Self-consistent sources for integrable equations via deformations of binary Darboux transformations

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Appearance of soliton equations with self-consistent sources:

- Mel'nikov 1983-92, ...
- Mathematically:
 - via a multiscaling limit of familiar integrable systems (Zakharov & Kuznetsov 1986, ...)
 - via a symmetry constraint imposed on a higher than two-dimensional integrable system (Konopelchenko, Sidorenko, Strampp 1991, Oevel 1993, ...)
- *Physically:* often a certain approximation of nonlinear interaction of waves with long and short wave length.



$$4 u_t - u_{xxx} - 3 (u^2)_x = (r^{\mathsf{T}} r)_x \qquad r_{xx} = P^2 r - u r$$

Without the source on the rhs of the KdV equation, the last equation is half of its Lax pair. Somehow an equation $r_t = \ldots$ seems to be missing (e.g., in order to address integrability).



Plot of u for a 2-soliton solution of the above scalar KdV equation with selfconsistent sources. Here an arbitrary function of t that is present in the solution has been chosen as sin(3t). There are lots of possibilities ...

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Example 2: (2+1)-dimensional Yajima-Oikawa system *Yajima-Oikawa* system

$$u_t = (r^{\mathsf{T}}r)_x$$
 i $r_t = r_{xx} - ur$

Integrable three-dimensional generalization (Oikawa, Okamura, Funakoshi '89):

$$u_t = (r^{\mathsf{T}}r)_{\mathsf{X}}$$
 i $(r_t + r_y) = r_{\mathsf{X}\mathsf{X}} - u r$

This looks like a reasonable evolution system ..., but via the transformation $\xi = x + y - t$, $\tau = t - y$, $\eta = y$, we get

$$u_{\tau} = u_{\xi} + (r^{\mathsf{T}}r)_{\xi}$$
 i $r_{\eta} = r_{\xi\xi} - ur$

(Grimshaw '77, Mel'nikov '83). Again, somehow an equation $r_{\tau} = \dots$ is missing.

We will present a more coherent picture in the sequel.



$$(4 \phi_{0,t} - \phi_{0,xxx} - 6 (\phi_{0,x})^2)_x -3 \phi_{0,yy} + 6 [\phi_{0,x}, \phi_{0,y}] = 0$$

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Binary Darboux transformation for pKP

Associated linear system and its adjoint:

$$\theta_{y} = \theta_{xx} + 2 \phi_{0,x} \theta \qquad \theta_{t} = \theta_{xxx} + 3 \phi_{0,x} \theta_{x} + \frac{3}{2} (\phi_{0,y} + \phi_{0,xx}) \theta$$

$$\eta_{y} = -\eta_{xx} - 2 \eta \phi_{0,x} \qquad \eta_{t} = \eta_{xxx} + 3 \eta_{x} \phi_{0,x} - \frac{3}{2} \eta (\phi_{0,y} - \phi_{0,xx})$$

These equations imply the compatibility of the system

$$\begin{aligned} \Omega_{x} &= -\eta \, \theta & \Omega_{y} &= -\eta \, \theta_{x} + \eta_{x} \, \theta \\ \Omega_{t} &= -\eta \, \theta_{xx} + \eta_{x} \, \theta_{x} - \eta_{xx} \, \theta - 3 \, \eta \, \phi_{0,x} \, \theta \end{aligned}$$

hence the existence of a "potential" $\boldsymbol{\Omega}.$ Then it follows that

$$\phi = \phi_0 - \theta \, \Omega^{-1} \, \eta$$

is a new solution of the pKP equation, and

$$q = \theta \, \Omega^{-1} \qquad r = \Omega^{-1} \, \eta$$

solve the linear equations with ϕ instead of ϕ_0 . This is an essential step in the binary Darboux transformation for the pKP equation.



If ϕ is an $m \times m$ matrix, then θ , q have matrix size $m \times n$, η , r have size $n \times m$, Ω and ω are $n \times n$ matrices.

Hence we consider a *vectorial* binary Darboux transformation, so there is no need to iterate it.

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$$\begin{aligned} \Omega_{x} &= -\eta \,\theta + c_{1} \,, \\ \Omega_{y} &= -\eta \,\theta_{x} + \eta_{x} \,\theta + c_{2} \,, \\ \Omega_{t} &= -\eta \,\theta_{xx} + \eta_{x} \,\theta_{x} - \eta_{xx} \,\theta - 3 \,\eta \,\phi_{0,x} \,\theta + c_{3} \,\theta_{x} \,\theta_{y} \,. \end{aligned}$$

with (matrix) functions c_i , i = 1, 2, 3. Consistency requires that

 $c_1 = \omega_x$ $c_2 = \omega_y$ $c_3 = \omega_t$

with a potential ω . Hence this deformation actually amounts to the substitution

 $\Omega\mapsto\Omega-\omega$

in the previous equations. Then ϕ , q, r no longer satisfy the pKP equation and the linear systems! Instead we find ...

