric integration: focus on preserved geometrical properties under discretization addressed to numerical solutions.

References

-  D Levi, L Martina and P Winternitz: *Lie-point symmetries of the discrete Liouville equation*, J. Phys A: Math. Theor. **48**, 2 (2015) 025204.
-  D Levi, L Martina and P Winternitz: *Structure Preserving Discretizations of the Liouville Equation and their Numerical Tests*, SIGMA **11** (2015), 080

Outline

- 1 Motivations
- 2 Liouville Equation
- 3 Invariant discretization
- 4 Numerical experiments
- 5 Conclusions

Motivations

Point-Symmetry preserving discretization

-  Dorodnitsyn V A 1991 *J. Soviet Math.* **55** 1490–1517; Dorodnitsyn V A 2011 , CRC Press; Dorodnitsyn V A, Kozlov R and Winternitz P 2000, *J. Math. Phys.* **41** 480–504.
-  Winternitz P 2004, **644** of Lecture Notes in Physics pp 185–243, B. Grammaticos, et al., nlin.SI/0309058; Winternitz P 2011, LMS Lecture Series, Ed.s Levi, Olver, Thomova, Winternitz;
-  Levi D and Winternitz P 1991 *Phys. Lett. A* **152** 335–338; Levi D and Winternitz P 1996 *J.Math. Phys.* **37** 5551–5576; Levi D and Winternitz P 2006 *J. Phys. A* **39**, no. 2, R1-R63

Motivations

Implementation on ODEs

-  Bourlioux A, Rebelo R and Winternitz P 2008 *J. Nonlinear Math. Phys.* **15** 362–372; Bourlioux A, Cyr-Gagnon C and Winternitz P 2006 *J.Phys. A* **39** 6877–6896;

Implementation on PDEs

-  F Valiquette and P Winternitz, 2005 *J.Phys. A* **39** 9765;
-  Levi D and Rodriguez M A 2014 *arXiv:1407.0838*;
-  Bihlo A and Popovych R O 2012 , *SIAM J. Sci. Comput.* **34** B810–B839.; Bihlo A and Nave J C 2013 , *SIGMA* **9**; Bihlo A 2013 *J. Phys. A: Math. Theor.* **46** 062001; Bihlo A, Coiteux-Roy X and Winternitz P 2014, *arXiv:1409.4340*.

A toy model: the Liouville Equation

The Liouville equation

$$z_{xy} = e^z.$$

Constant Curvature surfaces

sl(2) reduction of the **2-dim Toda lattice** $\partial\bar{\partial}z_j = \sum_i^\ell \beta \alpha_i \cdot j \exp [\beta \alpha_i \cdot z]$

A.V. Mikhailov JETP Lett. (1979)

$$U_{xy} = \Phi(U, U_x, U_y) \quad U_t = f(U, U_x, U_{xx}, \dots), \quad U_{t'} = g(U, U_y, U_{yy}, \dots)$$

S.I. Svinolupov, V.V. Sokolov, Fun. Appl. (1982)

$$\text{Algebraic form} \quad u u_{xy} - u_x u_y = u^3, \quad u = e^z.$$

Linearizability

$$u = 2 \frac{\phi_x \phi_y}{\phi^2}, \quad \phi_{xy} = 0 \quad (\text{B. T.})$$

$$\phi(x, y) = \psi(x) + \chi(y) \quad \Rightarrow \quad z = \ln \left(2 \frac{\psi_x \chi_y}{(\psi + \chi)^2} \right)$$

The Point Symmetry Group

∞ -dim Lie point symmetry algebra (Medolaghi, 1898)

$$X(f(x)) = f(x) \partial_x - f_x(x) u \partial_u,$$

$$Y(g(y)) = g(y) \partial_y - g_y(y) u \partial_u \quad \forall f, g \text{ smooth f.s}$$

$$[X(f), X(\tilde{f})] = X\left(f_x \tilde{f} - f \tilde{f}_x\right), \quad [Y(g), Y(\tilde{g})] = Y\left(g \tilde{g}_y - \tilde{g} g_y\right), \quad [X(f), Y(g)] = 0.$$

$$L = vir_x \oplus vir_y$$

$$\tilde{u}(\tilde{x}, \tilde{y}) = u(x(\tilde{x}), y(\tilde{y})) x_{\tilde{x}} y_{\tilde{y}}, \quad f(\tilde{x}) x_{\tilde{x}} = f(x), \quad g(\tilde{y}) y_{\tilde{y}} = g(y)$$

Maximal finite subalgebra

$$sl_x(2, \mathbb{R}) \oplus sl_y(2, \mathbb{R}) \subset L$$

$$f, g \in \mathcal{P}_2$$

Invariants of $SL_x(2, \mathbb{R}) \otimes SL_y(2, \mathbb{R})$

A basis of 2^o order "strong" invariants $I(x, y, u, u_x, u_y, u_{xx}, u_{xy}, u_{yy})$

$$I_1 = \frac{uu_{xy} - u_x u_y}{u^3}, \quad I_2 = \frac{(2uu_{xx} - 3u_x^2)(2uu_{yy} - 3u_y^2)}{u^6}$$

$$\text{pr}^{(2)} X(f) I_1 = \text{pr}^{(2)} Y(g) I_1 = 0 \quad \forall f, g$$

\Rightarrow $VIR(x) \otimes VIR(y)$ – Invariant

$$\text{pr}^{(2)} X(f) I_2 = \frac{2f_{xxx}(3u_y^2 - 2uu_{yy})}{u^4}, \quad \text{pr}^{(2)} Y(g) I_2 = \frac{2g_{yyy}(3u_x^2 - 2uu_{xx})}{u^4}$$

$$\Rightarrow f_{xxx} = g_{yyy} = 0$$

The symmetry preserving discretization

Idea:

- Replace a given **PDE** by a **system of difference equations** formed out of invariants of the action of **its** point symmetry group on a **stencil**.
- The difference system describes **both** a **lattice** and the **PΔE**
- In the continuous limit

$$\text{the lattice eq.} \rightarrow \text{identity}, \quad P\Delta E \rightarrow \text{PDE}$$

