# FIRST INTEGRALS OF AFFINE CONNECTIONS AND HAMILTONIAN SYSTEMS OF HYDRODYNAMIC TYPE

#### Maciej Dunajski

#### Department of Applied Mathematics and Theoretical Physics University of Cambridge

• Felipe Contatto, MD, arXiv:1510.01906.

 Given an affine connection ∇ on a surface Σ, determine necessary/sufficient local conditions (explicit curvature invariants) for the existence of first integrals.

- Given an affine connection ∇ on a surface Σ, determine necessary/sufficient local conditions (explicit curvature invariants) for the existence of first integrals.
- If ∇ is a Levi–Civita connection, then there can exist 0, 1 or 3 linear first integrals. Understand the non-metric case with exactly two local linear first integrals.

- Given an affine connection ∇ on a surface Σ, determine necessary/sufficient local conditions (explicit curvature invariants) for the existence of first integrals.
- If ∇ is a Levi–Civita connection, then there can exist 0, 1 or 3 linear first integrals. Understand the non-metric case with exactly two local linear first integrals.
- Application (unexpected!): Given a one-dimensional system of hydrodynamic type in Riemann invariants, determine necessary/sufficient conditions for the existence of a Hamiltonian (bi-Hamiltonian, tri-Hamiltonian) formulation of Dubrovin-Novikov type.

- Given an affine connection ∇ on a surface Σ, determine necessary/sufficient local conditions (explicit curvature invariants) for the existence of first integrals.
- If ∇ is a Levi–Civita connection, then there can exist 0, 1 or 3 linear first integrals. Understand the non-metric case with exactly two local linear first integrals.
- Application (unexpected!): Given a one-dimensional system of hydrodynamic type in Riemann invariants, determine necessary/sufficient conditions for the existence of a Hamiltonian (bi-Hamiltonian, tri-Hamiltonian) formulation of Dubrovin-Novikov type.
- Examples: Zoll connections. Hamiltonian systems from two-dimensional Frobebnius manifolds, ...

A simply-connected surface with a torsion–free affine connection
 (Σ, ∇) of differentiability class C<sup>4</sup>.

- A simply-connected surface with a torsion–free affine connection
   (Σ, ∇) of differentiability class C<sup>4</sup>.
- Affinely parametrised geodesic  $\gamma: \mathbb{R} \to \Sigma, \nabla_{\dot{\gamma}} \dot{\gamma} = 0$ . Or in local coordinates  $X^a$  on  $U \subset \Sigma$

$$\ddot{X}^a + \Gamma^a_{bc} \dot{X}^b \dot{X}^c = 0, \quad a, b, c = 1, 2.$$

- A simply-connected surface with a torsion–free affine connection
   (Σ, ∇) of differentiability class C<sup>4</sup>.
- Affinely parametrised geodesic  $\gamma: \mathbb{R} \to \Sigma, \nabla_{\dot{\gamma}} \dot{\gamma} = 0$ . Or in local coordinates  $X^a$  on  $U \subset \Sigma$

$$\ddot{X}^a + \Gamma^a_{bc} \dot{X}^b \dot{X}^c = 0, \quad a, b, c = 1, 2.$$

• Linear first integral:  $\kappa \equiv K_a(X)\dot{X}^a$  s.t.  $d\kappa/d\tau = 0$  along the geodesics. Equivalently

$$\nabla_a K_b + \nabla_b K_a = 0. \quad (K).$$

- A simply-connected surface with a torsion–free affine connection
   (Σ, ∇) of differentiability class C<sup>4</sup>.
- Affinely parametrised geodesic  $\gamma: \mathbb{R} \to \Sigma, \nabla_{\dot{\gamma}} \dot{\gamma} = 0$ . Or in local coordinates  $X^a$  on  $U \subset \Sigma$

$$\ddot{X}^a + \Gamma^a_{bc} \dot{X}^b \dot{X}^c = 0, \quad a, b, c = 1, 2.$$

• Linear first integral:  $\kappa \equiv K_a(X)\dot{X}^a$  s.t.  $d\kappa/d\tau = 0$  along the geodesics. Equivalently