pKP

$$\begin{array}{rcl} q_{y} - q_{xx} &=& 2 \, \phi_{x} \, q + \left(-q \, \omega_{y} + q \, \omega_{xx} + 2 \, q_{x} \, \omega_{x} \right) \, \Omega^{-1} \,, \\ q_{t} - q_{xxx} &=& 3 \, \phi_{x} q_{x} + \frac{3}{2} \left(\phi_{y} + \phi_{xx} \right) \, q + \frac{3}{2} \left(-q \, \omega_{y} + q \, \omega_{xx} + 2 \, q_{x} \, \omega_{x} \right) \, r \, q \\ &\quad - \left(q \, \omega_{t} - q \, \omega_{xxx} - 3 \left(q_{x} \, \omega_{x} \right)_{x} - 3 \, \phi_{x} \, q \, \omega_{x} \right) \, \Omega^{-1} \\ r_{y} + r_{xx} &=& -2 \, r \, \phi_{x} - \Omega^{-1} \left(\omega_{y} \, r + \omega_{xx} \, r + 2 \, \omega_{x} \, r_{x} \right) , \\ r_{t} - r_{xxx} &=& 3 \, r_{x} \, \phi_{x} - \frac{3}{2} \, r \, \left(\phi_{y} - \phi_{xx} \right) + \frac{3}{2} \, r \, q \, \left(\omega_{y} \, r + \omega_{xx} \, r + 2 \, \omega_{x} \, r_{x} \right) \\ &\quad - \Omega^{-1} \left(\omega_{t} \, r - \omega_{xxx} \, r - 3 \left(\omega_{x} \, r_{x} \right)_{x} - 3 \, \omega_{x} \, r \, \phi_{x} \right) \end{array}$$

and the extended pKP equation

$$(4 \phi_t - \phi_{xxx} - 6 (\phi_x)^2)_x - 3 \phi_{yy} + 6 [\phi_x, \phi_y] = (4 q \omega_t r - 6 q \omega_x r_y - 6 q \omega_x r_{xx} + 6 q \omega_y r_x - 18 q \omega_{xx} r_x - 6 q \omega_{xy} r - 10 q \omega_{xxx} r)_x + (6 q \omega_x r_x - 3 q \omega_y r + 9 q \omega_{xx} r)_y + (6 q \omega_x r_x - 3 q \omega_y r + 9 q \omega_{xx} r)_{xx}$$

Now we look for choices of ω , such that Ω gets eliminated in some of the equations for q and r! This requires $\omega_x = 0$ and either ...

1. $\omega = \omega(t)$ $(4\phi_t - \phi_{xxx} - 6(\phi_x)^2)_{v} - 3\phi_{vv} + 6[\phi_x, \phi_y] = 4(q\omega_t r)_{x}$ $q_v - q_{xx} = 2 \phi_x q$ $r_v + r_{xx} = -2 r \phi_x$ Via $\tilde{q} = q Q$ and $\tilde{r} = \mathcal{R} r$, with a suitable choice of Q(t) and $\mathcal{R}(t)$, we can absorb ω_t : $(4\phi_t - \phi_{xxx} - 6(\phi_x)^2)_{,i} - 3\phi_{yy} + 6[\phi_x, \phi_y] = (\tilde{q}\,\tilde{r})_x$ $\tilde{q}_{v} - \tilde{q}_{xx} = 2 \phi_{x} \tilde{q}$ $\tilde{r}_{v} + \tilde{r}_{xx} = -2 \tilde{r} \phi_{x}$ Mel'nikov. ... 2. $\omega = \omega(\mathbf{y})$ $(4\phi_t - \phi_{xxx} - 6(\phi_x)^2)_y - 3\phi_{yy} + 6[\phi_x, \phi_y]$ $= 3 (q \omega_{v} r_{x} - q_{x} \omega_{v} r)_{v} - 3 (q \omega_{v} r)_{v}$ $q_t - q_{\text{XXX}} = 3 \phi_x q_x + \frac{3}{2} (\phi_y + \phi_{\text{XX}}) q - \frac{3}{2} q \omega_y r q$ $r_{t} - r_{xxx} = 3 r_{x} \phi_{x} - \frac{3}{2} r (\phi_{y} - \phi_{xx}) + \frac{3}{2} r q \omega_{y} r$

Again, ω_{γ} can be absorbed.

pKP



The above procedure provides us with a **hetero binary Darboux transformation** from the pKP equation and its associated linear system to any of the pKP systems with self-consistent sources.

The rank of ω_t , respectively ω_y , determines the number of sources.

The method solves the extended (or deformed) pKP system, for any given (matrix) function $\omega(t)$, resp. $\omega(y)$.