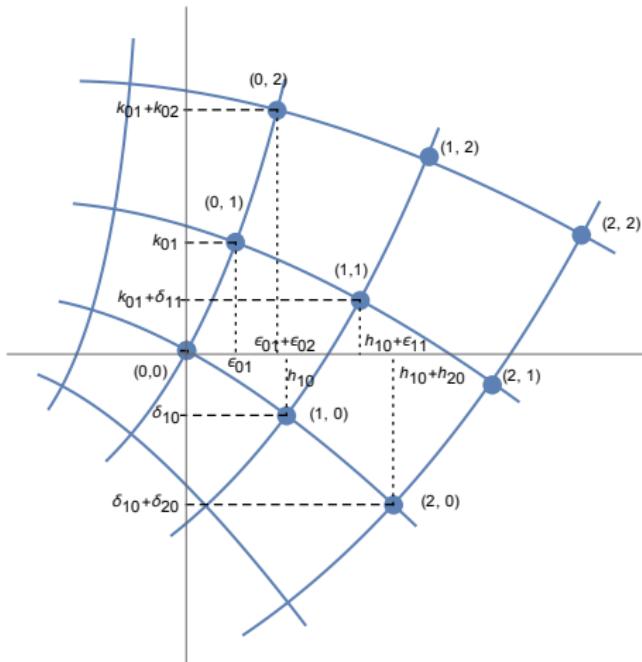
Given a PDE

$$F(x, y, u, u_x, u_y, u_{xx}, u_{xy}, u_{yy}, \dots) = 0 \Rightarrow \mathcal{L} \text{ (Lie symmetry alg.)}$$

PΔE

$$\begin{aligned} \mathcal{L} \Rightarrow E_\alpha(x_{m+i,n+j}, y_{m+i,n+j}, u_{m+i,n+j}) &= 0, \\ \alpha = 1, \dots, l, \quad i_{min} \leq i \leq i_{max}, \quad j_{min} \leq j \leq j_{max}. \end{aligned}$$

A **Stencil** = $\{N \text{ adjacent points } \in \mathbb{R}^2\}$ in the limit sufficient to reproduce all derivatives in PDE $\Rightarrow |i_{max} - i_{min}|$ and $|j_{max} - j_{min}|$.



2nd order PDE \Rightarrow 6-point stencil : $\{(0,0), (1,0), (0,1), (1,1), (2,0), (0,2)\}$

$$u_{xy} = F(x, y, u, u_x, u_y)$$

not involving $u_{xx}, u_{yy} \rightarrow$ **4-points**: $s_4^0 \equiv \{(0,0), (1,0), (0,1), (1,1)\}$.

Invariant discretization on 4-points

$$Z \in \mathcal{L} : \quad Z = \xi(x, y, u) \partial_x + \eta(x, y, u) \partial_y + \phi(x, y, u) \partial_u$$

Prolongation on the lattice: consider the action of the vector field \hat{Z} at some reference point $\{x_{0,0}, y_{0,0}, u_{0,0}\}$ and apply it to all points figuring on the stencil:

$$\text{pr}Z = \sum_{i,j} (\xi_{i,j} \partial_{x_{i,j}} + \eta_{i,j} \partial_{y_{i,j}} + \phi_{i,j} \partial_{u_{i,j}}).$$

$$X^D(f) = \text{pr } X(f) = \sum_{(m,n) \in \mathbb{S}_4^0} [f(x_{m,n}) \partial_{x_{mn}} - f'(x_{m,n}) u_{mn} \partial_{u_{mn}}],$$

$$Y^D(g) = \text{pr } Y(g) = \sum_{(m,n) \in \mathbb{S}_4^0} [g(y_{m,n}) \partial_{y_{mn}} - g'(y_{m,n}) u_{mn} \partial_{u_{mn}}].$$

Strong invariants $X^D(f) I(x_{ij}, y_{ij}, u_{ij}) = 0, Y^D(g) I(x_{ij}, y_{ij}, u_{ij}) = 0.$
 $f = 1, x, x^2$ $g = 1, y, y^2$

6 functionally independent invariants on $SL_x(2) \otimes SL_y(2)$:

$$\xi_1 = \frac{(x_{0,1} - x_{0,0})(x_{1,1} - x_{1,0})}{(x_{0,0} - x_{1,0})(x_{0,1} - x_{1,1})} = \frac{\epsilon_{0,1}\epsilon_{1,1}}{h_{1,0}(h_{1,0} + \epsilon_{1,1} - \epsilon_{0,1})},$$

$$\eta_1 = \frac{(y_{0,0} - y_{1,0})(y_{0,1} - y_{1,1})}{(y_{0,1} - y_{0,0})(y_{1,1} - y_{1,0})} = \frac{\delta_{1,0}\delta_{1,1}}{k_{0,1}(k_{0,1} + \delta_{1,1} - \delta_{1,0})}$$

$$H_1 = u_{0,0} \ u_{0,1} \ \epsilon_{0,1}^2 \ k_{0,1}^2$$

$$H_2 = u_{1,0} \ u_{1,1} \ \epsilon_{1,1}^2 \ (k_{0,1} + \delta_{1,1} - \delta_{1,0})^2$$

$$H_3 = \frac{u_{1,0} \ (h_{1,0} - \epsilon_{0,1})^2 \ (k_{0,1} - \delta_{1,0})^2}{u_{0,0} \ \epsilon_{0,1}^2 \ k_{0,1}^2}$$

$$H_4 = \frac{u_{1,1} \ \epsilon_{1,1}^2 \ (k_{0,1} + \delta_{1,1} - \delta_{1,0})^2}{u_{0,0} \ h_{1,0}^2 \ \delta_{1,0}^2}$$

Invariant lattice: $\xi_1 = A, \eta_1 = B$

Invariant orthogonal lattice

$$\xi_1 = 0, \eta_1 = 0 \iff x_{m,n} = x_m, y_{m,n} = y_n.$$

Checking the invariance on $VIR(x) \otimes VIR(y)$

$$\begin{aligned} \hat{X}^D(x^3)\xi_1 &= (x_{1,1} - x_{0,0})(x_{1,0} - x_{0,1})\xi_1|_{\xi_1=0} = 0 \\ &\quad \Downarrow \\ \forall n \quad \hat{X}^D(x^n)\xi_1|_{\xi_1=0} &= 0 \end{aligned} \tag{1}$$

The orthogonal lattice $\xi_1 = 0, \eta_1 = 0$ is the only $VIR(x) \otimes VIR(y)$ invariant lattice.