$$\nabla_a K_b + \nabla_b K_a = 0. \quad (K).$$

 Prolong this system to a connection on a rank-3 vector bundle *E* → Σ. Find the integrability conditions for the existence of one/two/three parallel sections. Express them in terms of the curvature of ∇ and its covariant derivatives (of order up to 3).
 Curvature decomposition

$$R_{ab}{}^{c}{}_{d} = \delta_{a}{}^{c}\mathrm{P}_{bd} - \delta_{b}{}^{c}\mathrm{P}_{ad} + B_{ab}\delta_{d}{}^{c}.$$

Schouten tensor  $P_{ab} = (2/3)R_{ab} + (1/3)R_{ba}$ , and  $B_{ab} = -2P_{[ab]}$ . Set  $\beta = B_{ab}\epsilon^{ab}$  for an arbitrary volume form  $\epsilon$ .

Curvature decomposition

$$R_{ab}{}^c{}_d = \delta_a{}^c \mathcal{P}_{bd} - \delta_b{}^c \mathcal{P}_{ad} + B_{ab}\delta_d{}^c.$$

Schouten tensor  $P_{ab} = (2/3)R_{ab} + (1/3)R_{ba}$ , and  $B_{ab} = -2P_{[ab]}$ . Set  $\beta = B_{ab}\epsilon^{ab}$  for an arbitrary volume form  $\epsilon$ .

• Proposition. There is a one-to-one correspondence between solutions to the Killing equations (K), and parallel sections of the prolongation connection D on a rank-3 vector bundle  $E = \Lambda^1(\Sigma) \oplus \Lambda^2(\Sigma) \to \Sigma$ 

$$D_a \begin{pmatrix} K_b \\ \mu \end{pmatrix} = \begin{pmatrix} \nabla_a K_b - \epsilon_{ab} \mu \\ \nabla_a \mu - \left( \mathbf{P}^b_a + \frac{1}{2} \beta \delta^b_a \right) K_b + \mu \theta_a \end{pmatrix}$$

Curvature decomposition

$$R_{ab}{}^c{}_d = \delta_a{}^c \mathcal{P}_{bd} - \delta_b{}^c \mathcal{P}_{ad} + B_{ab}\delta_d{}^c.$$

Schouten tensor  $P_{ab} = (2/3)R_{ab} + (1/3)R_{ba}$ , and  $B_{ab} = -2P_{[ab]}$ . Set  $\beta = B_{ab}\epsilon^{ab}$  for an arbitrary volume form  $\epsilon$ .

• Proposition. There is a one-to-one correspondence between solutions to the Killing equations (K), and parallel sections of the prolongation connection D on a rank-3 vector bundle  $E = \Lambda^1(\Sigma) \oplus \Lambda^2(\Sigma) \to \Sigma$ 

$$D_a \begin{pmatrix} K_b \\ \mu \end{pmatrix} = \begin{pmatrix} \nabla_a K_b - \epsilon_{ab} \mu \\ \nabla_a \mu - \left( \mathbf{P}^b_a + \frac{1}{2} \beta \delta^b_a \right) K_b + \mu \theta_a \end{pmatrix}.$$

• Compute the curvature of D, restric its holonomy so that parallel sections  $\Psi = (K_a, \mu)$  exist. Find obstructions.

• Integrability conditions for  $D\Psi = 0$ :  $\mathcal{F}\Psi = 0$  where  $\mathcal{F} = [D, D]$ .

- Integrability conditions for  $D\Psi = 0$ :  $\mathcal{F}\Psi = 0$  where  $\mathcal{F} = [D, D]$ .
- If  $\mathcal{F} = 0$  then  $\nabla$  is projectively flat. Otherwise differentiate:  $(\mathcal{DF})\Psi = 0, (\mathcal{DDF})\Psi = 0, \ldots$

- Integrability conditions for  $D\Psi = 0$ :  $\mathcal{F}\Psi = 0$  where  $\mathcal{F} = [D, D]$ .
- If  $\mathcal{F} = 0$  then  $\nabla$  is projectively flat. Otherwise differentiate:  $(\mathcal{DF})\Psi = 0, (\mathcal{DDF})\Psi = 0, \ldots$
- After K steps  $\mathcal{F}_K \Psi = 0$ , where  $\mathcal{F}_K$  is a matrix of linear blue eqn.