Via the step to \tilde{q} and \tilde{r} , this is then turned into a solution of the extended pKP system, where ω is absorbed.

As a consequence, the scs-extensions of pKP admit solutions depending on *arbitrary* functions of a single variable !

Exact pKP solutions in case of vanishing seed If $\phi_0 = 0$, special solutions of linear and adjoint linear system are $\theta = A e^{\vartheta(P)} B$ $\eta = C e^{-\vartheta(Q)} D$ $\vartheta(P) = P x + P^2 y + P^3 t$ with constant matrices A, B, C, D, P and Q (of appropriate size).

$$\implies \quad \Omega = \omega - C e^{-\vartheta(Q)} X e^{\vartheta(P)} B$$

with a constant matrix X that satisfies the Sylvester equation

$$XP - QX = DA$$

Now

pKP

$$\phi = \phi_0 - \theta \, \Omega^{-1} \, \eta \qquad q = \theta \, \Omega^{-1} \qquad r = \Omega^{-1} \, \eta$$

yields explicit solutions of the extended matrix pKP equations with self-consistent sources (and with $\omega(t)$, respectively $\omega(y)$).

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In the framework of **bidifferential calculus**, we can abstract the underlying structure from the specific example (here pKP) and then obtain corresponding self-consistent source extensions of quite a number of other integrable equations.

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Summary

Bidifferential calculus

A graded associative algebra is an associative algebra $\Omega = \bigoplus_{r \ge 0} \Omega^r \text{ over } \mathbb{C}, \text{ where } \mathcal{A} := \Omega^0 \text{ is an associative algebra}$ over \mathbb{C} and Ω^r , $r \ge 1$, are \mathcal{A} -bimodules such that $\Omega^r \Omega^s \subseteq \Omega^{r+s}$. A bidifferential calculus is a unital graded associative algebra Ω , supplied with two (\mathbb{C} -linear) graded derivations $\mathrm{d}, \mathrm{d} : \Omega \to \Omega$ of degree one (hence $\mathrm{d}\Omega^r \subseteq \Omega^{r+1}, \mathrm{d}\Omega^r \subseteq \Omega^{r+1}$), and such that

$$\mathrm{d}^2 = \bar{\mathrm{d}}^2 = \mathrm{d}\bar{\mathrm{d}} + \bar{\mathrm{d}}\mathrm{d} = 0$$

Several integrable equations can be expressed either as

 $\mathrm{d}\,\bar{\mathrm{d}}\,\phi_0 + \mathrm{d}\phi_0\,\mathrm{d}\phi_0 = 0$

with $\phi_0 \in Mat(m, m, A)$, or as

 $\mathrm{d}\left[\left(\bar{\mathrm{d}}g_0\right)g_0^{-1}\right]=0$

The two equations are related by the Miura equation

$$\bar{\mathrm{d}}g_0 = (\mathrm{d}\phi_0) \, g_0$$

which has both equations as integrability conditions.



A linear system and an adjoint linear system for the above equation for ϕ_0 is given by

 $\bar{\mathrm{d}}\theta = (\mathrm{d}\phi_0)\,\theta + (\mathrm{d}\theta)\,\Delta$

respectively

$$\bar{\mathrm{d}}\eta = -\eta\,\mathrm{d}\phi_0 + \Gamma\,\mathrm{d}\eta$$

where $\theta \in Mat(m, n, A)$, $\eta \in Mat(n, m, A)$, $\Delta, \Gamma \in Mat(n, n, A)$. They have to satisfy

$$\bar{\mathrm{d}}\Delta = (\mathrm{d}\Delta)\Delta \qquad \bar{\mathrm{d}}\mathsf{\Gamma} = \mathsf{\Gamma}\,\mathrm{d}\mathsf{\Gamma}$$

as a consequence of the properties of d and $\bar{d}.$

> $\Gamma \Omega - \Omega \Delta = \eta \theta$ $\bar{\mathrm{d}}\Omega = (\mathrm{d}\Omega) \Delta - (\mathrm{d}\Gamma) \Omega + (\mathrm{d}\eta) \theta$

The equations resulting from acting with d or \bar{d} on the last equation are satisfied as a consequence of the preceding equations. It follows (Dimakis & M-H 2008) that

$$\phi = \phi_0 - \theta \, \Omega^{-1} \, \eta$$

is a new solution of the $\phi\text{-equation}$ and

$$q = \theta \, \Omega^{-1} \qquad r = \Omega^{-1} \, \eta$$

satisfy

 $\bar{\mathrm{d}}q = (\mathrm{d}\phi) q + \mathrm{d}(q \Gamma)$ $\bar{\mathrm{d}}r = -r (\mathrm{d}\phi) + \mathrm{d}(\Delta r)$