The invariants H_1, \dots, H_4 all vanish or become infinite on $\xi_1 = 0, \eta_1 = 0$.
 The only **finite** $SL_x(2) \otimes SL_y(2)$ -invariants

$$J_1 = H_1 H_3 = u_{0,1} u_{1,0} h_{1,0}^2 k_{0,1}^2, \quad (2)$$

$$J_2 = \frac{1}{\xi_1^2} \frac{H_2}{H_3} = u_{0,0} u_{1,1} h_{1,0}^2 k_{0,1}^2. \quad (3)$$

No Virasoro - invariants

$$\hat{X}^D(x^3) J_1 = -h_{1,0}^2 J_1, \quad \hat{X}^D(x^3) J_2 = -h_{1,0}^2 J_2.$$

$J_2 - J_1$ is a weak Virasoro invariant \Rightarrow Wave equation

Expanding u in Taylor series on the lattice

$$J_2 - J_1 = h_{1,0}^3 k_{0,1}^3 (uu_{xy} - u_x u_y).$$

The **Liouville equation** is approximated by the $SL_x(2) \otimes SL_y(2)$ invariant difference scheme

$$\begin{aligned} J_2 - J_1 &= a \operatorname{sign}(J_1) |J_1|^{3/2} + b \operatorname{sign}(J_2) J_1 |J_2|^{1/2} \\ &+ c \operatorname{sign}(J_1) |J_1|^{1/2} J_2 + d \operatorname{sign}(J_1) |J_2|^{3/2}, \quad (a + b + c + d = 1) \\ \xi_1 &= 0, \quad \eta_1 = 0, \end{aligned}$$

$$\begin{aligned} \lim_{h,k \rightarrow 0} \frac{1}{h^3 k^3} \{ J_2 - J_1 - [a|J_1|^{3/2} + bJ_1|J_2|^{1/2} + c|J_1|^{1/2} J_2 + d|J_2|^{3/2}] \} &= \\ &= [uu_{xy} - u_x u_y - u^3][1 + \mathcal{O}(h, k)] \end{aligned}$$

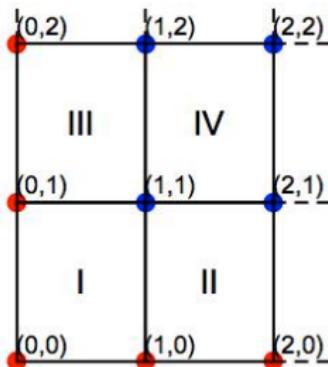
Recurrence formula

$$b = d = 0, c = 1 - a, \quad a \in \mathbb{R}$$

$$\begin{aligned} u_{m+1,n+1} &= \frac{u_{m,n+1} u_{m+1,n}}{u_{m,n}} A_{m,n+1;m+1,n}, \\ A_{m,n+1;m+1,n} &= \frac{1 + a h k \operatorname{sign}(u_{m+1,n} u_{m,n+1}) \sqrt{|u_{m,n+1} u_{m+1,n}|}}{1 + (a - 1) h k \operatorname{sign}(u_{m+1,n} u_{m,n+1}) \sqrt{|u_{m,n+1} u_{m+1,n}|}}. \end{aligned}$$

$$\begin{array}{lll} u_{m_0,0} = 0 & u_{m_0+1,n} &= u_{m_0+1,n-1} \frac{u_{m_0-1,n}}{u_{m_0-1,n-1}} \\ u_{0,n_0} = 0 & u_{m,n_0+1} &= u_{m-1,n_0+1} \frac{u_{m,n_0-1}}{u_{m-1,n_0-1}} \\ u_{0,n_0} = u_{m_0,0} = 0 & u_{m_0+1,n_0+1} &= u_{m_0-1,n_0+1} \frac{u_{m_0+1,n_0-1}}{u_{m_0-1,n_0-1}} \end{array}$$

The 9-point - stencil



$$\begin{aligned}
 J_1 &= u_{01}u_{10}h^2k^2, & J_2 &= u_{00}u_{11}h^2k^2, \\
 J_3 &= u_{11}u_{20}h^2k^2, & J_4 &= u_{10}u_{21}h^2k^2, \\
 J_5 &= u_{11}u_{02}h^2k^2, & J_6 &= u_{01}u_{12}h^2k^2, \\
 J_7 &= u_{12}u_{21}h^2k^2, & J_8 &= u_{11}u_{22}h^2k^2.
 \end{aligned}$$

$$J_4 J_6 = J_1 J_7$$

$$J_2 - J_1 = J_4 - J_3 = J_6 - J_5 = J_8 - J_7 = h^3 k^3 (u u_{xy} - u_x u_y) [1 + \mathcal{O}(h, k)]$$

$$\begin{aligned} \alpha[4(J_2 - J_1) - (J_6 - J_5 + J_4 - J_3)] + \beta[4(J_8 - J_7) - 3(J_6 - J_5 + J_4 - J_3)] \\ = 2h^3 k^3 (u u_{xy} - u_x u_y) (\alpha - \beta) [1 + \mathcal{O}(h^2, h k, k^2)] \end{aligned}$$

$$\begin{aligned} 2\alpha[4A_3 - 2A_1 - (A_4 + A_5)] + 2\beta[4A_6 + 2A_1 - 3(A_4 + A_5)] = \\ = \sum_{a,b=1}^6 \gamma_{a,b} A_a \sqrt{|A_b|}, \quad \sum_{a,b=1}^6 \gamma_{a,b} = 2(\alpha - \beta). \end{aligned}$$

$$A_1 = \frac{1}{2} (3J_1 - J_8), A_2 = \frac{1}{2} (J_1 + J_4 + J_6 - 2J_8), A_3 = \cdot$$

$$u_{22} \leftrightarrow J_8 \\ I)$$

$$J_8 = J_7 + 3(J_2 - J_1) - \frac{1}{\sqrt{2}}(3J_1 - J_7)\sqrt{|3J_1 - J_7|}$$

$$u_{22} = \frac{1}{u_{11}}[u_{12}u_{21} + 3(u_{11}u_{00} - u_{10}u_{01}) \\ - \frac{1}{\sqrt{2}}hk(3u_{01}u_{10} - u_{12}u_{21})\sqrt{|3u_{01}u_{10} - u_{12}u_{21}|}]$$