- Integrability conditions for  $D\Psi = 0$ :  $\mathcal{F}\Psi = 0$  where  $\mathcal{F} = [D, D]$ .
- If  $\mathcal{F} = 0$  then  $\nabla$  is projectively flat. Otherwise differentiate:  $(\mathcal{DF})\Psi = 0, (\mathcal{DDF})\Psi = 0, \ldots$
- After K steps  $\mathcal{F}_K \Psi = 0$ , where  $\mathcal{F}_K$  is a matrix of linear blue eqn.
- Stop when rank  $(\mathcal{F}_K) = \operatorname{rank} (\mathcal{F}_{K+1})$ . The space of parallel sections has dimension  $(3 \operatorname{rank}(\mathcal{F}_K))$ .

- Integrability conditions for  $D\Psi = 0$ :  $\mathcal{F}\Psi = 0$  where  $\mathcal{F} = [D, D]$ .
- If  $\mathcal{F} = 0$  then  $\nabla$  is projectively flat. Otherwise differentiate:  $(\mathcal{DF})\Psi = 0, (\mathcal{DDF})\Psi = 0, \ldots$
- After K steps  $\mathcal{F}_K \Psi = 0$ , where  $\mathcal{F}_K$  is a matrix of linear blue eqn.
- Stop when rank  $(\mathcal{F}_K) = \operatorname{rank} (\mathcal{F}_{K+1})$ . The space of parallel sections has dimension  $(3 \operatorname{rank}(\mathcal{F}_K))$ .
- Set  $L_b \equiv \epsilon^{cd} \nabla_c \mathbf{P}_{db}$  and define

$$F^{a} = \frac{1}{3} \epsilon^{ab} (L_{b} - \epsilon^{cd} \nabla_{b} B_{cd}), \quad N_{a} = -F_{a} + \epsilon^{bc} \nabla_{a} B_{bc}$$
  
$$M_{a}^{b} = \frac{1}{3} \epsilon^{bc} \epsilon^{de} (\nabla_{a} Y_{dec} - \nabla_{a} \nabla_{c} B_{de}) + \beta P^{b}{}_{a} + \frac{1}{2} \beta^{2} \delta^{b}{}_{a},$$
  
$$I_{N} = \epsilon_{cd} \epsilon^{be} M_{e}{}^{c} \left( N_{b} F^{d} - \frac{1}{2} \beta M_{b}{}^{d} \right).$$

Theorem (Contatto, MD) The necessary condition for a  $C^4$  torsion-free affine connection  $\nabla$  on a surface  $\Sigma$  to admit a linear first integral is the vanishing, on  $\Sigma$ , of invariants  $I_N$  and  $I_S$  respectively. For any point  $p \in \Sigma$ there exists a neighbourhood  $U \subset \Sigma$  of p such that conditions  $I_N = I_S = 0$  on U are sufficient for the existence of a first integral on U. There exist precisely two independent linear first integrals on U if and only if the tensor

$$T_a{}^b \equiv N_a F^b - \beta M_a{}^b.$$

vanishes and the skew part of the Ricci tensor of  $\nabla$  is non-zero on U. There exist three independent first integrals on U if and only if the connection is projectively flat and its Ricci tensor is symmetric.