Deformation of the potential

Guided by the pKP example: $\Omega \mapsto \Omega - \omega$. Hence

BDC

$$\Gamma \Omega - \Omega \Delta = \eta \theta + c \bar{\mathrm{d}}\Omega = (\mathrm{d}\Omega) \Delta - (\mathrm{d}\Gamma) \Omega + (\mathrm{d}\eta) \theta + \gamma$$

where $\mathbf{c} := \Gamma \omega - \omega \Delta$, $\gamma := \overline{d}\omega - (d\omega)\Delta + (d\Gamma)\omega$. By straightforward computations, one shows that

$$\phi = \phi_0 - \theta \, \Omega^{-1} \, \eta \qquad q = \theta \, \Omega^{-1} \qquad r = \Omega^{-1} \, \eta$$

constitutes a solution of

$$\mathrm{d}\,\bar{\mathrm{d}}\,\phi + \mathrm{d}\phi\,\mathrm{d}\phi = \mathrm{d}(\,q\,\gamma\,r - q\,\mathrm{d}(c\,r)\,)$$

and

$$\bar{\mathrm{d}}q = (\mathrm{d}\phi) \, q + \mathrm{d}(q \, \Gamma) - q \, \gamma \, \Omega^{-1} - (\mathrm{d}q) \, c \, \Omega^{-1}$$
$$\bar{\mathrm{d}}r = -r \, \mathrm{d}\phi + \mathrm{d}(\Delta \, r) - \Omega^{-1} \, \gamma \, r + \Omega^{-1} \, \mathrm{d}(c \, r)$$

If ϕ_0 and g_0 satisfy the Miura equation, then ϕ, q, r together with

$$g = (I - \theta \, \Omega^{-1} \, \Gamma^{-1} \eta) \, g_0$$

(I identity matrix) satisfy

$$\bar{\mathrm{d}}g - (\mathrm{d}\phi)g = (q\gamma + (\mathrm{d}q)c)\Omega^{-1}\Gamma^{-1}\Omega r g_0$$

If c = 0, i.e., $\Gamma \omega = \omega \Delta$, then we have

BDC

$$g^{-1} = g_0^{-1} \left(I + \theta \, \Delta^{-1} \, \Omega^{-1} \, \eta \right)$$

and g satisfies the extended Miura equation

$$\bar{\mathrm{d}}g - (\mathrm{d}\phi)g = (q\gamma\,\Delta^{-1}r)g$$

which implies the following extension of the g-equation:

$$\mathrm{d}[(\bar{\mathrm{d}}g)g^{-1}] = \mathrm{d}(q\gamma\,\Delta^{-1}r)$$

Via the extended Miura equation we can eliminate ϕ in the previous equations for q and r in favor of g.



In the following examples, we specify the graded algebra $\boldsymbol{\Omega}$ to be of the form

$$oldsymbol{\Omega} = \mathcal{A} \otimes oldsymbol{\Lambda} \,, \qquad oldsymbol{\Lambda} = igoplus_{i=0}^2 oldsymbol{\Lambda}^i$$

where Λ is the exterior (Grassmann) algebra of the vector space \mathbb{C}^2 . It is then sufficient to define d and \overline{d} on \mathcal{A} , since they extend to Ω in a straightforward way, treating the elements of Λ as constants. Moreover, d and \overline{d} extend to matrices over Ω . We choose a basis ξ_1, ξ_2 of Λ^1 .

Recovering the pKP example

Let \mathcal{A}_0 be the space of smooth complex functions on \mathbb{R}^3 . We extend it to $\mathcal{A} = \mathcal{A}_0[\partial_x]$. On \mathcal{A} we define

BDC

$$df = [\partial, f]\xi_1 + \frac{1}{2}[\partial_y + \partial^2, f]\xi_2, \ \bar{d}f = \frac{1}{2}[\partial_y - \partial^2, f]\xi_1 + \frac{1}{3}[\partial_t - \partial^3, f]\xi_2$$

The maps d and \overline{d} extend to linear maps on $\Omega = \mathcal{A} \otimes \Lambda$ and moreover to matrices over Ω . We need to choose

$$\Delta = \Gamma = -\partial$$

in order to eliminate explicit operator terms in the linear equations. c = 0 iff $\omega_x = 0$. The expression for γ takes the form

$$\gamma = \frac{1}{2}\omega_y \,\xi_1 + \left(\frac{1}{3}\omega_t + \frac{1}{2}\omega_y \,\partial\right)\xi_2$$

We recover all eqs in the pKP section (with $\omega_x = 0$).