II)

$$J_8 = \frac{J_7 + 3(J_2 - J_1) - \frac{3}{\sqrt{2}}J_1 \operatorname{sign}(3J_1 - J_7)\sqrt{|3J_1 - J_7|}}{1 - \frac{1}{\sqrt{2}}\operatorname{sign}(3J_1 - J_7)\sqrt{|3J_1 - J_7|}}$$

$$u_{22} = \{u_{12}u_{21} + 3(u_{11}u_{00} - u_{10}u_{01}) -$$

$$\frac{3}{\sqrt{2}}hku_{01}u_{10}\operatorname{sign}(3u_{01}u_{10} - u_{12}u_{21})\sqrt{|3u_{01}u_{10} - u_{12}u_{21}|}\}$$

$$\{u_{11}[1 - \frac{hk}{\sqrt{2}}\operatorname{sign}(3u_{01}u_{10} - u_{12}u_{21})\sqrt{|3u_{01}u_{10} - u_{12}u_{21}|}]\}^{-1}$$

- 7 points involved.
- Boundary conditions;
- Numerical instabilities close to zeroes.

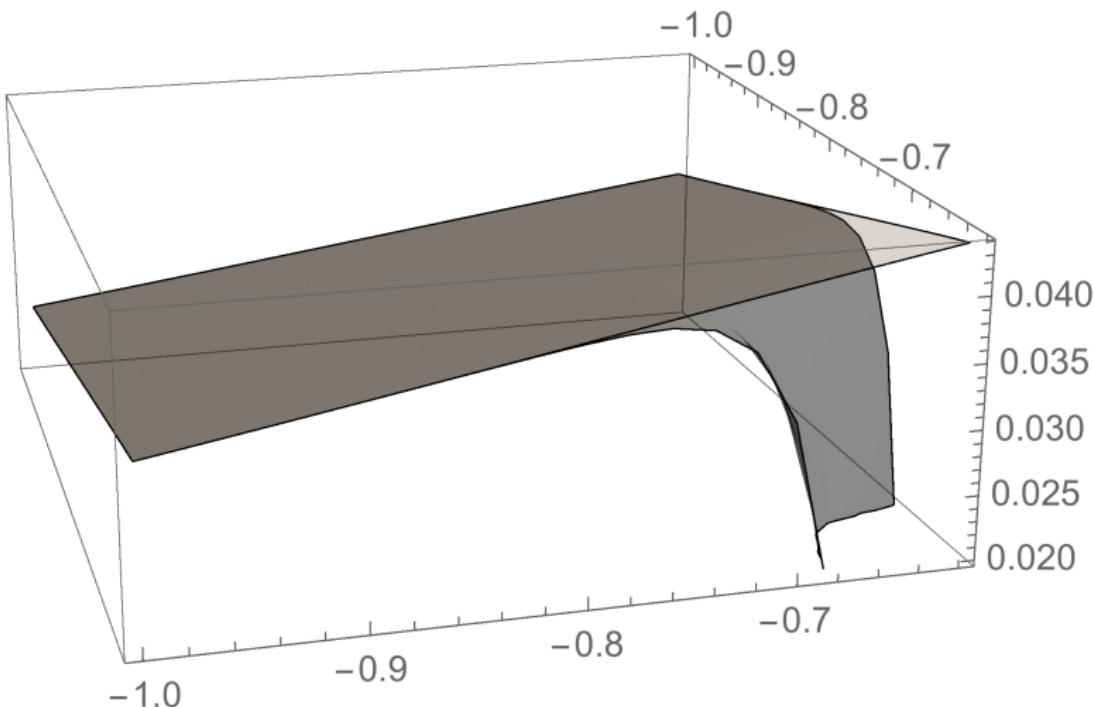


Figure : The 4- point (light) and 7-point (dark) recursion for the solution $f_1 = 2\{(x^2 + 1)(y^2 + 1)(\tan^{-1}(x) + \tan^{-1}(y) + 6)^2\}_{-1}$. Steps $h = k = 0.02$ on a grid 20×20 .

Discrete Integrability

Adler, Startsev *Theor. Math. Phys.* **121** (1999)

discretization of the algebraic Liouville equation on a 4-point lattice

$$u_{i+1,j+1} \left(1 + \frac{1}{u_{i+1,j}}\right) \left(1 + \frac{1}{u_{i,j+1}}\right) u_{i,j} = 1.$$

Linearizable via

$$u_{i,j} = -\frac{(v_{i+1,j} - v_{i,j})(v_{i,j+1} - v_{i,j})}{v_{i+1,j} v_{i,j+1}}, \quad v_{i+1,j+1} - v_{i+1,j} - v_{i,j+1} + v_{i,j} = 0.$$

General solution

$$u_{i,j} = -\frac{(c_{i+1} - c_i)(k_{j+1} - k_j)}{(c_{i+1} + k_j)(c_i + k_{j+1})} \quad \forall c_i, k_j$$

It has **NO** continuous point symmetries. Generalized symmetries.

$$c_{m+1} = \phi_1(x) + h \frac{d\phi_1}{dx} + \mathcal{O}(h^2), \quad k_{n+1} = \phi_2(y) + k \frac{d\phi_2}{dy} + \mathcal{O}(k^2)$$

$$u_{m,n} = -hk \frac{\phi_{1,x}\phi_{2,y}}{(\phi_1 + \phi_2)^2} + \mathcal{O}(h^3, h^2k, hk^2, k^3)$$