#### CONNECTIONS WITH TWO FIRST INTEGRALS

 If ∇ is a Levi-Civita connection of some metric on Σ with scalar curvature R, then (Darboux 1887)

$$I_N := *\frac{1}{432} dR \wedge d(|\nabla R|^2), \quad I_S := *dR \wedge d(\triangle R).$$

### CONNECTIONS WITH TWO FIRST INTEGRALS

 If ∇ is a Levi-Civita connection of some metric on Σ with scalar curvature R, then (Darboux 1887)

$$I_N := * \frac{1}{432} dR \wedge d(|\nabla R|^2), \quad I_S := * dR \wedge d(\triangle R).$$

• A Levi-Civita connection can not admit precisely two local first integrals. A non-metric connection can:

Theorem (Contatto, MD). Let  $\nabla$  be an affine connection on a surface  $\Sigma$  which admits exactly two non-proportional linear first integrals which are independent at some point  $p \in \Sigma$ . Coordinates  $X^a = (X, Y)$  can be chosen on an open set  $U \subset \Sigma$  containing p such that

$$\Gamma_{12}^1 = \Gamma_{21}^1 = \frac{c}{2}, \Gamma_{11}^2 = \frac{P_X}{Q}, \Gamma_{12}^2 = \Gamma_{21}^2 = \frac{P_Y + Q_X - cP}{2Q}, \Gamma_{22}^2 = \frac{Q_Y}{Q}$$

and all other components vanish, where c is a constant equal to 0 or 1, and (P,Q) are arbitrary functions of (X,Y).

# HAMILTONIAN SYSTEMS OF HYDRODYNAMIC TYPE

• One-dimensional systems of hydrodynamic type

$$\frac{\partial X^1}{\partial t} = \lambda^1 (X^1, X^2) \frac{\partial X^1}{\partial x}, \quad \frac{\partial X^2}{\partial t} = \lambda^2 (X^1, X^2) \frac{\partial X^2}{\partial x}. \quad (HT)$$

# HAMILTONIAN SYSTEMS OF HYDRODYNAMIC TYPE

• One-dimensional systems of hydrodynamic type

$$\frac{\partial X^1}{\partial t} = \lambda^1 (X^1, X^2) \frac{\partial X^1}{\partial x}, \quad \frac{\partial X^2}{\partial t} = \lambda^2 (X^1, X^2) \frac{\partial X^2}{\partial x}. \quad (HT)$$

• Local hydrodynamic Hamiltonian formulation

$$\frac{\partial X^a}{\partial t} = \Omega^{ab} \frac{\delta H}{\delta X^b},$$

where

$$H[X^1, X^2] = \int_{\mathbb{R}} \mathcal{H}(X^1, X^2) dx, \quad \Omega^{ab} = g^{ab} \frac{\partial}{\partial x} + b_c^{ab} \frac{\partial X^c}{\partial x}.$$

# HAMILTONIAN SYSTEMS OF HYDRODYNAMIC TYPE

• One-dimensional systems of hydrodynamic type

$$\frac{\partial X^1}{\partial t} = \lambda^1 (X^1, X^2) \frac{\partial X^1}{\partial x}, \quad \frac{\partial X^2}{\partial t} = \lambda^2 (X^1, X^2) \frac{\partial X^2}{\partial x}. \quad (HT)$$

• Local hydrodynamic Hamiltonian formulation

$$\frac{\partial X^a}{\partial t} = \Omega^{ab} \frac{\delta H}{\delta X^b},$$

where

$$H[X^1, X^2] = \int_{\mathbb{R}} \mathcal{H}(X^1, X^2) dx, \quad \Omega^{ab} = g^{ab} \frac{\partial}{\partial x} + b_c^{ab} \frac{\partial X^c}{\partial x}.$$

• Poisson bracket (Dubrovin+Novikov (1983), Tsarev (1985) )

$$\{F,G\} = \int_{\mathbb{R}} \frac{\delta F}{\delta X^a} \left( g^{ab} \frac{\partial}{\partial x} + b_c^{ab} \frac{\partial X^c}{\partial x} \right) \frac{\delta G}{\delta X^b} dx$$

Skew-symmetry+Jacobi identity:  $g^{ab}$  is a flat metric with Christoffel symbols  $\gamma^c_{ab}$  defined by  $b^{ab}_c=-g^{ad}\gamma^b_{\ dc}.$ 