Matrix 2d-Toda with self-consistent sources \mathcal{A}_0 complex functions on $\mathbb{R}^2 \times \mathbb{Z}$, smooth in the first two variables. $\mathcal{A} = \mathcal{A}_0[\mathbb{S}, \mathbb{S}^{-1}], \mathbb{S}$ shift operator in discrete variable $k \in \mathbb{Z}$. $\mathrm{d}f = [\mathbb{S}, f] \xi_1 + [\partial_{\mathsf{v}}, f] \xi_2, \qquad \mathrm{d}f = [\partial_{\mathsf{x}}, f] \xi_1 - [\mathbb{S}^{-1}, f] \xi_2$ For $f \in \mathcal{A}$, we write $f^{\pm}(x, y, k) := f(x, y, k \pm 1)$. We write $\phi = \varphi \mathbb{S}^{-1}, \ q = \tilde{q} \mathbb{S}^{-1}, \ r = \mathbb{S}^{-1} \tilde{r}, \ \Delta = \Gamma = \mathbb{S}^{-1}, \ \Omega = \tilde{\Omega} \mathbb{S}, \ \omega = \tilde{\omega} \mathbb{S}$ and set c = 0, which is $\tilde{\omega}^+ = \tilde{\omega}$.

2dToda

Source-free case: $d \bar{d} \phi + d \phi d \phi = 0$ becomes

$$\varphi_{xy} - (\varphi^+ - \varphi)(\varphi_y + I) + (\varphi_y + I)(\varphi - \varphi^-) = 0$$

In the scalar case, in terms of $V := \varphi_y$, this reads $(\ln(1+V))_x = \varphi^+ - \varphi + \varphi^-$. Differentiating with respect to y, it becomes the *two-dimensional Toda lattice equation* $(\ln(1+V))_{xy} = V^+ - 2V + V^-$ (Mikhailov '79). scs-extension and solutions: Hu et al. 2007.

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$$\varphi_{xy} - (\varphi^+ - \varphi) (\varphi_y + I) + (\varphi_y + I) (\varphi - \varphi^-) = (\tilde{q}^+ \, \tilde{\omega}_y \, \tilde{r}^-)^- - \tilde{q}^+ \, \tilde{\omega}_y \, \tilde{r}^-$$

Those of the equations for \tilde{q} and \tilde{r} that do not involve $\tilde{\Omega}$ are

$$ilde{q}_{\mathsf{x}} = ilde{q}^+ - ilde{q} + (\varphi^+ - \varphi) \, ilde{q} \,, \qquad ilde{r}_{\mathsf{x}} = ilde{r} - ilde{r} - ilde{r} \, (\varphi^+ - \varphi)$$

The Miura-dual is

$$(g_{x} g^{-1})_{y} - [g^{+} g^{-1} - (g^{+} g^{-1})^{-}] = -\tilde{q}^{+} \tilde{\omega}_{y} \tilde{r} + (\tilde{q}^{+} \tilde{\omega}_{y} \tilde{r})^{-},$$

$$\tilde{q}_{x} = \tilde{q}^{+} - \tilde{q} + g_{x} g^{-1} \tilde{q}, \qquad \tilde{r}_{x} = \tilde{r} - \tilde{r}^{-} - \tilde{r} g_{x} g^{-1}$$

In the scalar case, in terms of $u = \ln g$ this takes the form

$$u_{xy} - e^{u^+ - u} + e^{u - u^-} = -\tilde{q}^+ \tilde{\omega}_y \tilde{r} + (\tilde{q}^+ \tilde{\omega}_y \tilde{r})^- ,$$

$$\tilde{q}_x = \tilde{q}^+ - \tilde{q} + u_x \tilde{q} , \qquad \tilde{r}_x = \tilde{r} - \tilde{r}^- - u_x \tilde{r}$$

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$$\varphi_{xy} - (\varphi^+ - \varphi)(\varphi_y + I) + (\varphi_y + I)(\varphi - \varphi^-) = (\tilde{q}\,\tilde{\omega}_x\,\tilde{r}^-)_y$$

Those of the equations for \tilde{q} and \tilde{r} that do not depend on $\tilde{\Omega}$ are

$$\tilde{q}_y = \tilde{q} - \tilde{q}^- - \varphi_y \, \tilde{q}^-, \qquad \tilde{r}_y = \tilde{r}^+ - \tilde{r} + \tilde{r}^+ \, \varphi_y^+$$

The Miura-dual is

$$(g_{x} g^{-1})_{y} - [g^{+} g^{-1} - (g^{+} g^{-1})^{-}] = -(\tilde{q} \, \tilde{\omega}_{x} \, \tilde{r})_{y},$$

 $\tilde{q}_{y} = \tilde{q} - g (g^{-1} \, \tilde{q})^{-}, \qquad \tilde{r}_{y} = -\tilde{r} + \tilde{r}^{+} g^{+} g^{-1}$

In the scalar case (m = 1), in terms of $u = \ln g$, $a = e^{-y} g^{-1} \tilde{q} \tilde{\omega}_x$ and $b = e^y g \tilde{r}$, this can be expressed as follows,

$$u_{xy} - e^{u^+ - u} + e^{u - u^-} = -(a b)_y,$$

$$a_y + u_y a + a^- = 0, \qquad b_y - b u_y - b^+ = 0.$$

Such a system appeared in X. Liu, Y. Zeng, R. Liu 2008.