The invariant discretization by the pseudo-group approach

Alternative symmetry preserving discretization R. Rebello and F. Valiquette (2014)

The **entire** $VIR(x) \otimes VIR(y)$ is preserved as **generalized symmetries**

$$\begin{aligned}\hat{X}(f, g) &= \sum_{i,j} \{ f(x_i) \partial_{x_i} + g(y_j) \partial_{y_j} \\ &\quad - \left[\frac{f(x_{j+1}) - f(x_j)}{x_{j+1} - x_j} + \frac{g(y_{i+1}) - g(y_i)}{y_{i+1} - y_i} \right] \partial_{u_{ij}} \}\end{aligned}$$

$$u_{11}u_{00} - u_{10}v_{01} - u_{00}u_{01}u_{10}(x_{10} - x_{00})(y_{01} - y_{00}) = 0,$$

$$x_{01} = x_{00}, \quad y_{10} = y_{00}.$$

Numerical experiments

- ① preserving the $SL_x(2, \mathbb{R}) \otimes SL_y(2, \mathbb{R})$

$$u_{11}u_{00} - u_{10}u_{01} = h k [au_{01}u_{10} + (1-a)u_{00}u_{11}] \operatorname{sign}(u_{01}u_{10})\sqrt{|u_{01}u_{10}|},$$

- ② preserving linearizability

$$u_{11}u_{00} - u_{10}u_{01} = h k u_{00}u_{11} \left[\frac{u_{01} + u_{10}}{2} - h k u_{01}u_{10} \right],$$

- ③ preserving generalized symmetries

$$u_{11}u_{00} - u_{10}u_{01} = h k u_{00}u_{01}u_{10},$$

- ④ The *standard* discretization

$$u_{11}u_{00} - u_{10}u_{01} = h k u_{00}^3,$$

Higher order corrections in h, k

5 test functions

$$f_1 = \frac{2}{(x^2 + 1)(y^2 + 1)(\tan^{-1}(x) + \tan^{-1}(y) + 6)^2},$$
$$f_2 = \frac{8 \left(1 - 4 \left(x + \frac{1}{2}\right)\right) (1 - 4y) \exp(-2x(1 + 2x) - 2y(y + 2))}{(e^{-2x(1+2x)} + e^{2y(1-2y)} + 1)^2},$$
$$f_3 = -\frac{3.38 \sin(1.3(x + 0.01)) \cos(1.3(y + 0.01))}{(\cos(1.3(x + 0.01)) + \sin(1.3(y + 0.01)) + 3)^2}$$
$$f_4 = \frac{8xy}{(x^2 + y^2 + 2)^2}$$
$$f_5 = \frac{383.1 e^{3.862(2.5(x-0.5)+0.4y+2.5)}}{(e^{9.655(x+0.5)} + 12.83e^{1.545y})^2}$$

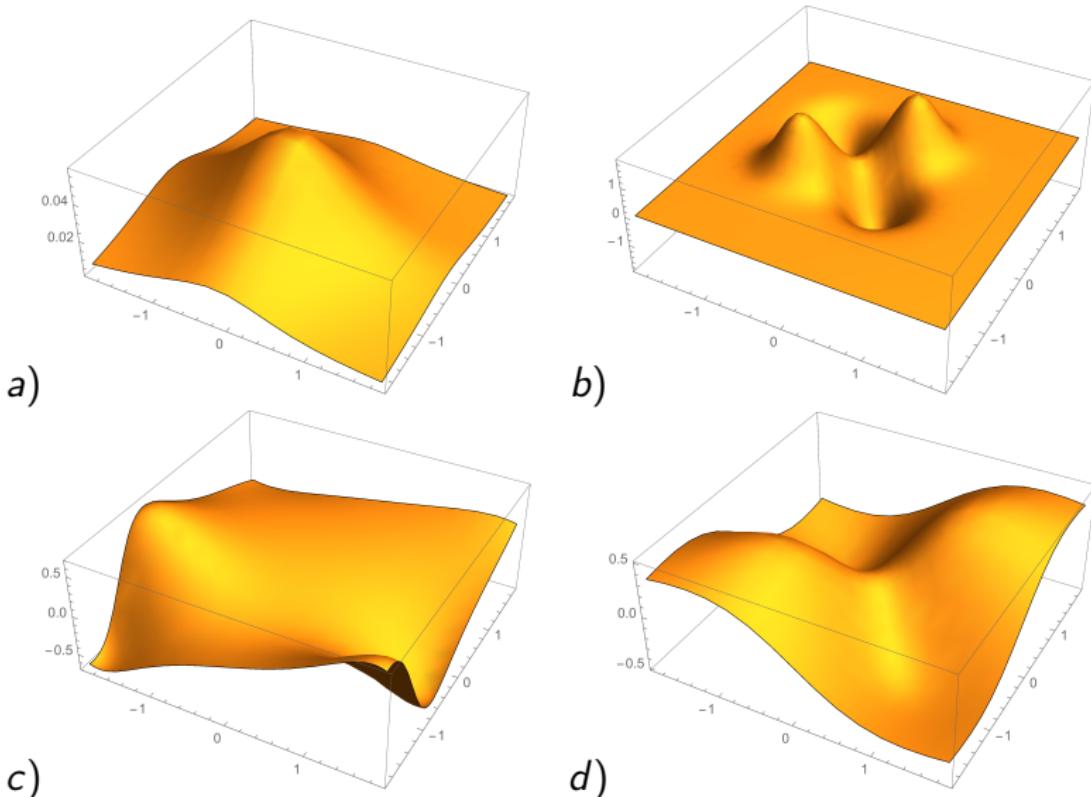


Figure : Plots of the exact solutions a) f_1 , b) f_2 , c) f_3 and d) f_4 in the domain \mathcal{D}_1 used in the numerical integrations.