Theorem 3 (Contatto, MD). The hydrodynamic type system (HT) admits one, two or three Hamiltonian formulations with hydrodynamic Hamiltonians if and only if the affine torsion–free connection  $\nabla$  defined by its non–zero components

$$\begin{split} \Gamma_{11}^1 &= \partial_1 \ln A - 2B, \quad \Gamma_{22}^2 = \partial_2 \ln B - 2A, \quad \Gamma_{12}^1 = -\left(\frac{1}{2}\partial_2 \ln A + A\right), \\ \text{where} \quad A &= \frac{\partial_2 \lambda^1}{\lambda^2 - \lambda^1}, \quad B = \frac{\partial_1 \lambda^2}{\lambda^1 - \lambda^2}, \quad \text{and} \quad \partial_a = \partial/\partial X^a \end{split}$$

admits one, two or three independent linear first integrals respectively.

#### REMARKS

• The connection from Theorem 3 is generically not metric but is metrisable by the metric

$$h = AB \ dX \odot dY, \quad X^a = (X, Y).$$

The unparametrised geodesics of h and of  $\nabla$  conicide, and are integral curves of a 2nd order ODE

$$Y'' = (\partial_X Z)Y' - (\partial_Y Z)(Y')^2, \quad \text{where} \quad Z \equiv \ln (AB),$$

• The connection from Theorem 3 is generically not metric but is metrisable by the metric

$$h = AB \ dX \odot dY, \quad X^a = (X, Y).$$

The unparametrised geodesics of h and of  $\nabla$  conicide, and are integral curves of a 2nd order ODE

$$Y'' = (\partial_X Z)Y' - (\partial_Y Z)(Y')^2, \quad \text{where} \quad Z \equiv \ln (AB),$$

 In the tri-Hamiltonian case (Ferapontov (1991)) the connection from Theorem 3 has symmetric Ricci tensor, and is projectively flat.
 Equivalently, the metric h has constant Gaussian curvature i. e.

$$(AB)^{-1}\partial_1\partial_2\ln(AB) = \text{const.}$$

• The connection from Theorem 3 is generically not metric but is metrisable by the metric

$$h = AB \ dX \odot dY, \quad X^a = (X, Y).$$

The unparametrised geodesics of h and of  $\nabla$  conicide, and are integral curves of a 2nd order ODE

$$Y'' = (\partial_X Z)Y' - (\partial_Y Z)(Y')^2, \quad \text{where} \quad Z \equiv \ln (AB),$$

 In the tri-Hamiltonian case (Ferapontov (1991)) the connection from Theorem 3 has symmetric Ricci tensor, and is projectively flat.
 Equivalently, the metric h has constant Gaussian curvature i. e.

$$(AB)^{-1}\partial_1\partial_2\ln(AB) = \text{const.}$$

• Example: HT system with  $\lambda^1 = -\lambda^2 = (X - Y)^n (X + Y)^m$ . Always bi-Hamiltonian. Tri-Hamiltonian iff  $nm(n^2 - m^2) = 0$ .

• Two-dimensional Frobenius manifolds: coordinates  $u^a = (u, v)$ , a function  $F: U \to \mathbb{R}$ , associative structure constants  $C^a{}_{bc} := \eta^{ad} C_{bcd}$ 

$$C = \frac{\partial^3 F}{\partial u^a \partial u^b \partial u^c} du^a du^b du^c, \quad \mathbf{e} = \frac{\partial}{\partial u^1}, \quad \eta = \frac{\partial^3 F}{\partial u^1 \partial u^a \partial u^b} du^a du^b.$$

• Two-dimensional Frobenius manifolds: coordinates  $u^a = (u, v)$ , a function  $F: U \to \mathbb{R}$ , associative structure constants  $C^a{}_{bc} := \eta^{ad} C_{bcd}$ 

$$C = \frac{\partial^3 F}{\partial u^a \partial u^b \partial u^c} du^a du^b du^c, \quad \mathbf{e} = \frac{\partial}{\partial u^1}, \quad \eta = \frac{\partial^3 F}{\partial u^1 \partial u^a \partial u^b} du^a du^b.$$