A matrix version of the discrete KP equation with self-consistent sources

Let \mathcal{A}_0 be the space of complex functions of discrete variables $k_0, k_1, k_2 \in \mathbb{Z}$, and $\mathbb{S}_0, \mathbb{S}_1, \mathbb{S}_2$ corresponding shift operators. We extend \mathcal{A}_0 to $\mathcal{A} = \mathcal{A}_0[\mathbb{S}_0^{\pm 1}, \mathbb{S}_1^{\pm 1}, \mathbb{S}_2^{\pm 1}]$ and define d and \overline{d} on \mathcal{A} via

$$df = \sum_{i=1}^{2} c_{i}^{-1} [\mathbb{S}_{i}^{-1}, f] \xi_{i}, \qquad \bar{d}f = \sum_{i=1}^{2} [\mathbb{S}_{i}^{-1} \mathbb{S}_{0}, f] \xi_{i}$$

where c_i are constants. Then d and \overline{d} extend to $\Omega = \mathcal{A} \otimes \Lambda$ and to matrices over Ω . In the following we will use the notation

$$f_{,0} := \mathbb{S}_0 f \mathbb{S}_0^{-1}, \quad f_{,-0} := \mathbb{S}_0^{-1} f \mathbb{S}_0, \quad f_{,i} := \mathbb{S}_i f \mathbb{S}_i^{-1}, \quad f_{,-i} := \mathbb{S}_i^{-1} f \mathbb{S}_i$$

We write

$$\Delta = \Gamma = \mathbb{S}_0, \ \Omega = \tilde{\Omega} \mathbb{S}_0^{-1}, \ \omega = \tilde{\omega} \mathbb{S}_0^{-1}, \ \phi = \varphi \mathbb{S}_0, \ q = \tilde{q} \mathbb{S}_0, \ r = \mathbb{S}_0 \tilde{r}$$

The resulting g-equations are

pКР

$$\begin{aligned} c_{i}\left((g_{,i}\,g_{,0}^{-1})_{,j}-g_{,i}\,g_{,0}^{-1}\right)-c_{j}\left((g_{,j}\,g_{,0}^{-1})_{,i}-g_{,j}\,g_{,0}^{-1}\right)\\ &=\left(c_{i}-1\right)\left[(\tilde{q}_{,i}\left(\tilde{\omega}_{,i}-\tilde{\omega}\right)\tilde{r}_{,0})_{,j}-\tilde{q}_{,i}\left(\tilde{\omega}_{,i}-\tilde{\omega}\right)\tilde{r}_{,0}\right]\\ &-(c_{j}-1)\left[(\tilde{q}_{,j}\left(\tilde{\omega}_{,j}-\tilde{\omega}\right)\tilde{r}_{,0})_{,i}-\tilde{q}_{,j}\left(\tilde{\omega}_{,j}-\tilde{\omega}\right)\tilde{r}_{,0}\right]\\ \tilde{q}_{,i} &=\left(c_{i}-1\right)^{-1}\left[c_{i}\,g_{,i}\,g_{,0}^{-1}\tilde{q}_{,0}-q\right]-\left[\tilde{q}_{,i}\left(\tilde{\omega}_{,i}-\tilde{\omega}\right)\tilde{r}_{,0}\right]\tilde{q}_{,0}\\ &-\tilde{q}_{,i}\left(\tilde{\omega}_{,i}-\tilde{\omega}\right)\tilde{\Omega}_{,0,0}^{-1}\\ \tilde{r}_{,-i} &=\left(c_{i}-1\right)^{-1}\left[c_{i}\,\tilde{r}_{,-0}\,g_{,-0}\,g_{,-i}^{-1}-\tilde{r}\right]-\tilde{r}_{,-0}\left[\tilde{q}_{,-0}\left(\tilde{\omega}-\tilde{\omega}_{,-i}\right)_{,-0}\tilde{r}_{,-i}\right]\\ &+\tilde{\Omega}_{,0}^{-1}\left(\tilde{\omega}-\tilde{\omega}_{,-i}\right)\tilde{r}_{,-i}\\ \text{Set }\tilde{\omega}_{,1}=\tilde{\omega}, \text{ keep only equations without }\tilde{\Omega}: \end{aligned}$$

$$\begin{split} c_2 \left((g_{,2} \, g_{,0}^{-1})_{,1} - g_{,2} \, g_{,0}^{-1} \right) &- c_1 \left((g_{,1} \, g_{,0}^{-1})_{,2} - g_{,1} \, g_{,0}^{-1} \right) \\ &= (c_2 - 1) \left[(\tilde{q}_{,2} \, (\tilde{\omega}_{,2} - \tilde{\omega}) \, \tilde{r}_{,0})_{,1} - \tilde{q}_{,2} \, (\tilde{\omega}_{,2} - \tilde{\omega}) \, \tilde{r}_{,0} \right], \\ \tilde{q}_{,1} &= (c_1 - 1)^{-1} \left[c_1 \, g_{,1} \, g_{,0}^{-1} \, \tilde{q}_{,0} - \tilde{q} \right], \\ \tilde{r}_{,-1} &= (c_1 - 1)^{-1} \left[c_1 \, \tilde{r}_{,-0} \, g_{,-0} \, g_{,-1}^{-1} - \tilde{r} \right] \end{split}$$