Global numerical estimator

$$\chi_{\alpha}(F) = \sqrt{\frac{\sum_{ij} \left(F_{ij}^{\alpha} - F_{ij} \right)^2}{\sum_{ij} F_{ij}^2}}$$

Table : Relative mean square distance between the numerical solutions and the analytic one in the domain \mathcal{D}_0 .

	χ_{Inv}	χ_{AS}	χ_{RV}	χ_{stand}
f_1	5.2×10^{-6}	2.7×10^{-6}	3.1×10^{-4}	9.2×10^{-4}
f_2	3.4×10^{-4}	1.5×10^{-4}	7.6×10^{-3}	2.2×10^{-2}
f_3	4.7×10^{-5}	1.5×10^{-5}	3.0×10^{-3}	9.2×10^{-3}
f_4	4.3×10^{-5}	7.9×10^{-5}	5.2×10^{-3}	2.0×10^{-2}
f_5	3.8×10^{-2}	3.0×10^{-2}	2.8×10^{-1}	4.3×10^{-1}

$\mathcal{D}_0 = [-1.5, 1.08] \times [-1.0, 1.58]$, $h = k = 0.02$, lattice points 130×130

Point-like numerical estimator

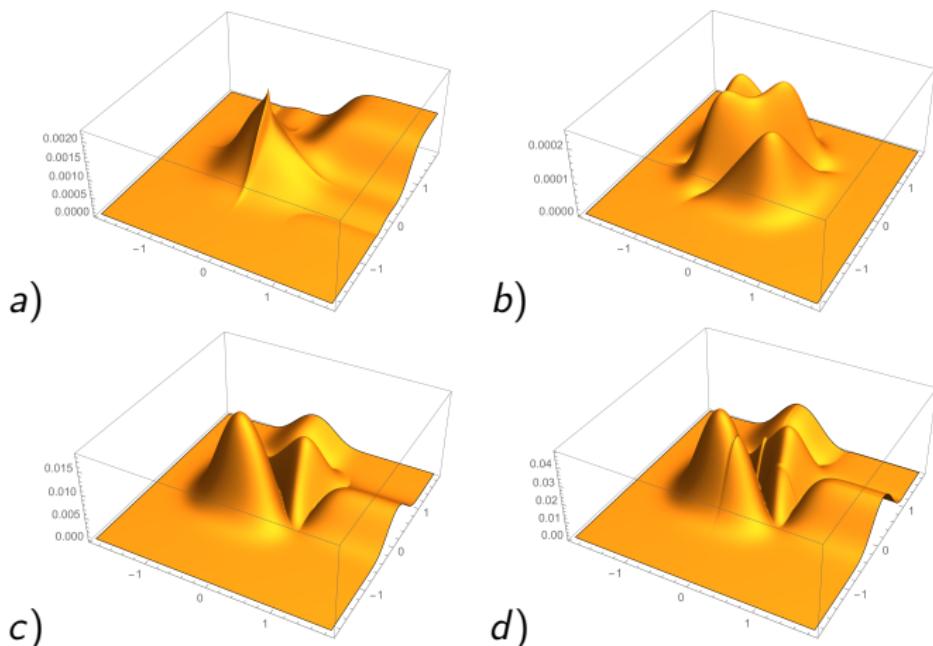


Figure : $R_{ij} = \left| \frac{F_{ij}^\alpha - F_{ij}}{F_{ij}} \right|$ for f_2 : a) Invariant, b) Adler-Startsev, c) R-V., d) Standard. Maximal error 2×10^{-3} , 2×10^{-4} , 1.5×10^{-2} , 4×10^{-2} .

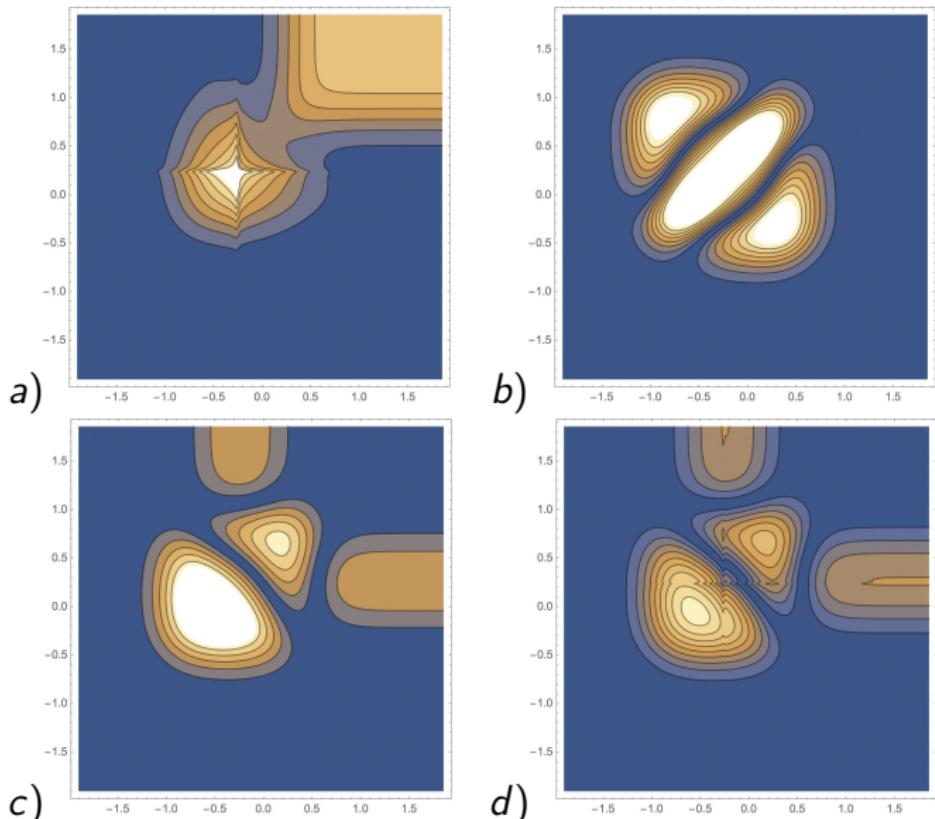
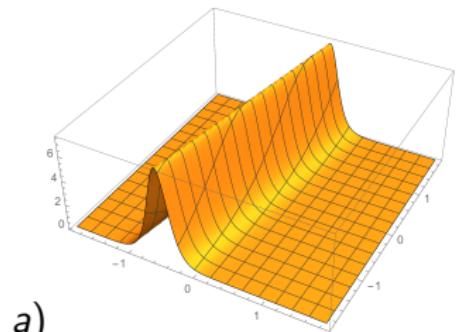
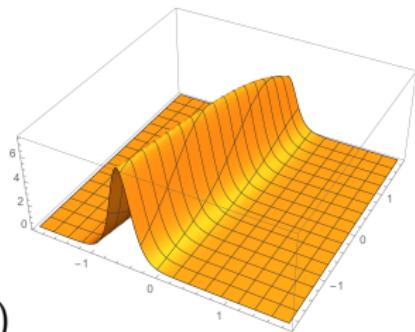