• (Dubrovin (1996), Hitchin (1997))  $F(u,v) = \frac{1}{2}u^2v + f(v)$ , where

$$f = v^k, \ k \neq 0, 2, \quad f = v^2 \ln v, \quad f = \ln v, \quad f = e^{2v}.$$

• Two-dimensional Frobenius manifolds: coordinates  $u^a = (u, v)$ , a function  $F: U \to \mathbb{R}$ , associative structure constants  $C^a{}_{bc} := \eta^{ad} C_{bcd}$ 

$$C = \frac{\partial^3 F}{\partial u^a \partial u^b \partial u^c} du^a du^b du^c, \quad \mathbf{e} = \frac{\partial}{\partial u^1}, \quad \eta = \frac{\partial^3 F}{\partial u^1 \partial u^a \partial u^b} du^a du^b.$$

• (Dubrovin (1996), Hitchin (1997))  $F(u,v) = \frac{1}{2}u^2v + f(v)$ , where

$$f = v^k, \ k \neq 0, 2, \quad f = v^2 \ln v, \quad f = \ln v, \quad f = e^{2v}.$$

• Two-dimensional Frobenius manifolds: coordinates  $u^a = (u, v)$ , a function  $F: U \to \mathbb{R}$ , associative structure constants  $C^a{}_{bc} := \eta^{ad} C_{bcd}$ 

$$C = \frac{\partial^3 F}{\partial u^a \partial u^b \partial u^c} du^a du^b du^c, \quad \mathbf{e} = \frac{\partial}{\partial u^1}, \quad \eta = \frac{\partial^3 F}{\partial u^1 \partial u^a \partial u^b} du^a du^b.$$

• (Dubrovin (1996), Hitchin (1997))  $F(u,v) = \frac{1}{2}u^2v + f(v)$ , where

$$f = v^k, \ k \neq 0, 2, \quad f = v^2 \ln v, \quad f = \ln v, \quad f = e^{2v}$$

• Hydrodynamic type system with Riemann invariants

$$X = u + \int \sqrt{f'''(v)} dv, \quad Y = u - \int \sqrt{f'''(v)} dv.$$

• Two-dimensional Frobenius manifolds: coordinates  $u^a = (u, v)$ , a function  $F: U \to \mathbb{R}$ , associative structure constants  $C^a{}_{bc} := \eta^{ad} C_{bcd}$ 

$$C = \frac{\partial^3 F}{\partial u^a \partial u^b \partial u^c} du^a du^b du^c, \quad \mathbf{e} = \frac{\partial}{\partial u^1}, \quad \eta = \frac{\partial^3 F}{\partial u^1 \partial u^a \partial u^b} du^a du^b.$$

• (Dubrovin (1996), Hitchin (1997))  $F(u,v) = \frac{1}{2}u^2v + f(v)$ , where

$$f = v^k, \ k \neq 0, 2, \quad f = v^2 \ln v, \quad f = \ln v, \quad f = e^{2v}$$

• Hydrodynamic type system with Riemann invariants

$$X = u + \int \sqrt{f'''(v)} dv, \quad Y = u - \int \sqrt{f'''(v)} dv.$$

• Theorem 3: Tri-hamiltonian with 3-parameter family of flat metrics

$$g(c_1, c_2, c_3) = \lambda^{-1} \Big( \frac{dX^2}{c_1 + c_2 X + c_3 X^2} - \frac{dY^2}{c_1 + c_2 Y + c_3 Y^2} \Big),$$

• Two-dimensional Frobenius manifolds: coordinates  $u^a = (u, v)$ , a function  $F: U \to \mathbb{R}$ , associative structure constants  $C^a{}_{bc} := \eta^{ad}C_{bcd}$ 

$$C = \frac{\partial^3 F}{\partial u^a \partial u^b \partial u^c} du^a du^b du^c, \quad \mathbf{e} = \frac{\partial}{\partial u^1}, \quad \eta = \frac{\partial^3 F}{\partial u^1 \partial u^a \partial u^b} du^a du^b.$$