Scalar discrete KP equation with self-consistent sources Let m = 1, $\tilde{\omega}_{,2} - \tilde{\omega} = K(c_1 - 1)/[c_1(c_2 - 1)]$ constant, and $g = \frac{\tau, -0}{\tau}$ $\tilde{q} = \frac{\rho, -0}{\tau}$ $\tilde{r} = \frac{\sigma}{\tau, -0}$

dKP

Then

$$(c_1 - 1) \tau_{,0} \rho_{,1} + \tau_{,0,1} \rho - c_1 \tau_{,1} \rho_{,0} = 0 (c_1 - 1) \tau_{,1} \sigma_{,0} + \tau \sigma_{,0,1} - c_1 \tau_{,0} \sigma_{,1} = 0$$

$$\frac{1}{\tau_{,0} \tau_{,1,2}} \Big(c_2 \tau_{,0,1} \tau_{,2} - c_1 \tau_{,0,2} \tau_{,1} - K \rho_{,2} \sigma_{,0,1} \Big) \\ = \Big[\frac{1}{\tau_{,0} \tau_{,1,2}} \Big(c_2 \tau_{,0,1} \tau_{,2} - c_1 \tau_{,0,2} \tau_{,1} - K \rho_{,2} \sigma_{,0,1} \Big) \Big]_{,-0}$$

The last equation is equivalent to

$$c_2 \tau_{,0,1} \tau_{,2} - c_1 \tau_{,0,2} \tau_{,1} - c_{12} \tau_{,0} \tau_{,1,2} = K \rho_{,2} \sigma_{,0,1}$$

with an arbitrary scalar c_{12} that does not depend on the discrete variable k_0 .

 \rightarrow discrete KP equation with scs (Hu&Wang '06, Doliwa&Lin '14).

Introduction

The full system of equations for ϕ, q, r, Ω

The following is the abstract system, for which we have a hetero binary Darboux transformation:

$$d\bar{d}\phi + d\phi d\phi = d(q\gamma r)$$
$$\bar{d}q = (d\phi)q + d(q\Gamma) + q\gamma\hat{\Omega}$$
$$\bar{d}r = -r d\phi + d(\Delta r) + \hat{\Omega}\gamma r$$
$$\Delta\hat{\Omega} - \hat{\Omega}\Gamma = r q$$
$$\bar{d}\hat{\Omega} = d(\hat{\Omega}\Gamma) + (dr)q + \hat{\Omega}\gamma\hat{\Omega}$$

where

$$\bar{\mathrm{d}}\Delta = (\mathrm{d}\Delta)\Delta \qquad \bar{\mathrm{d}}\Gamma = \Gamma \,\mathrm{d}\Gamma \qquad \Gamma \,\omega - \omega \,\Delta = 0$$
$$\gamma := \bar{\mathrm{d}}\omega - (\mathrm{d}\omega)\,\Delta + (\mathrm{d}\Gamma)\,\omega - \kappa \,\omega - \omega \,\lambda$$

and we have set $\hat\Omega:=-\Omega^{-1}.$ Let's take a look at this in the pKP hierarchy case.

Extension of the pKP hierarchy

 \mathcal{A}_0 : smooth functions of x and $\mathbf{t} = (t_1, t_2, \ldots)$

$$df = [\mathcal{E}_{\mu_1}, f] \xi_1 + [\mathcal{E}_{\mu_2}, f] \xi_2$$

$$\bar{d}f = [(\mu_1^{-1} - \partial_x)\mathcal{E}_{\mu_1}, f] \xi_1 + [(\mu_2^{-1} - \partial_x)\mathcal{E}_{\mu_2}, f] \xi_2$$