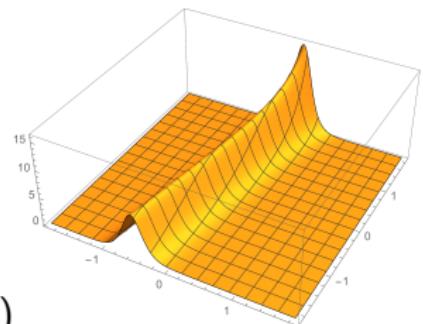
Figure :



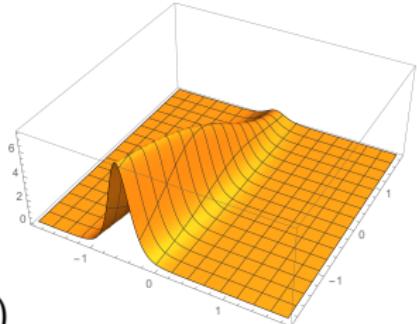
a)



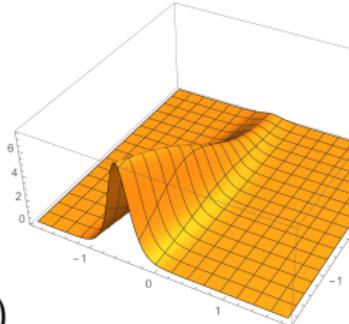
b)



c)



d)



e)

Figure : The function f_5 : a) analytic, b) symmetry preserving, c) Adler-Startsev, d) Rebelo-Valiquette, e) Standard.

Stability on the step size

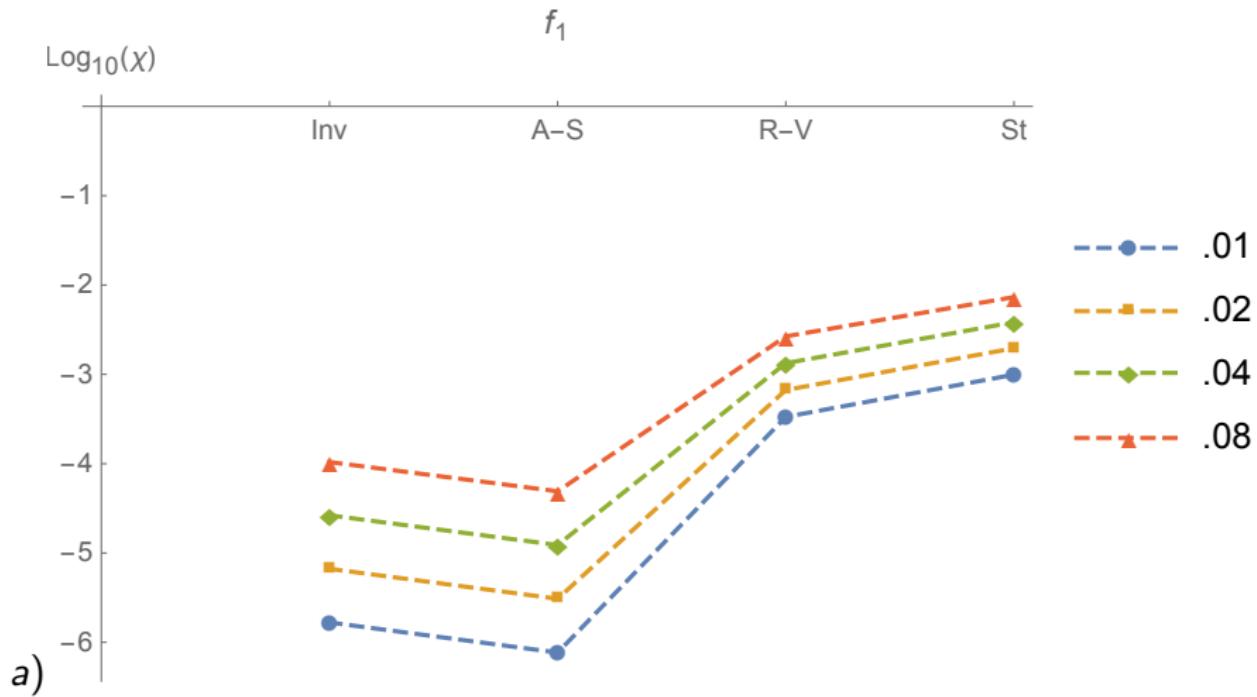
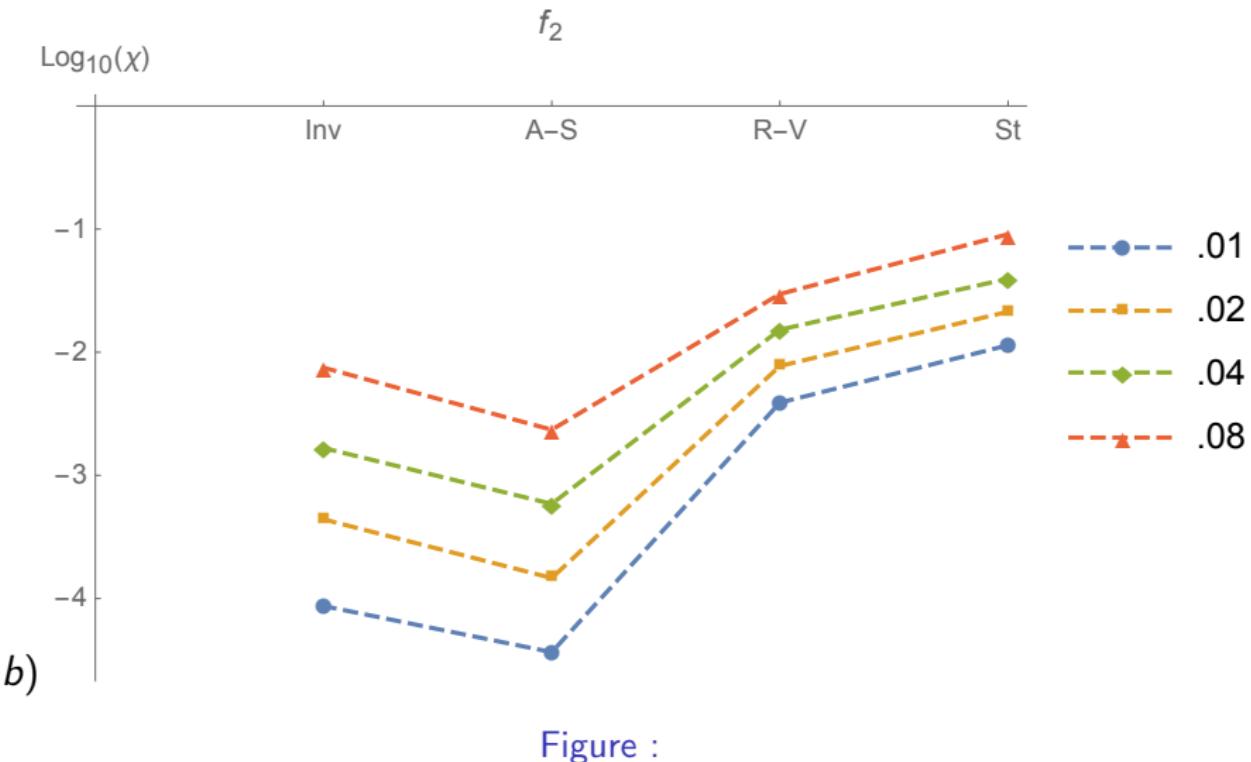