• (Dubrovin (1996), Hitchin (1997))  $F(u,v) = \frac{1}{2}u^2v + f(v)$ , where

$$f = v^k, \ k \neq 0, 2, \quad f = v^2 \ln v, \quad f = \ln v, \quad f = e^{2v}$$

• Hydrodynamic type system with Riemann invariants

$$X = u + \int \sqrt{f'''(v)} dv, \quad Y = u - \int \sqrt{f'''(v)} dv.$$

• Theorem 3: Tri-hamiltonian with 3-parameter family of flat metrics

$$g(c_1, c_2, c_3) = \lambda^{-1} \Big( \frac{dX^2}{c_1 + c_2 X + c_3 X^2} - \frac{dY^2}{c_1 + c_2 Y + c_3 Y^2} \Big),$$

•  $\eta \equiv g(1,0,0), I \equiv g(0,1,0)$  (intersection form),  $J \equiv g(0,0,1)$  s. t.  $J_{ab} = I_{ac}I_{bd}\eta^{cd}$  (Romano 2014).

• A connection ∇ on a compact surface ∑ is *Zoll* if its unparametrised geodesics are simple closed curves.

- A connection ∇ on a compact surface Σ is Zoll if its unparametrised geodesics are simple closed curves.
- Axisymmetric Zoll metrics on  $\Sigma=S^2$

 $h = (F-1)^2 dX^2 + \sin^2 X dY^2, \quad F = F(X), \quad F: [0,\pi] \to [0,1]$ 

where  $F(0) = F(\pi) = 0$  and  $F(\pi - X) = -F(X)$ .

- A connection ∇ on a compact surface ∑ is Zoll if its unparametrised geodesics are simple closed curves.
- Axisymmetric Zoll metrics on  $\Sigma=S^2$

 $h = (F-1)^2 dX^2 + \sin^2 X dY^2, \quad F = F(X), \quad F : [0,\pi] \to [0,1]$ 

where  $F(0) = F(\pi) = 0$  and  $F(\pi - X) = -F(X)$ .

• Non-metric Zoll connection with a linear first integral

$$\Gamma_{11}^{1} = \frac{F'}{F-1} - 2\cot X, \quad \Gamma_{22}^{1} = -\frac{(H^{2}+1)\sin X\cos X}{(F-1)^{2}}$$
$$\Gamma_{12}^{1} = \Gamma_{21}^{1} = \frac{1}{2}\frac{H'\sin X\cos X - 2H}{\cos X(F-1)}, \quad H = H(X)$$

where  $H(0) = H(\pi) = H(\pi/2) = 0$ , and  $H(\pi - X) = H(X)$ .

- A connection ∇ on a compact surface Σ is Zoll if its unparametrised geodesics are simple closed curves.
- Axisymmetric Zoll metrics on  $\Sigma=S^2$

 $h = (F-1)^2 dX^2 + \sin^2 X dY^2, \quad F = F(X), \quad F: [0,\pi] \to [0,1]$ 

where  $F(0) = F(\pi) = 0$  and  $F(\pi - X) = -F(X)$ .

Non-metric Zoll connection with a linear first integral

$$\Gamma_{11}^{1} = \frac{F'}{F-1} - 2\cot X, \quad \Gamma_{22}^{1} = -\frac{(H^{2}+1)\sin X\cos X}{(F-1)^{2}}$$
  
$$\Gamma_{12}^{1} = \Gamma_{21}^{1} = \frac{1}{2}\frac{H'\sin X\cos X - 2H}{\cos X(F-1)}, \quad H = H(X)$$

where  $H(0) = H(\pi) = H(\pi/2) = 0$ , and  $H(\pi - X) = H(X)$ . • Exactly two linear first integrals? Find that  $T_h^a = 0$  if

$$F = 1 + c(H^2 + 1)\cot X, \quad c \in \mathbb{R}$$

but the boundary conditions do not hold ... (open problem).

# Thank You!