Miwa shift operator: $\mathcal{E}_{\mu}f = f_{[\mu]}\mathcal{E}_{\mu}$, $f_{[\mu]}(x, \mathbf{t}) = f(x, \mathbf{t} + [\mu])$, $[\mu] = (\mu, \mu^2/2, \mu^3/3, \ldots)$. $\Delta = \Gamma = -I_n \partial_x$. Then $\omega_x = 0$ and

$$(\mu_{2}^{-1} - \phi + \phi_{-[\mu_{2}]})_{-[\mu_{1}]} (\mu_{1}^{-1} - \phi + \phi_{-[\mu_{1}]}) \\ -(\mu_{1}^{-1} - \phi + \phi_{-[\mu_{1}]})_{-[\mu_{2}]} (\mu_{2}^{-1} - \phi + \phi_{-[\mu_{2}]}) - (\phi_{-[\mu_{1}]} - \phi_{-[\mu_{2}]})_{\times} \\ = \mu_{1}^{-1} q_{-[\mu_{1}]} (\omega - \omega_{-[\mu_{1}]}) r - \mu_{1}^{-1} q_{-[\mu_{1}] - [\mu_{2}]} (\omega - \omega_{-[\mu_{1}]})_{-[\mu_{2}]} r_{-[\mu_{2}]} \\ -\mu_{2}^{-1} q_{-[\mu_{1}]} (\omega - \omega_{-[\mu_{1}]}) r + \mu_{2}^{-1} q_{-[\mu_{1}] - [\mu_{2}]} (\omega - \omega_{-[\mu_{1}]}) [\mu_{1}] r_{-[\mu_{2}]} r_{-[\mu_{2}]}$$

$$-\mu_{2}^{-1}q_{-[\mu_{2}]}(\omega-\omega_{-[\mu_{2}]})r + \mu_{2}^{-1}q_{-[\mu_{2}]-[\mu_{1}]}(\omega-\omega_{-[\mu_{2}]})_{-[\mu_{1}]}r_{-[\mu_{1}]}$$

$$\mu_{1}^{-1}(q - q_{-[\mu_{1}]}) - q_{x} = (\phi - \phi_{-[\mu_{1}]}) q + \mu_{1}^{-1} q_{-[\mu_{1}]} (\omega - \omega_{-[\mu_{1}]}) \hat{\Omega},$$

$$\mu_{1}^{-1}(r_{[\mu_{1}]} - r) - r_{x} = -r (\phi_{[\mu_{1}]} - \phi) + \mu_{1}^{-1} \hat{\Omega} (\omega_{[\mu_{1}]} - \omega) r_{[\mu_{1}]}$$

$$\hat{\Omega}_{\mathsf{x}} = -r \, q \qquad \mu_1^{-1} (\hat{\Omega}_{[\mu_1]} - \hat{\Omega}) = -r \, q_{[\mu_1]} + \mu_1^{-1} \hat{\Omega} \left(\omega_{[\mu_1]} - \omega \right) \hat{\Omega}$$

The simplest equations

$$\begin{aligned} q_{t_1} &= q_x + q \,\omega_{t_1} \hat{\Omega} & r_{t_1} &= r_x + \hat{\Omega} \,\omega_{t_1} r \\ q_{t_2} &= q_{xx} + 2 \left(\phi_{t_1} - q \,\omega_{t_1} r \right) q + q \,\omega_{t_2} \,\hat{\Omega} \\ r_{t_2} &= -r_{xx} - 2r \left(\phi_{t_1} - q \,\omega_{t_1} r \right) + \hat{\Omega} \,\omega_{t_2} r \\ (\phi_{t_1} - \phi_x - q \,\omega_{t_1} r)_{t_1} &= 0 \end{aligned}$$

Setting $\omega_{t_2} = 0$ and dropping the first two equations, we obtain

 $u_{t_1} - u_x = -2(q \omega_{t_1} r)_x$ $q_{t_2} = q_{xx} - u q$ $r_{t_2} = -r_{xx} + r u$ in terms of $u = -2(\phi_{t_1} - q \omega_{t_1} r)$. Via $t_2 \mapsto -i t_2$, and with the reduction $r = q^{\dagger} (u, \omega_{t_1}$ Hermitian), this becomes

$$u_{t_1} - u_x = -2 (q \omega_{t_1} q^{\dagger})_x$$
 i $q_{t_2} = q_{xx} - u q$

which is, up to a transformation of the independent variables and absorption of ω , the (2+1)-dimensional *Yajima-Oikawa* system. Now we know it has solutions depending on arbitrary functions of t_1 and we can easily construct such solutions.

Summary

- Integrable systems with self-consistent sources arise via a simple deformation of the potential Ω , which is at the heart of the binary Darboux transformation method, and by dropping some equations that emerge from the linear system.
- The essence of this has been formulated in the framework of *bidifferential calculus*. Choosing any realization of the latter, one should, in general, obtain scs-extensions of the respective integrable equations.
- For the integrable equations addressed so far (KdV, Boussinesq, KP, sine-Gordon, NLS, DS, 2dToda, discrete KP), we recovered all known versions of scs-extensions, even some more, and we generalized them to matrix versions.
- Our approach shows that the appearance of *arbitrary functions* of a single independent variable is a typical feature (on which the "source generation method" of Hu and Wang (2006) is based).

Introduction	рКР	BDC	2dToda	dKP	System	pKP hierarchy	Summary

Thanks for your attention !