Figure :



Stability on the parameter a

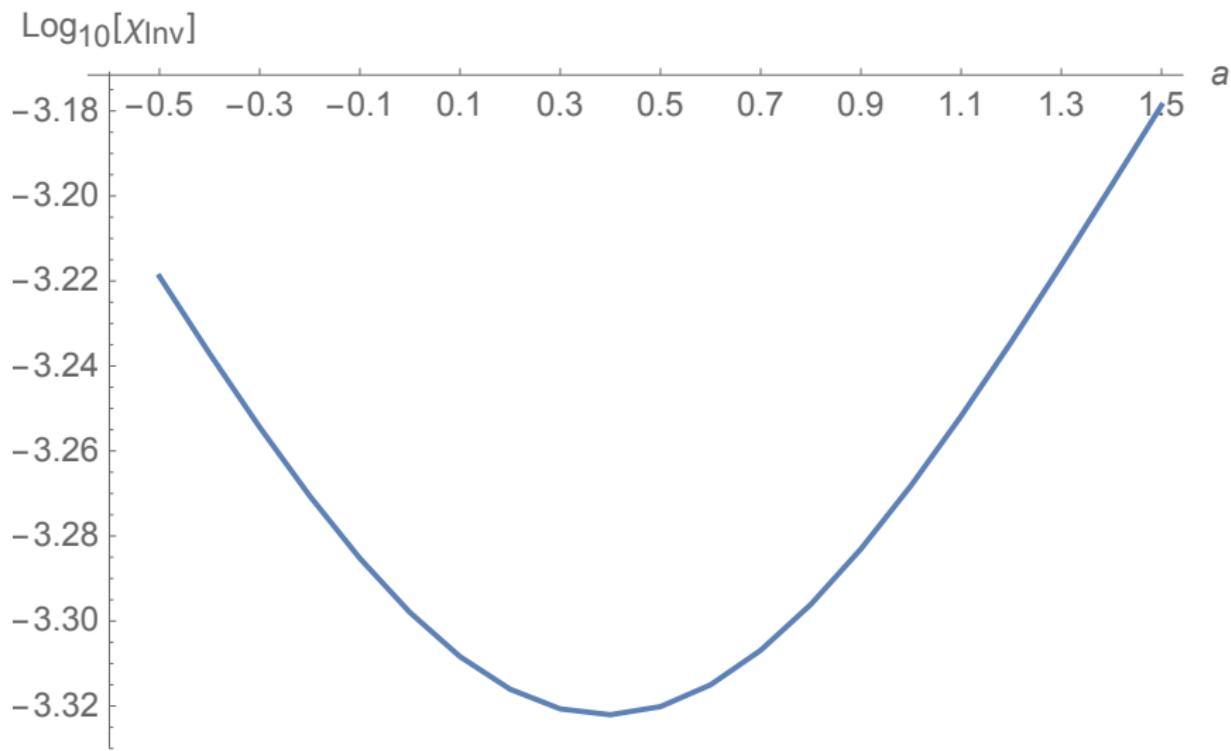


Figure : Plot of χ_{Inv} for the function f_2 in the parameter range $a \in [-0.5, 1.5]$.

Conclusions

- Explicit construction of symmetry preserving discretization is obtained for PDE;
- Maximal finite subgroup of Infinite-dimensional symmetry group is preserved;
- Lattice equations may be weak invariant of the full group;
- Discretization preserving generalized symmetriy group can be obtained by the pseudo-group approach.
- Linearizability preserving discretizations are more stable than the other approches, but ...
- Numerical experiments based on the preserving symmetry discretization works well like linearizable, except around zeros
- Discretizations of other equations Liouville type
- Use of symmetries for controlling
- The 3WI equation, DS eq.
- Multidimensional non integrable eq.s